

MATLAB[®] Today

By Steve Eddins, Ph.D.

True or false:

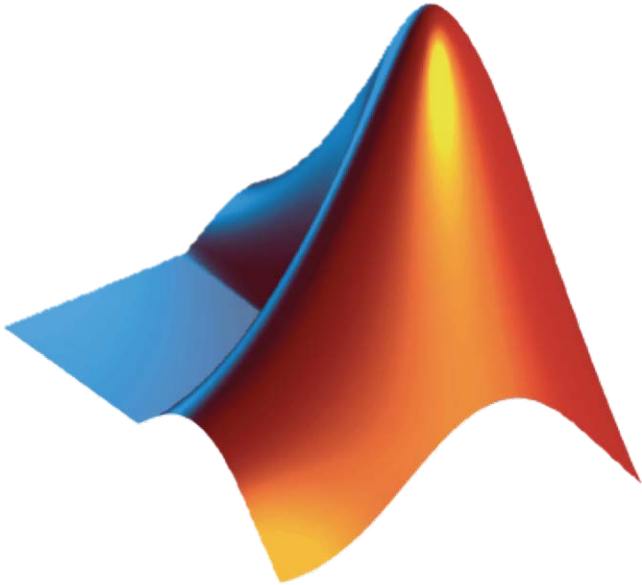
*Every cell in the human body
gets replaced every 7 years*

Continuously Rebuilding the Human Body

- Mostly true
 - Skin cells – 35 days
 - Red blood cells – 120 days
 - Skeleton – 10 years
 - Neocortical neurons – lifetime



Continuously Rebuilding MATLAB



Almost everything in MATLAB is completely new or has been rebuilt over the last 7-10 years.

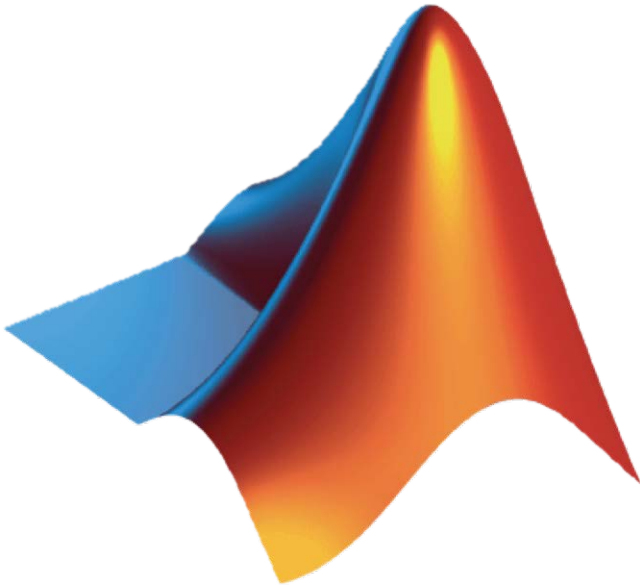
Continuously Rebuilding MATLAB

Why?

Your needs change.

Computational
technologies and
environments change.

The pace of change in
MATLAB has never
been more rapid.



81137_92238v00_RainbowColorMap_57312.pdf (page 1 of 18)

Search

Rainbow Color Map Critiques: An Overview and Annotated Bibliography

By Steve Eddins, MathWorks

Overview

A rainbow color map is based on the order of colors in the spectrum of visible light—the same colors that appear in a rainbow. Figure 1 shows one particular form of rainbow color map. Since multiple methods exist for computing rainbow color maps, they do not all look identical, but they all feature the same general ordering of colors.



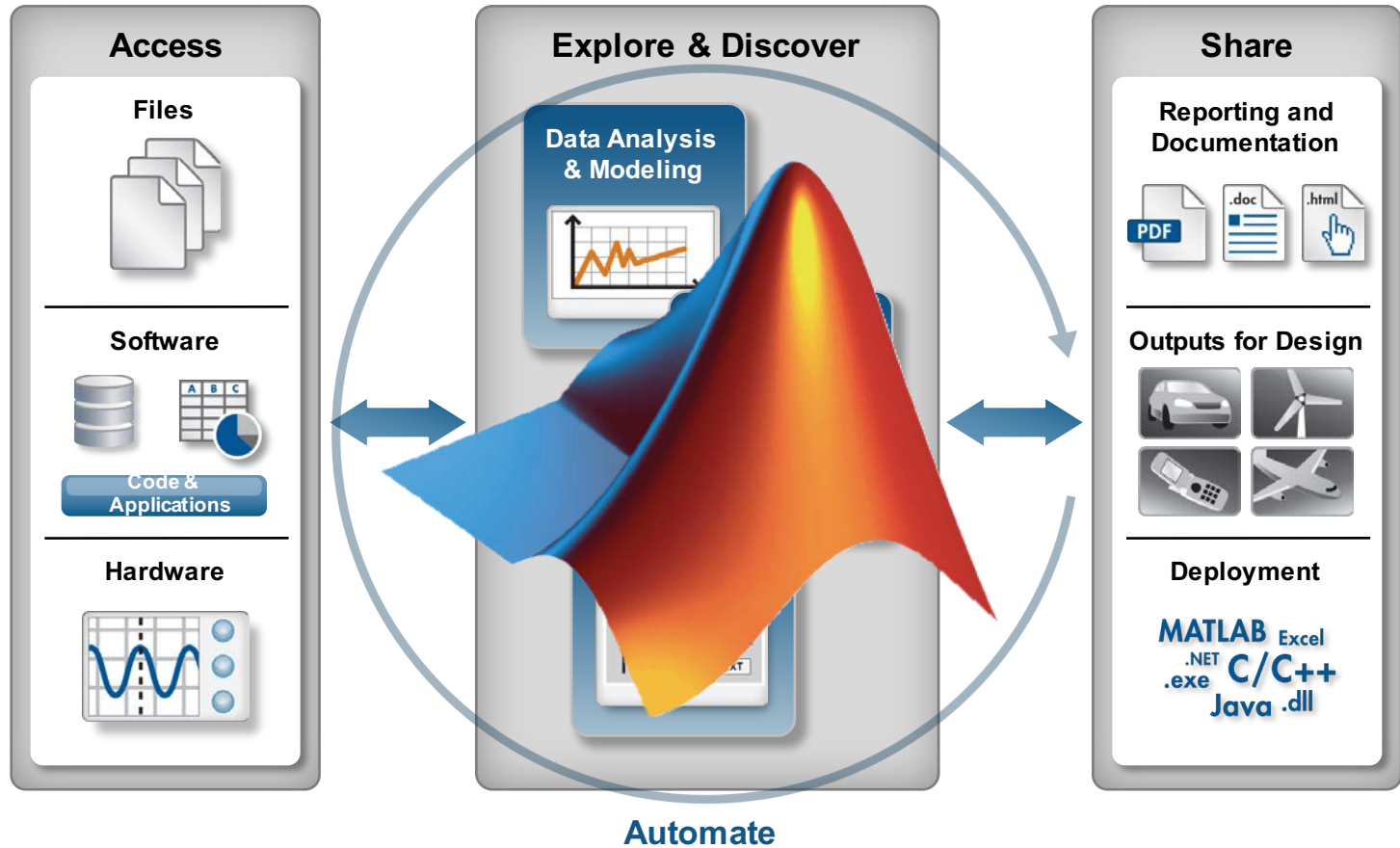
Figure 1. Visible light spectrum.

Data credit: “[Spectral and XYZ Color Functions](#),” Jeff Mather, MATLAB Central File Exchange.

Rainbow color maps commonly appear in data visualizations in many different scientific and engineering communities. Technical computing software often provides a rainbow color map as the default choice.

Before Release 2014b, MATLAB® used a rainbow color map as the default for figures. In MATLAB, the rainbow color map is known as `rainbow`.

Technical Computing Workflow



So Here's Where We're Going in the Next Hour

- Access
 - Files
 - Software
 - Hardware
- Graphics
- Math
- Software Development
- Image Processing
- Computer Vision

Getting Your Data

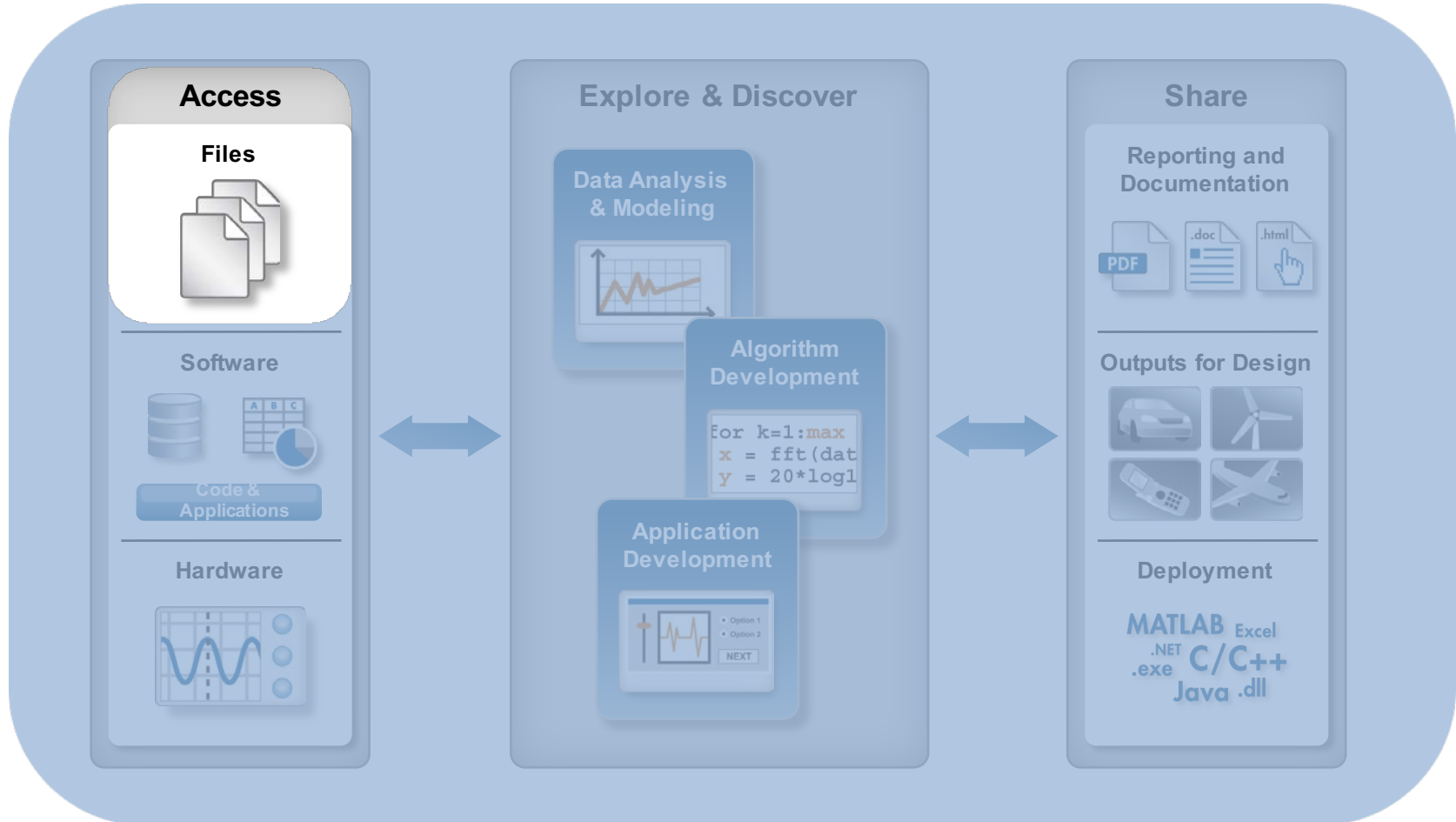


Image File Enhancements

TIFF:

LogL and LogLUV HDR files
BigTIFF

NITF JPEG

DPX

DICOM anonymizer
(privacy requirements)



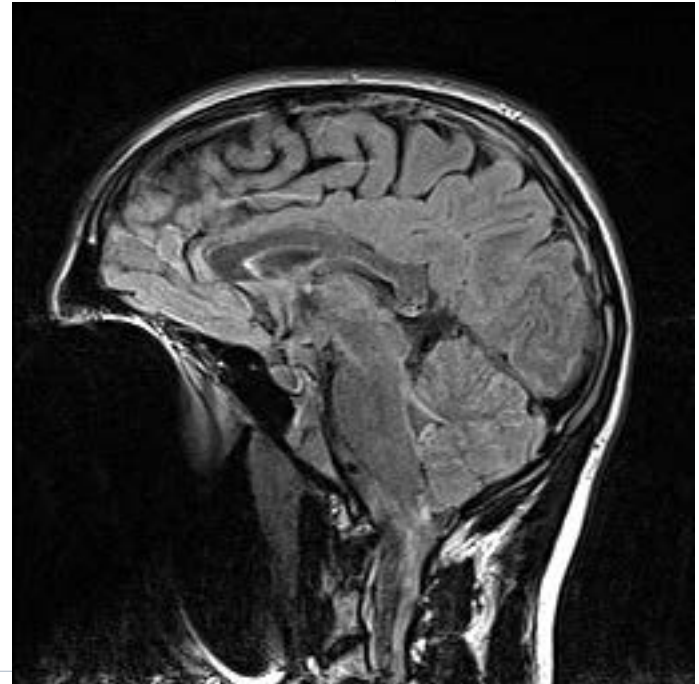
Command Window

```
>> dicomanon('31237418','31237418a')  
>> info = dicominfo('31237418a');  
>> info.PatientName
```

```
ans =
```

```
FamilyName: ''  
GivenName: ''  
MiddleName: ''  
NamePrefix: ''  
NameSuffix: ''
```

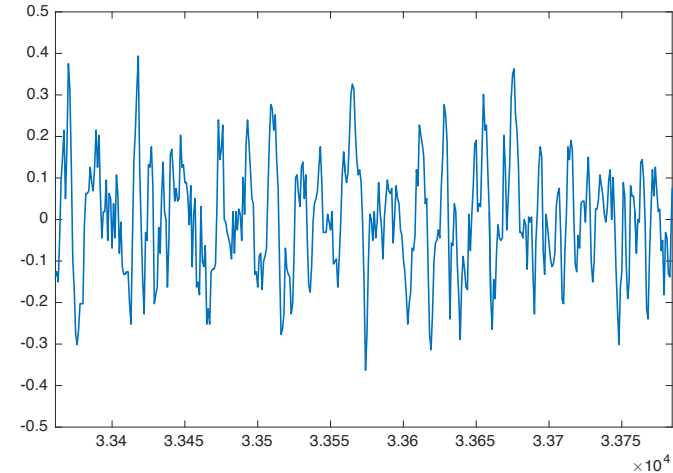
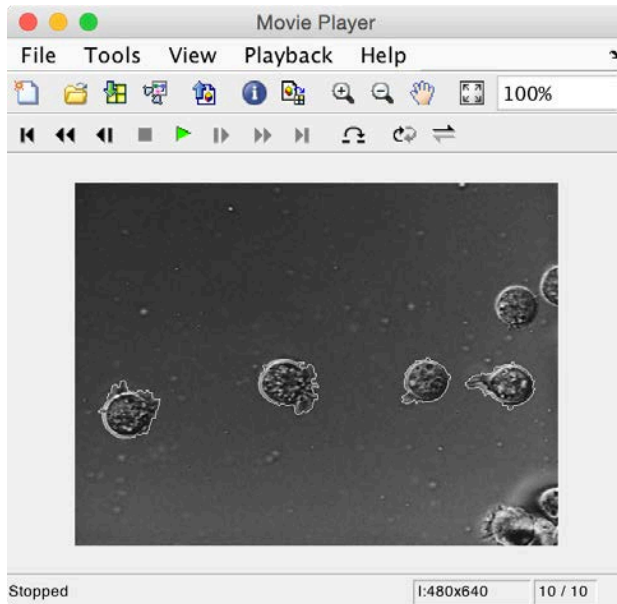
31237418



Video and Audio File Enhancements

MPEG-4

Mac support for MPEG-4 H.264



MP3

MPEG-4 audio

MPEG-4 AAC

Wave enhancements

Scientific Data File Enhancements

HDF5, netCDF

OPeNDAP online servers

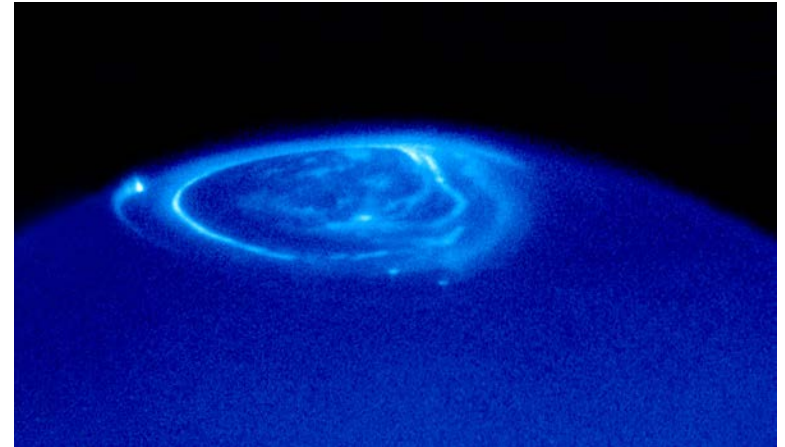


Image credit: NASA, ESA & John T. Clarke (Univ. of Michigan)

FITS export

Datastores

Datastore – for reading structured data in one or many files

Good for big data, Hadoop, HDFS



Tabular text datastores
Image datastores

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R					
1	Year	Month	Day	MoYr	Day	DayE	DayT	Time	CRSArr	Uni	CA	Flight	N	Actual	CRSL	AS	ArrTime	ArDelay	Dep	Delay	Origin	Dest	Dist
2	2000	3	2	4	1641	1635	1831	1830	WN			1728	N353	50	55	41	1	6	ELP		LBB		
3	2000	3	7	7004	1900	2307	2249	NA			1124	N444	173	173	118	18	14	NA		JGA			
4	2000	3	11	7	1042	1042	1107	1107	PI			929	NA	25	25	NA	0	0	SYR		ITH		
5	2000	3	1990	10	31	6	1655	1655	1742	1755	PI	903	NA	47	60	NA	-13	0	LGA		SYR		
6	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
7	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
8	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
9	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
10	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
11	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
12	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
13	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
14	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
15	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
16	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
17	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
18	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
19	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
20	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
21	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
22	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
23	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929	NA	25	25	NA	0	0	SYR		ITH		
24	2000	3	1990	10	11	7	1042	1042	1107	1107	PI	929											

Web Service Interfaces

- Often called *RESTful interfaces*
- webread
- webwrite

Example RESTful API: NASA Landsat Imagery

HTTP REQUEST

```
GET https://api.nasa.gov/planetary/earth/imagery
```

QUERY PARAMETERS

Parameter	Type	Default	Description
lat	float	n/a	Latitude
lon	float	n/a	Longitude
dim	float	0.025	width and height of image in degrees
date	YYYY-MM-DD	<i>today</i>	date of image; if not supplied, then the most recent image (i.e., closest to today) is returned
cloud_score	bool	False	calculate the percentage of the image covered by clouds
api_key	string	DEMO_KEY	api.nasa.gov key for expanded usage

<https://api.nasa.gov/api.html#imagery>

Command Window

```
>> url = 'https://api.nasa.gov/planetary/earth/imagery';  
>> result = webread(url,...  
                    'lat',42.300,...  
                    'lon',-71.351,...  
                    'api_key','DEMO_KEY')  
  
result =  
  
    date: '2015-08-28T15:26:54'  
    url: 'https://earthengine.googleapis.com/api/thum..  
    id: 'LC8_L1T_TOA/LC80120312015240LGN00'  
  
>> mw = webread(result.url);  
>> imshow(mw)
```

Command Window

```
>> url = 'https://api.nasa.gov/planetary/earth/imagery';  
>> result = webread(url,...  
                    'lat',42.300,...  
                    'lon',-71.351,...  
                    'api_key','DEMO_KEY')
```

```
result =
```

```
    date: '2015-08-28T15:26:54'  
    url: 'https://earthengine.googleapi  
    id: 'LC8_L1T_TOA/LC801203120152400'
```

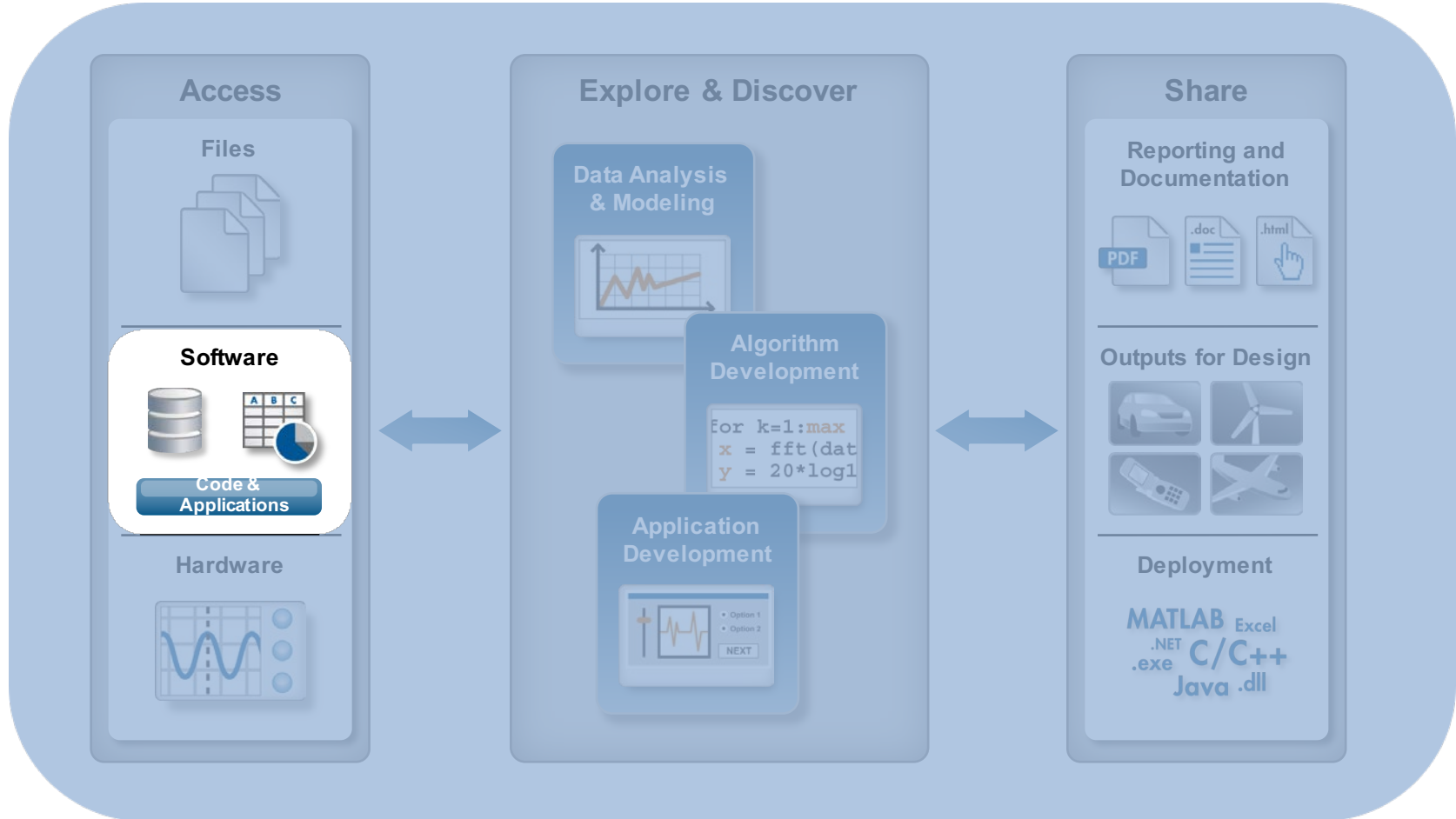
```
>> mw = webread(result.url);  
>> imshow(mw)
```

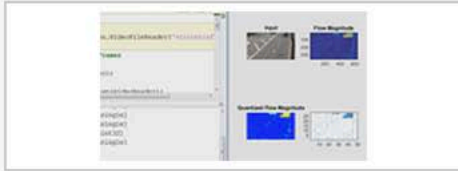


Web Service Interface options

- Character encoding
- Timeout (how long before giving up on request)
- Username, password
- Request method (GET or POST)
- Desired content type (text, audio, image, table, etc.)

Using Other Software and Apps





Computer Vision System Toolbox OpenCV Interface

by [MathWorks Computer Vision System Toolbox Team](#)

03 Oct 2014 (Updated 04 Sep 2015)

Use OpenCV algorithms in MATLAB



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File Size: 15.1 KB

File ID: #47953

Version: 1.5

OpenCV Interface: What's Included

- Prebuilt OpenCV binaries
- Build script to create OpenCV based MEX-files
- Data type conversions between MATLAB and OpenCV
- Examples to help get started with common workflows

Python

- Call Python from MATLAB
- Call MATLAB from Python

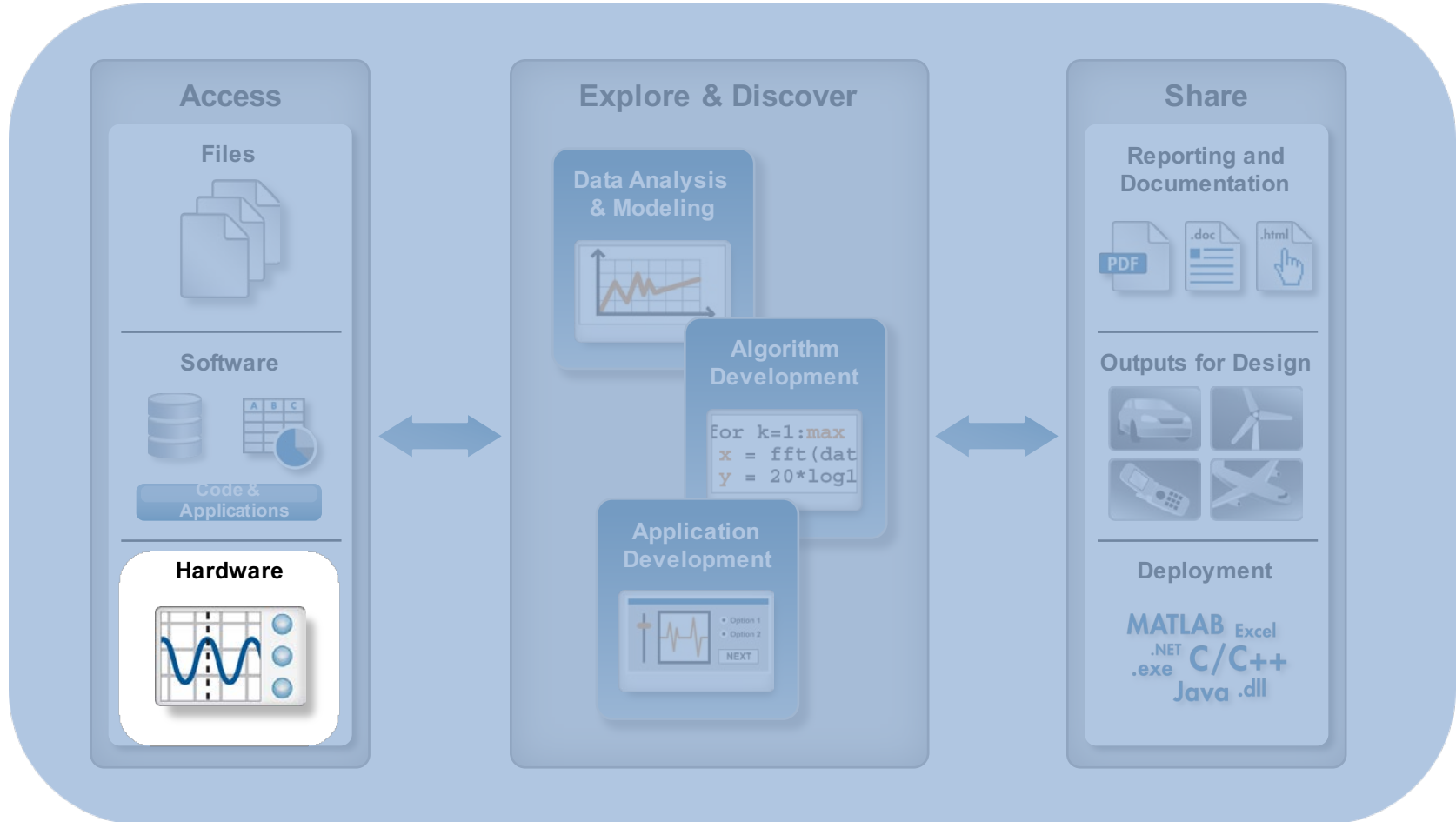
Command Window

```
>> T = 'A watershed is the ridge that divides areas drai
>> tw = py.textwrap.TextWrapper(pyargs(...
    'initial_indent', '% ', ...
    'subsequent_indent', '% ', ...
    'width', int32(30)));
>> wrapped = wrap(tw,T);
>> wrapped = cellfun(@(pystr) {char(pystr)},wrapped);
>> fprintf('%s\n',wrapped{:})
```

```
% A watershed is the ridge
% that divides areas drained
% by different river systems.
% A catchment basin is the
% geographical area draining
% into a river or reservoir.
% The watershed transform
% applies these ideas to gray-
% scale image processing in a
% way that can be used to
% solve a variety of problems.
```

```
>>> import matlab.engine  
>>> eng = matlab.engine.start_matlab()  
>>> t = eng.gcd(18.0,4.0,nargout=3)  
>>> print(t)  
(2.0, 1.0, -4.0)
```

Hooking Up Your Hardware



Explosion in Hardware Support

117 manufacturers

Application areas:

- Communications
- Control systems
- DSP
- Embedded systems
- FPGA
- Image processing and computer vision
- Internet of things
- Mechatronics

Protocols and standards:

- Audio
- Bluetooth
- CAN
- Ethernet
- I2C/SPI
- Safety
- Serial
- USB
- Video

Explosive Support



Baumer Camera Support from Image Acquisition Toolbox
 Use Baumer cameras with MATLAB and Simulink to acquire image data.
 Vendors: Baumer
 Tags: MathWorks Supported



BeagleBoard Support from Image Acquisition Toolbox
 Low-cost, single-board computer.
 Vendors: BeagleBoard
 Tags: C/C++ Code Generation, MathWorks Supported, Project-Based Learning, Support Package Installer Enabled



BeagleBone Black Support from Image Acquisition Toolbox
 Generate code optimized for BeagleBone Black.
 Vendors: ARM, BeagleBoard, Texas Instruments
 Tags: C/C++ Code Generation, MathWorks Supported, Project-Based Learning, Support Package Installer Enabled



BeagleBone Black Support from Image Acquisition Toolbox
 Acquire sensor and image data from BeagleBone Black.
 Vendors: BeagleBoard, Texas Instruments
 Tags: MathWorks Supported, Project-Based Learning, Support Package Installer Enabled



BitFlow Frame Grabber Support from Image Acquisition Toolbox
 Use BitFlow Frame Grabbers to acquire image data.
 Vendors: BitFlow
 Tags: MathWorks Supported



BitFlow Neon Support from Image Acquisition Toolbox
 Use BitFlow Neon with Simulink to acquire image data for medical, or semiconductor imaging.
 Vendors: BitFlow
 Tags: MathWorks Supported, Project-Based Learning, Support Package Installer Enabled



Automation Technology Camera Support from Image Acquisition Toolbox
 Use Automation Technology cameras with MATLAB and Simulink to acquire image data.
 Vendors: Automation Technology
 Tags: MathWorks Supported



Basler Camera Support from Image Acquisition Toolbox
 Use Basler cameras with MATLAB and Simulink to acquire image data.
 Vendors: Basler
 Tags: MathWorks Supported



Camera Link Support from Image Acquisition Toolbox
 Use Camera Link frame grabbers with MATLAB and Simulink to support image processing and computer vision workflows.
 Vendors: BitFlow, Data Translation, Imperx, Matrox Imaging, National Instruments
 Tags: MathWorks Supported



Cohu Camera Support from Image Acquisition Toolbox
 Use Cohu cameras with MATLAB and Simulink to acquire image data.
 Vendors: Cohu
 Tags: MathWorks Supported



Data Translation Frame Grabber Support from Image Acquisition Toolbox
 Use Data Translation frame grabbers with MATLAB and Simulink to acquire image data.
 Vendors: Data Translation
 Tags: MathWorks Supported



DCAM Camera Support from Image Acquisition Toolbox
 Use DCAM cameras with MATLAB and Simulink to acquire image data.
 Vendors: DCAM
 Tags: MathWorks Supported



FLIR Camera Support from Image Acquisition Toolbox
 Use FLIR cameras with MATLAB and Simulink to acquire image data.
 Vendors: FLIR
 Tags: MathWorks Supported



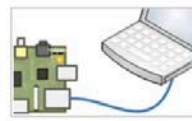
GenTL Camera Support from Image Acquisition Toolbox
 Use GenTL cameras with MATLAB and Simulink to acquire image data.
 Vendors: GenTL
 Tags: MathWorks Supported



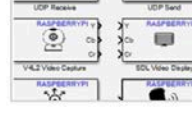
Arduino Support from MATLAB
 Student-priced microcontroller board for introducing electrical engineering and mechatronics.
 Vendors: Arduino
 Tags: Project-Based Learning, Support Package Installer Enabled



Arduino Support from Simulink
 Student-priced microcontroller board for introducing electrical engineering and mechatronics.
 Vendors: Arduino
 Tags: Support Package Installer Enabled, C/C++ Code Generation, MathWorks Supported, Target Hardware



Raspberry Pi Support from MATLAB
 Use MATLAB to acquire sensor and image data from your connected Raspberry Pi.
 Vendors: Raspberry Pi
 Tags: MathWorks Supported, Project-Based Learning, Support Package Installer Enabled



Raspberry Pi Support from Simulink
 Credit-card sized, low-cost, single-board computer with audio and video capabilities for teaching.
 Vendors: Raspberry Pi
 Tags: C/C++ Code Generation, MathWorks Supported, Project-Based Learning, Support Package Installer Enabled



ThingSpeak Support from Desktop MATLAB
 Prototype Internet of Things (IoT) applications using ThingSpeak and MATLAB.
 Vendors: ioBridge

USB Webcam and IP Cameras

USB Webcam Support with MATLAB

Use webcams with MATLAB to acquire images and video on PCs.

- ▶ USB Webcam Support with MATLAB

- ▶ IP Camera Support from MATLAB

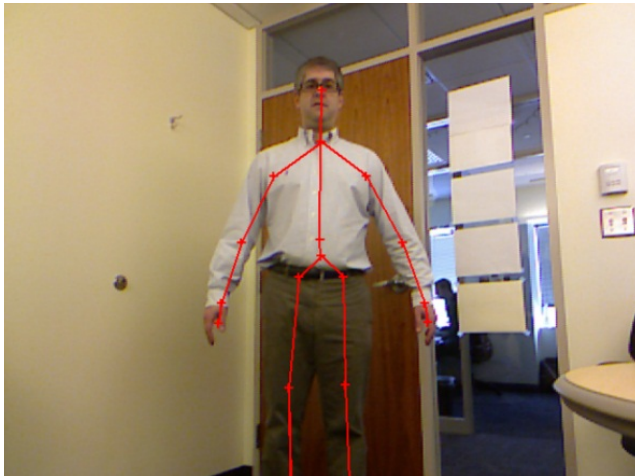
Using UVC compliant webcams with MATLAB®, you can explore and develop live image processing and computer vision applications on PCs.

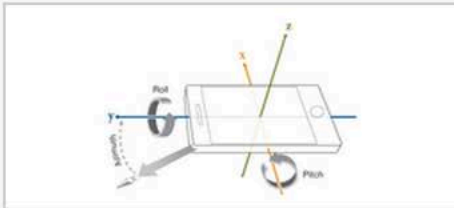
MATLAB provides webcam support through a Hardware Support Package available via the Support Package Installer.



Microsoft Kinect

- Image Acquisition Toolbox (Windows only)
 - Depth map
 - Video
 - Skeleton data for up to 6 people in field of view





MATLAB Support Package for Apple iOS Sensors

by [MathWorks Mobile Sensor Connectivity Team](#)

15 Jul 2015 (Updated 21 Jul 2015)

Use MATLAB to acquire sensor data from built-in sensors on your Apple iOS device



[Watch this File](#)



5.0 | 1 rating

[Rate this file](#)

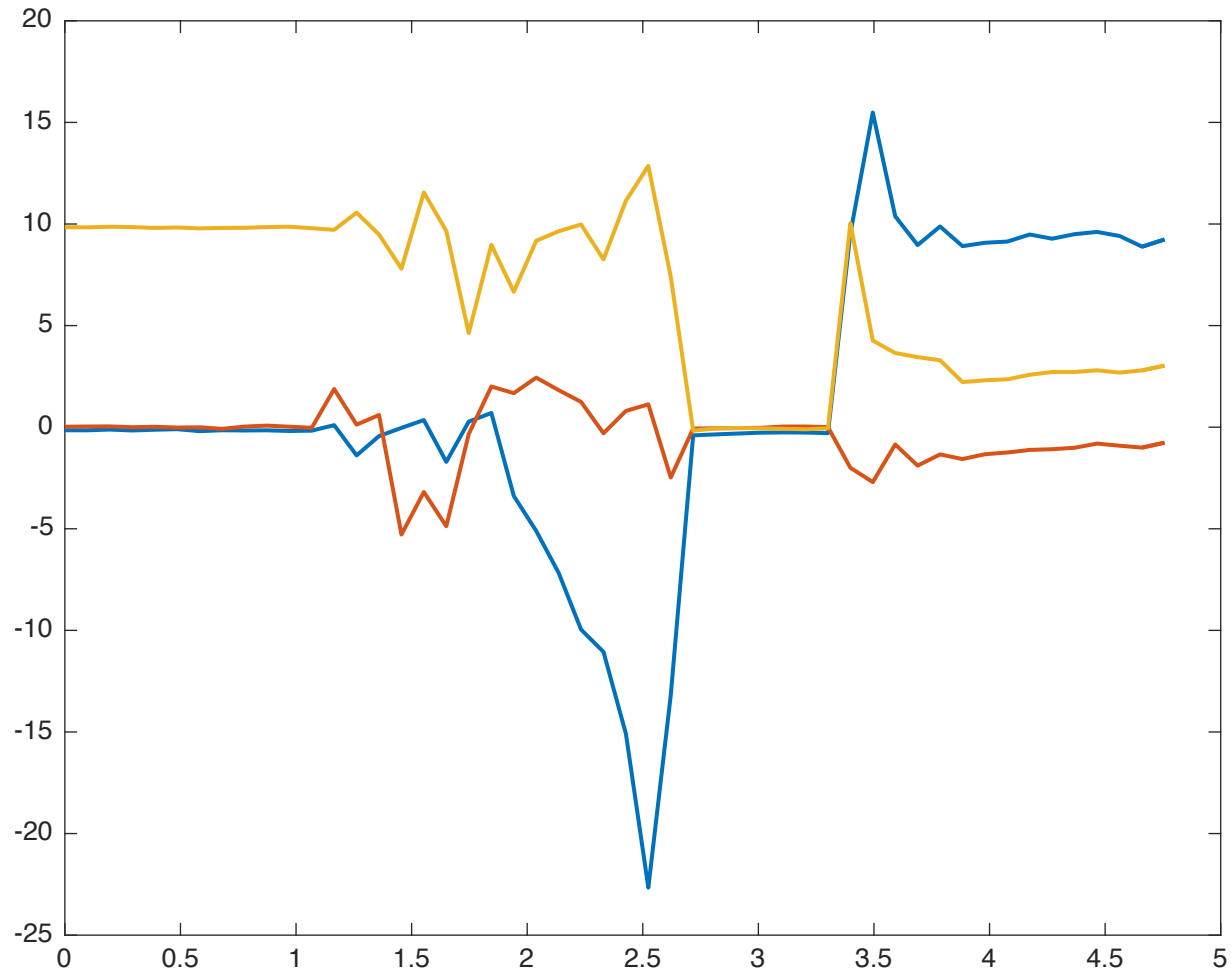
413 Downloads (last 30 days)

File Size: 15.1 KB

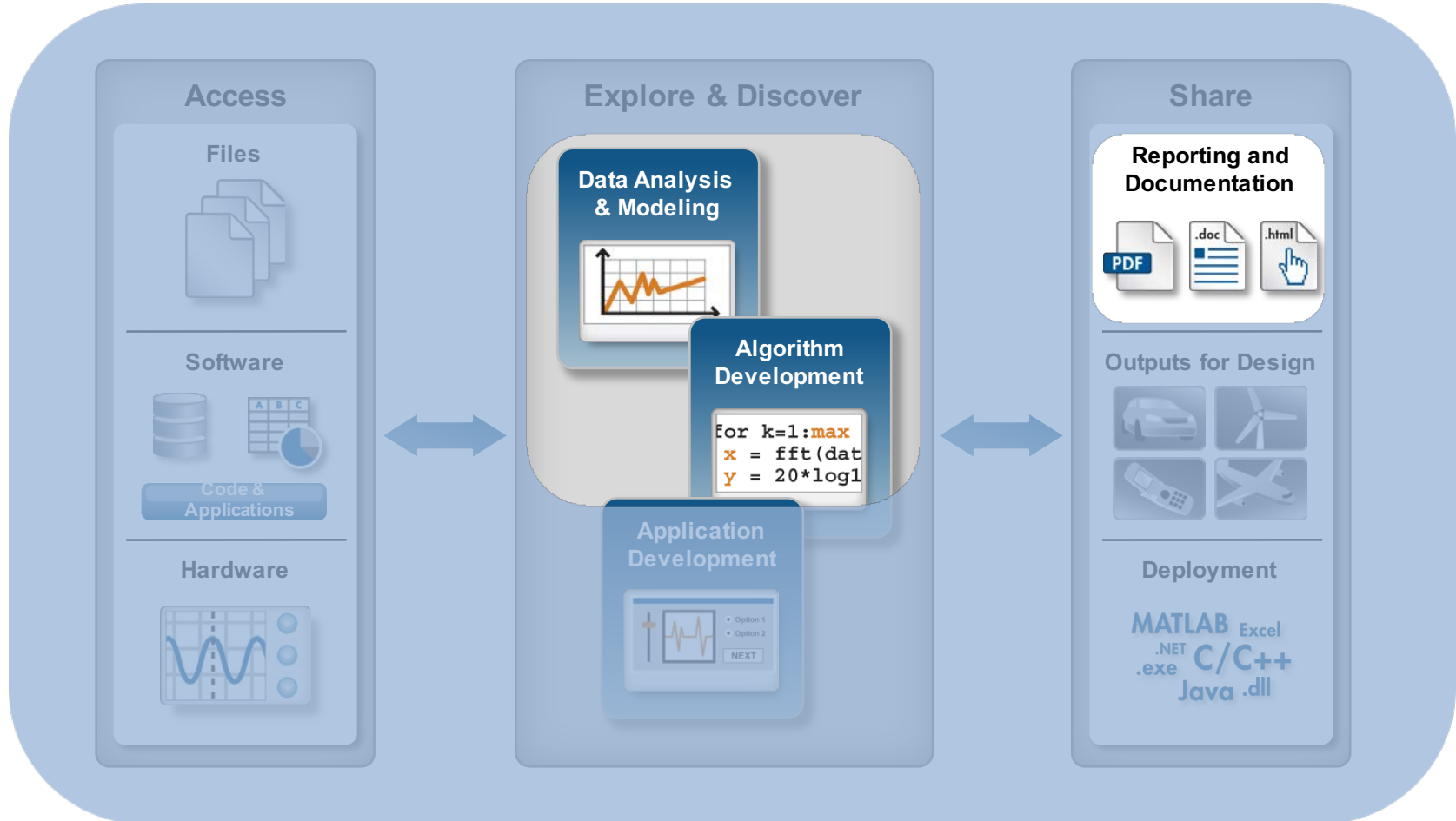
File ID: #51235

Version: 1.0

Foolish Demo



MATLAB Graphics

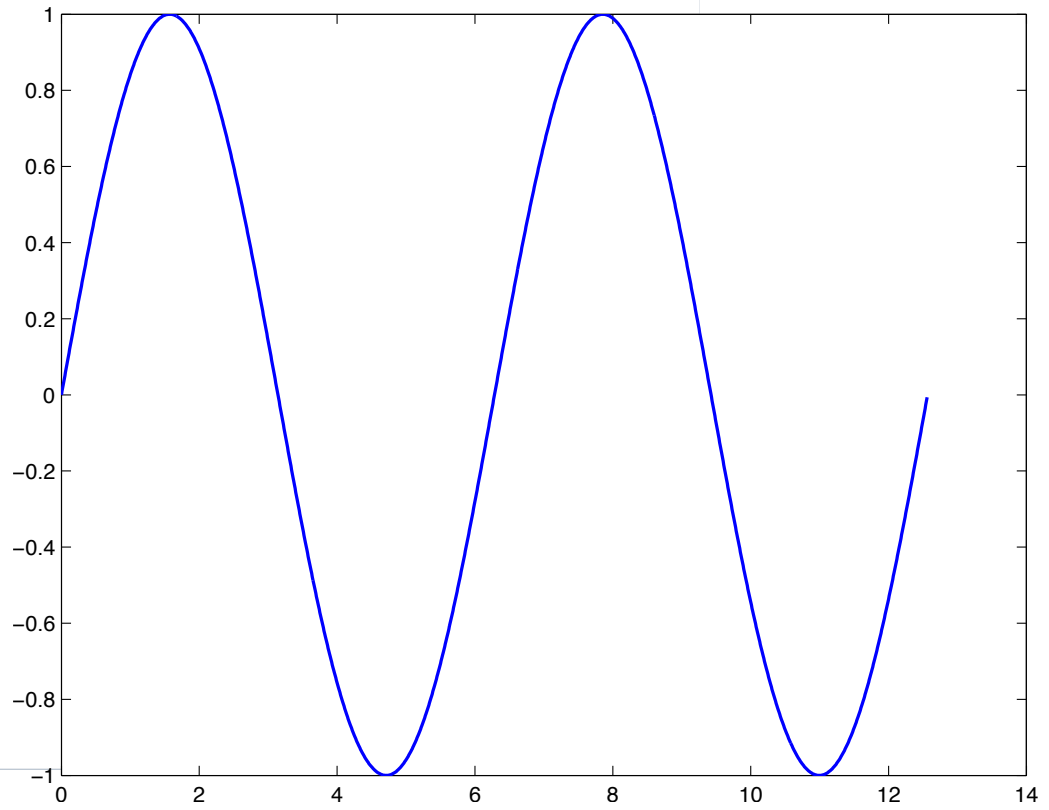


Command Window

```
>> t = 0:0.01:4*pi;  
>> p = plot(t,sin(t))
```

p =

174.0016



Command Window

```
>> t = 0:0.01:4*pi;  
>> p = plot(t,sin(t))
```

p =

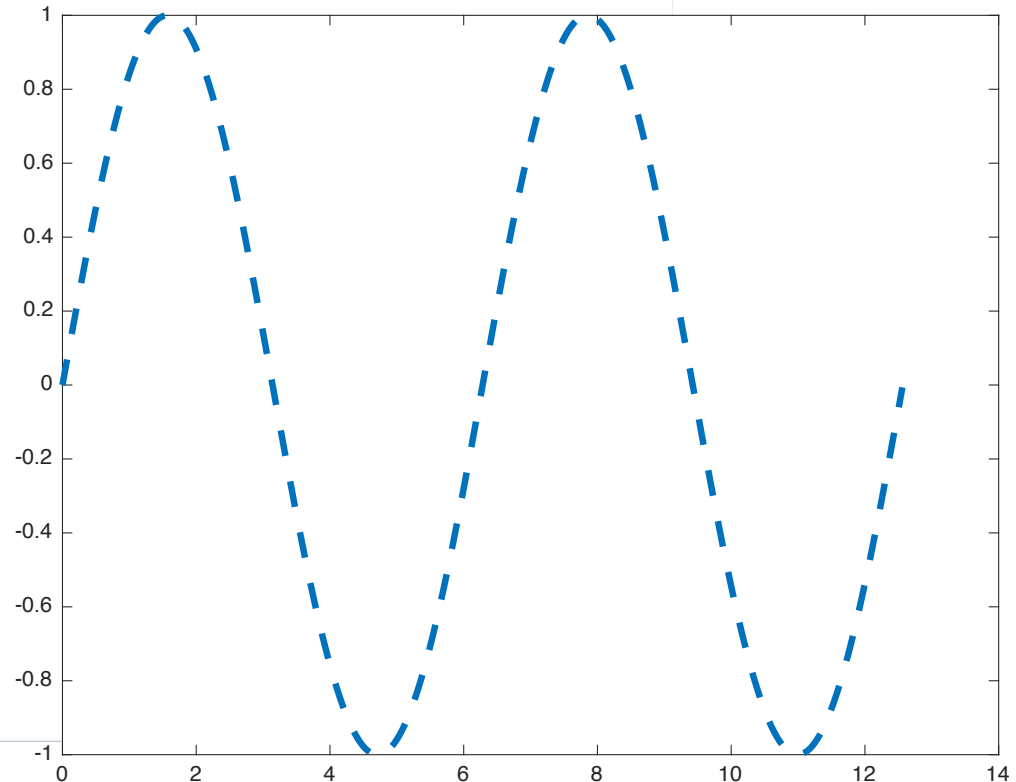
[Line](#) with properties:

Color: [0 0.4470 0.7410]
LineStyle: '-' ←
LineWidth: 1.5000 ←
Marker: 'none'
MarkerSize: 6
MarkerFaceColor: 'none'
XData: [1x1257 double]
YData: [1x1257 double]
ZData: [1x0 double]

Show [all properties](#)

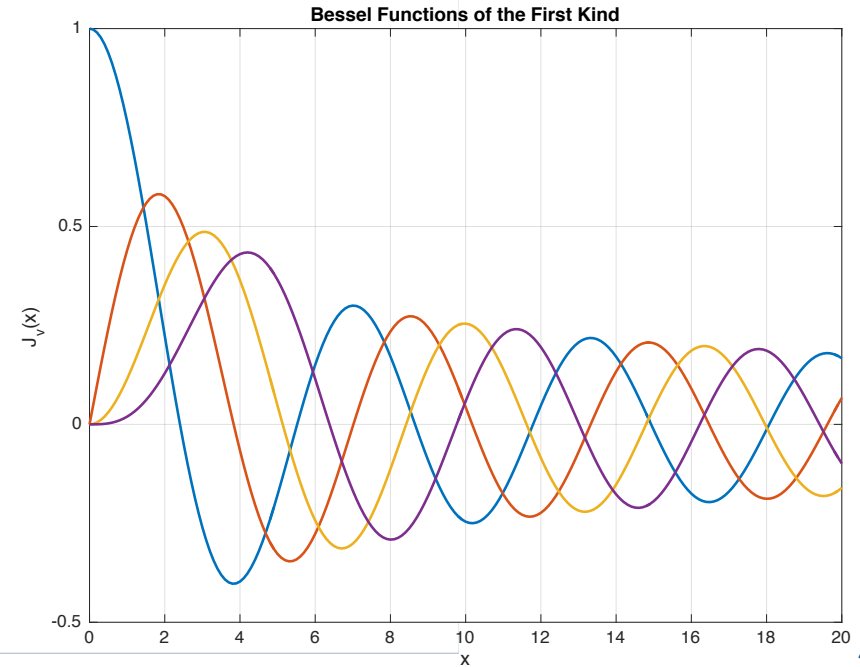
Command Window

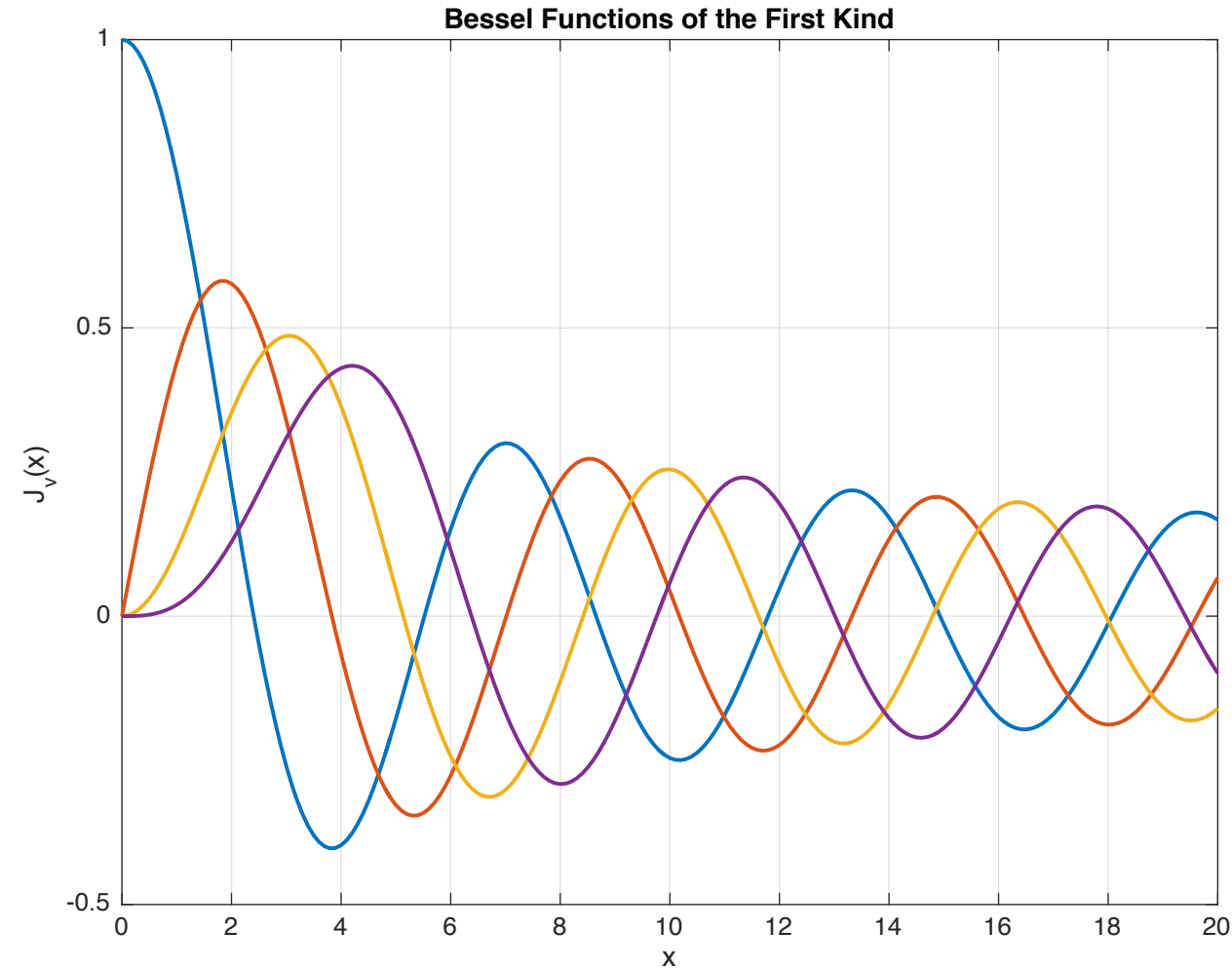
```
>> p.LineStyle = '--';  
>> p.LineWidth = 3;
```



Command Window

```
>> x = 0:0.1:20;  
>> plot(x,besselj(0,x));  
>> grid on  
>> title('Bessel Functions of the First Kind')  
>> xlabel('x')  
>> ylabel('J_v(x)')  
>> hold on  
>> plot(x,besselj(1,x))  
>> plot(x,besselj(2,x))  
>> plot(x,besselj(3,x))  
>> hold off
```





Antialiased lines, text

Subtle grid color
that doesn't distract

Line colors easier to
distinguish

Better "hold on" behavior

Better title formatting

exponent on axis ($2 \cdot 10^{-2}$ instead of 0.02)

Subject: exponent on axis ($2 \cdot 10^{-2}$ instead of 0.02)

From: [Rachel van Ooteghem](#)

Date: 19 Dec, 2005 11:04:16

Message: 1 of 6

[Reply to this message](#)

[⊕ Add author to My Watch List](#)

[View original format](#)

[Flag as spam](#)

When I give: `plot([0 1],[0 0.02])` I get a graph where on the y-axis the ticks range from 0 to 0.02.

Due to space limitations I would rather have it like it does with: `plot([0 1],[0 0.002])`, where the ticks range from 0 to 2, with an exponent above the y-axis. Matlab does this automatically for smaller values on the axes.

I would like to have a y-axis from 0 to 2 with an exponent of 10^{-2} .

Is this possible?

"I would like to have a y-axis from 0 to 2
with an exponent of 10^{-2} "

How do I format tick labels?



Asked by [MathWorks Support Team](#) on 5 Aug 2013

Latest activity Edited by [MathWorks Support Team](#) on 23 Dec 2014

Accepted Answer by [MathWorks Support Team](#)

I have an axis with tick labels and I want them all to have 3.1 format. For example, I do a plot (1:5) and I change my tick labels using the command

```
set(gca, 'XTick', [1.0 1.5 2.0 2.5 3.0 3.5 4.0 4.5 5.0])
```

However, they appear as:

```
[1 1.5 2 2.5 3 3.5 4 4.5 5]
```

I would like to get them to appear as I typed them in the above command.

Also, I want to know if it is possible to specify the format of the plot axes tick label which is automatically placed by MATLAB.

"I want all my axes tick labels to have one fractional digit."

Command Window

```
>> plot([0 1],[0 0.02])  
>> ax = gca;  
>> yruler = ax.YAxis
```

```
yruler =
```

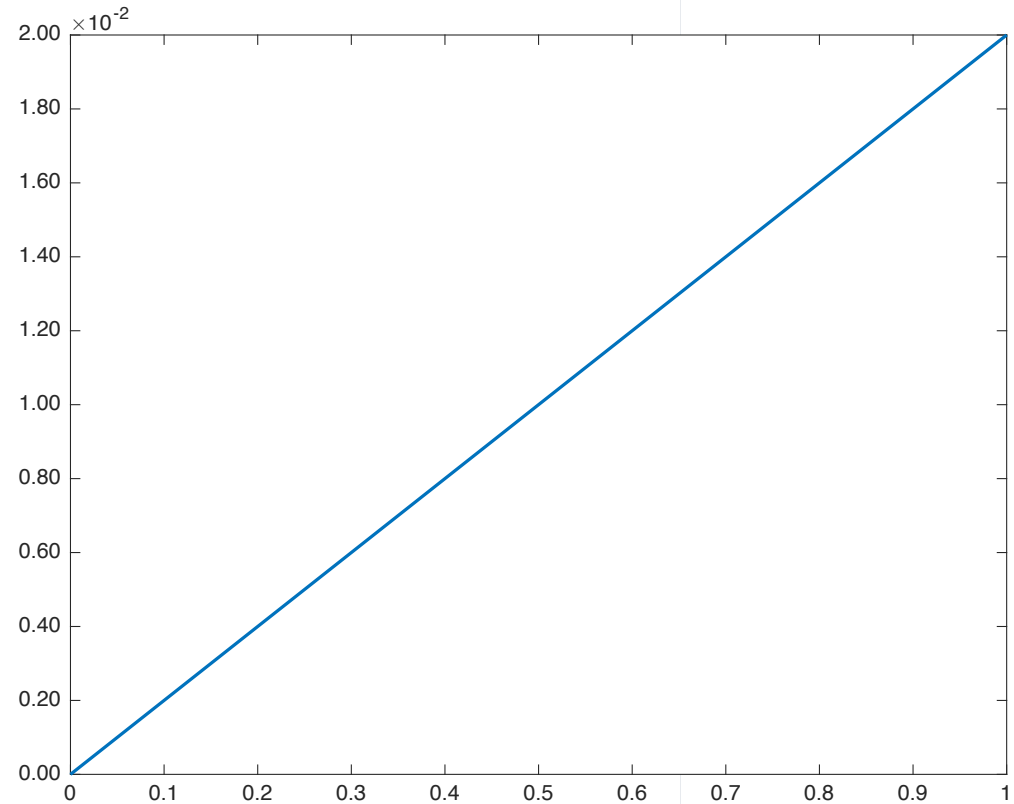
[NumericRuler](#) with properties:

```
    Limits: [0 0.020000000000000000]  
    Scale: 'linear'  
    Exponent: 0  
    TickValues: [1x11 double]  
    TickLabelFormat: '%g'
```

Show [all properties](#)

Command Window

```
>> yruler.Exponent = -2;  
>> yruler.TickLabelFormat = '%4.2f';
```

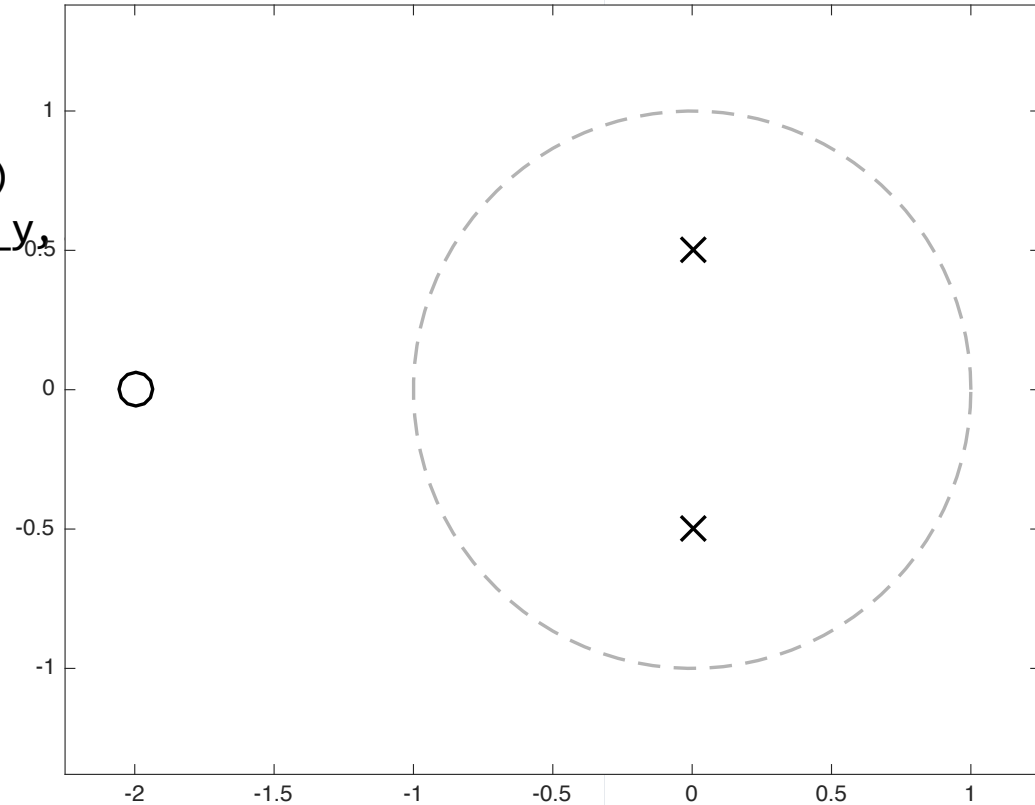


Command Window

```
>> theta = linspace(0,2*pi,100);  
>> unit_circle_x = cos(theta);  
>> unit_circle_y = sin(theta);  
>> plot([0 0],[-0.5 0.5],'xk',...  
        'MarkerSize',15)  
>> hold on  
>> plot(-2,0,'ok','MarkerSize',15)  
>> plot(unit_circle_x,unit_circle_y,...  
        'Color',[.7 .7 .7],...  
        'LineStyle','--');  
>> hold off  
>> axis([-2.25 1.25 -1.25 1.25])  
>> axis equal
```

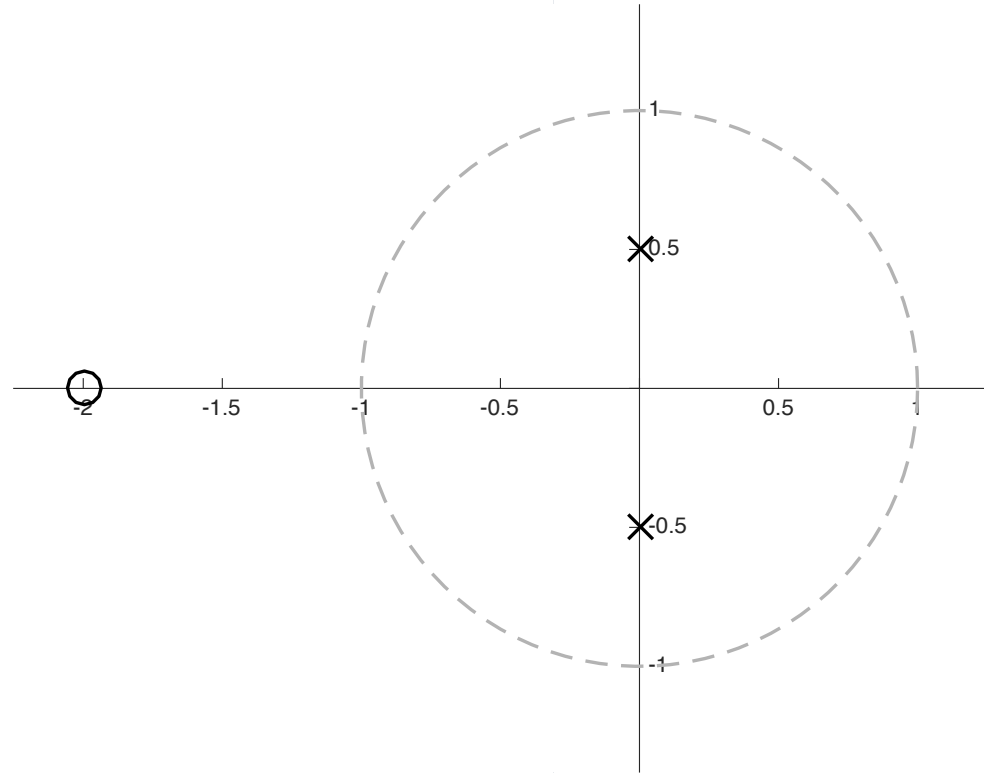

Command Window

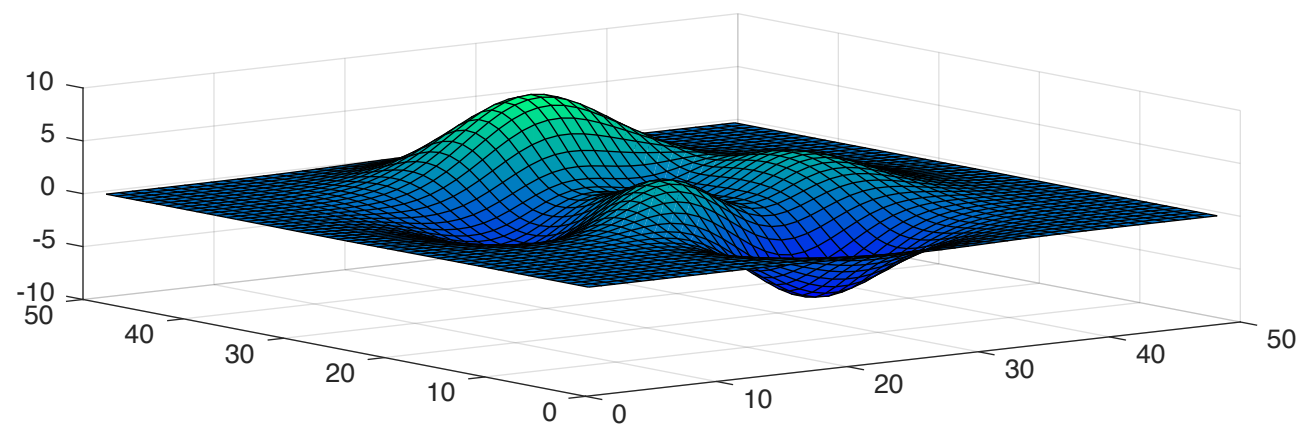
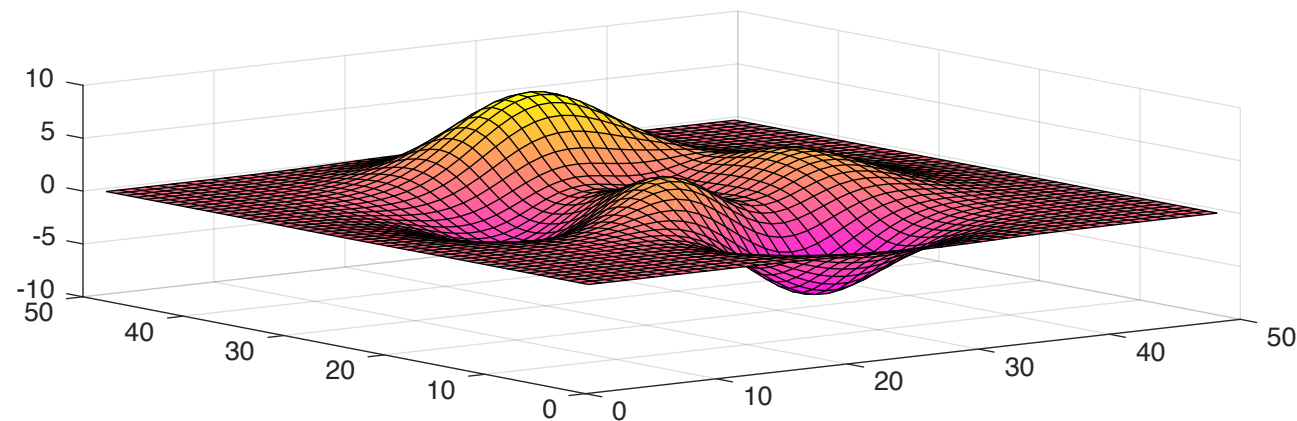
```
>> theta = linspace(0,2*pi,100);  
>> unit_circle_x = cos(theta);  
>> unit_circle_y = sin(theta);  
>> plot([0 0],[-0.5 0.5],'xk',...  
        'MarkerSize',15)  
>> hold on  
>> plot(-2,0,'ok','MarkerSize',15)  
>> plot(unit_circle_x,unit_circle_y,...  
        'Color',[.7 .7 .7],...  
        'LineStyle','--')  
>> hold off  
>> axis([-2.25 1.25 -1.25 1.25])  
>> axis equal
```

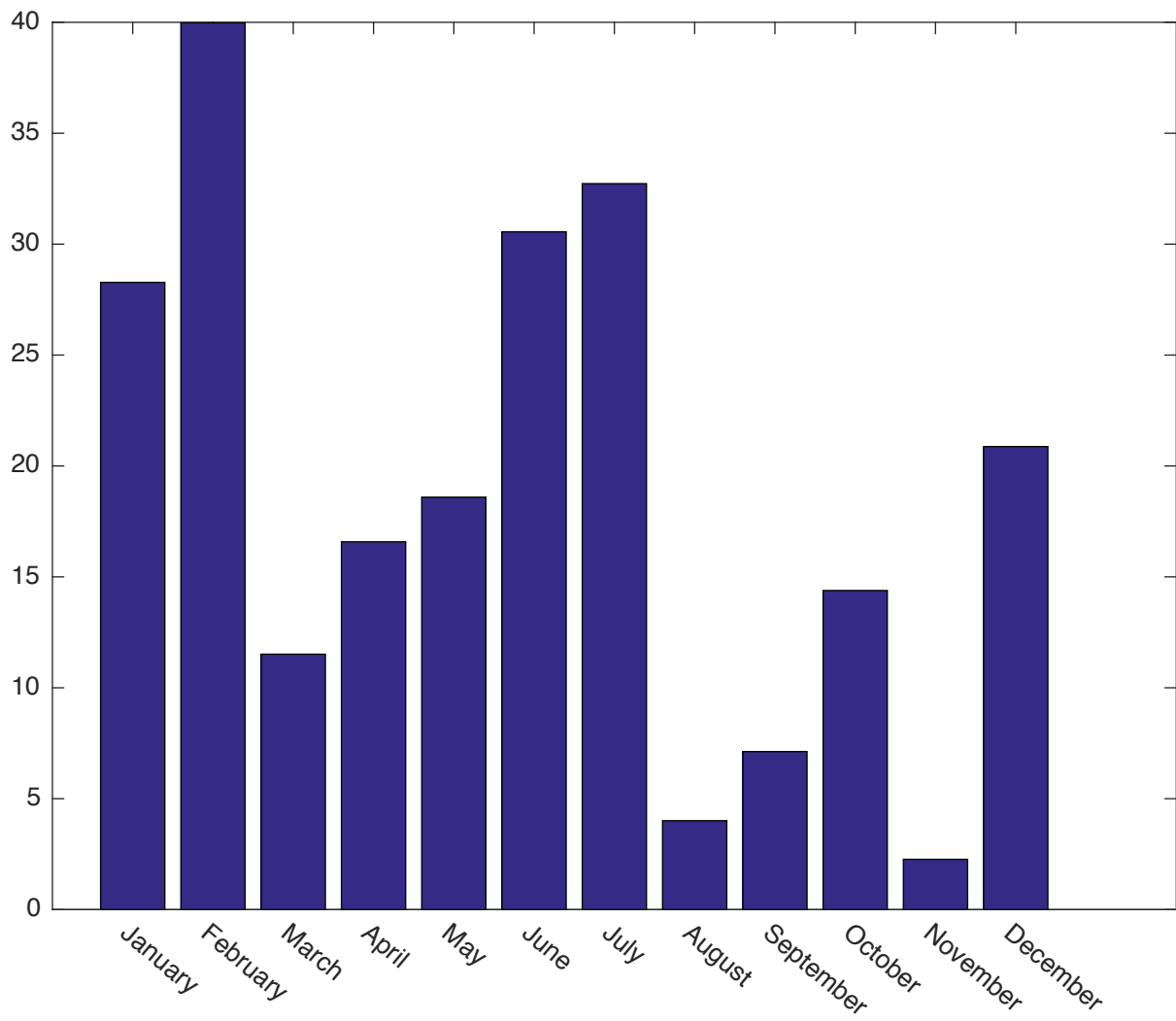


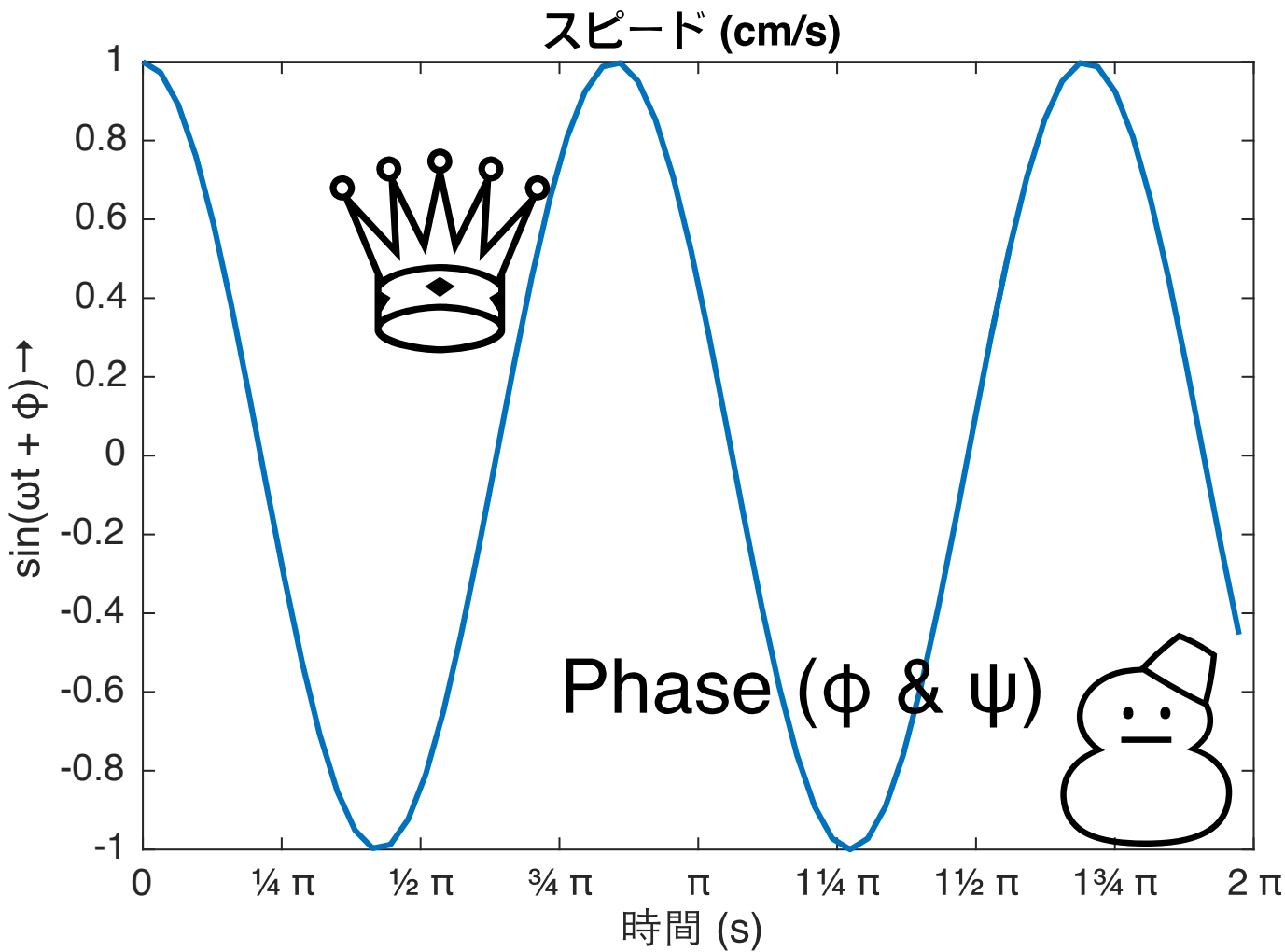
Command Window

```
>> ax = gca;  
>> ax.XAxisLocation = 'origin';  
>> ax.YAxisLocation = 'origin';  
box off
```





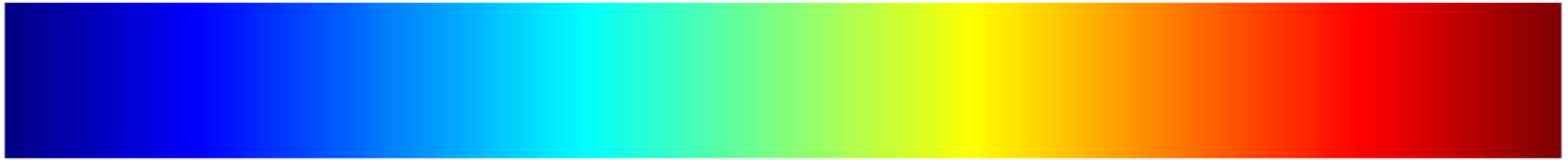




What's a Parula?



Image credit: [Dario Sanches](#). Cropped by Steve Eddins



The "jet" colormap
MATLAB default from 1997 – 2014
Also known as a "rainbow" colormap

Rainbow Color Map (Still) Considered Harmful

*IEEE Computer
Graphics and
Applications,*
2007
Borland &
Taylor II

Research has shown that the rainbow color map is rarely the optimal choice when displaying data with a pseudocolor map. The rainbow color map confuses viewers through its lack of perceptual ordering, obscures data through its uncontrolled luminance variation, and actively misleads interpretation through the introduction of non-data-dependent gradients.

Despite much published research on its deficiencies, the rainbow color map is prevalent in the visualization community. We present survey results showing that the rainbow color map continues to appear in more than half of the relevant papers in IEEE Visualization Conference proceedings; for example, it appeared on 61 pages in 2005. Its use is encouraged by its selection as the default color map used in most visualization toolkits that we inspected. The visualization community must do better.

In this article, we reiterate the characteristics that

mericals, weather forecasts, and even the IEEE Visualization Conference 2006 call for papers, just to name a few. The problem with this wide use of the rainbow color map is that research shows that it is rarely, if ever, the optimal color map for a given visualization.¹⁻⁶ Here we will discuss the rainbow color map's characteristics of confusing the viewer, obscuring data, and actively misleading interpretation.

Confusing

For all tasks that involve comparing relative values, the color map used should exhibit perceptual ordering. A simple example of a perceptually ordered color map is the gray-scale color map. Increasing luminance from black to white is a strong perceptual cue that indicates values mapped to darker shades of gray are lower in value than values mapped to lighter shades of gray. This mapping is natural and intuitive.

Data visualization: the end of the rainbow

IEEE Spectrum, 1998
Rogowitz & Treinish



t the core of all good science and engineering is the respectful treatment of data: instruments are calibrated, algorithms are scrutinized, and the behavior of analytical or simulation models studied, on the assumption that the tools suit the data at hand.

But the knowledge to use one set of tools, data visualization software, is often lacking. Visualization should help make sense of the flood of output data. When applied without some insight into visual perception, however, it can introduce errors in understanding as surely as if a wrong analysis algorithm were used. In short, a picture can tell a thousand lies.

Blind spots in visualization are inevitable if attention is not paid to how the human visual system processes information, to the nature of the data, and to how the data are to be used. But once identified, these factors can be manip-

ulated to good effect, as a variety of visualizations drawn from fields as diverse as geography, medicine, and physics will show.

The key is the colormap, which may be defined as a mapping from a data value to a color. (The term colormap is also sometimes used in other contexts specifically for the contents of the memory locations governing display.)

A rainbow colormap is often supplied as a default in visualization software, the vendor wishing perhaps to provide the greatest possible range of colors with which to work. In this kind of colormap, red is mapped to the highest data value, blue to the lowest, and the other data values are interpolated along the full extent of the spectrum. An example would be a temperature profile mapped over a land mass on a weather map.

But there is more to color than meets the eye. Color, after all, is a perceptual as well as physical phenomenon. What is commonly called color—hue—is only one of three parameters. Another is the brightness of the signal—intensity. The third is the admixture of white—saturation. Change

BERNICE E. ROGOWITZ & LLOYD A. TREINISH
IBM Corp., Thomas J. Watson Research Center

The End of the Rainbow? Color Schemes for Improved Data Graphics

PAGES 385,391

Modern computer displays and printers enable the widespread use of color in scientific communication, but the expertise for designing effective graphics has not kept pace with the technology for producing them. Historically, even the most prestigious publications have tolerated high defect rates in figures and illustrations [Cleveland, 1984], and technological advances that make creating and reproducing graphics easier do not appear to have decreased the frequency of errors. Flawed graphics consequently beget more flawed graphics as authors emulate published examples. Color has the potential to enhance communication, but design mistakes can result in color figures that are less effective than gray scale displays of the same data.

Empirical research on human subjects can build a fundamental understanding of visual perception [Ware, 2004] and scientific methods can be used to evaluate existing designs, but creating effective data graphics is a design task and not fundamentally a scientific pursuit. Like writing well, creating good data graphics requires a combination of formal knowledge and artistic sensibility tempered by experience: a combination of "substance, statistics, and design" [Tufte, 1983, p. 51].

Unlike writing, however, proficiency in creating data graphics is not a main component of secondary or postsecondary education. This article provides some concrete suggestions to

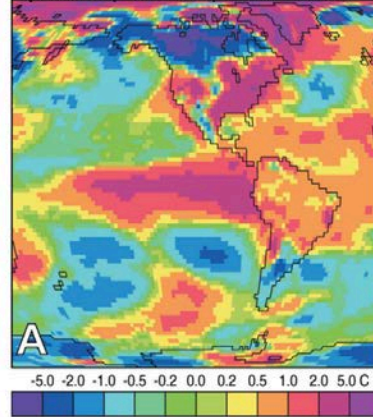
one spectral color scheme, and a better alternative, may appear to color-blind readers.

Color-blind individuals see some colored data graphics quite differently from the general population. The human visual system normally perceives color through photosensitive cones in the eye that are tuned to receive wavelengths in the red, green, and blue portions of the visible spectrum. People who lack cones sensitive to one of the three wavelengths are called dichromats [Fortner and Meyer, 1997]. Individuals whose

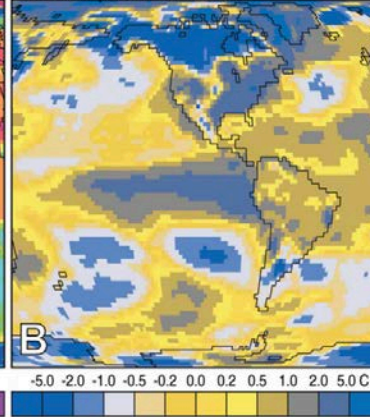
receptors are shifted toward one or the other end of the spectrum are called anomalous trichromats. The term "color deficient" encompasses dichromats and anomalous trichromats, as well as those who exhibit rarer forms of impaired color vision. Because a sex-linked recessive gene is implicated in the condition, color-vision deficiency is far more common in men than in women.

Algorithms based on psychophysical observations make it possible to simulate the appearance of colored images to color-deficient viewers [Brettel et al., 1997]. Data maps of the type shown here serve two main purposes: detection of large-scale patterns and determination of specific grid-cell or point values. The saturated spectral scale (Figure 1a) creates a region of confusion centered on the North American continent where achieving either purpose becomes nearly impossible for dichromat

Spectral (Rainbow) Color Scale



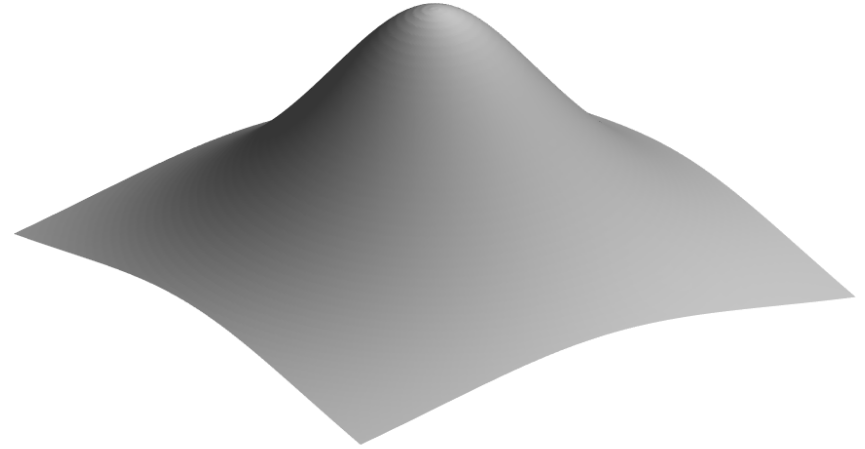
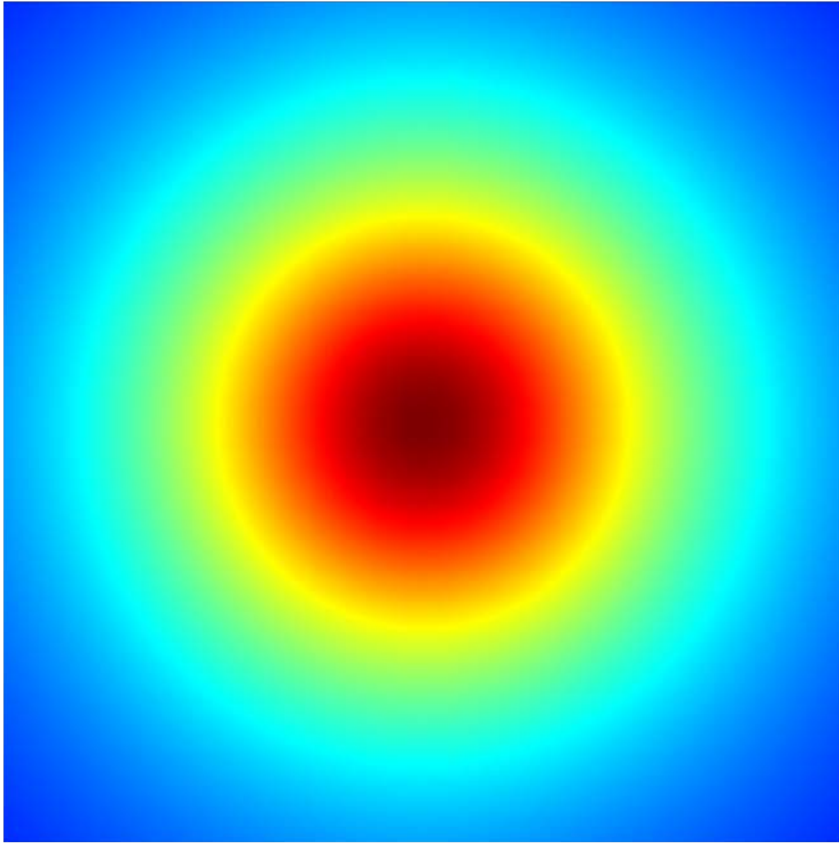
Protanopic Simulation

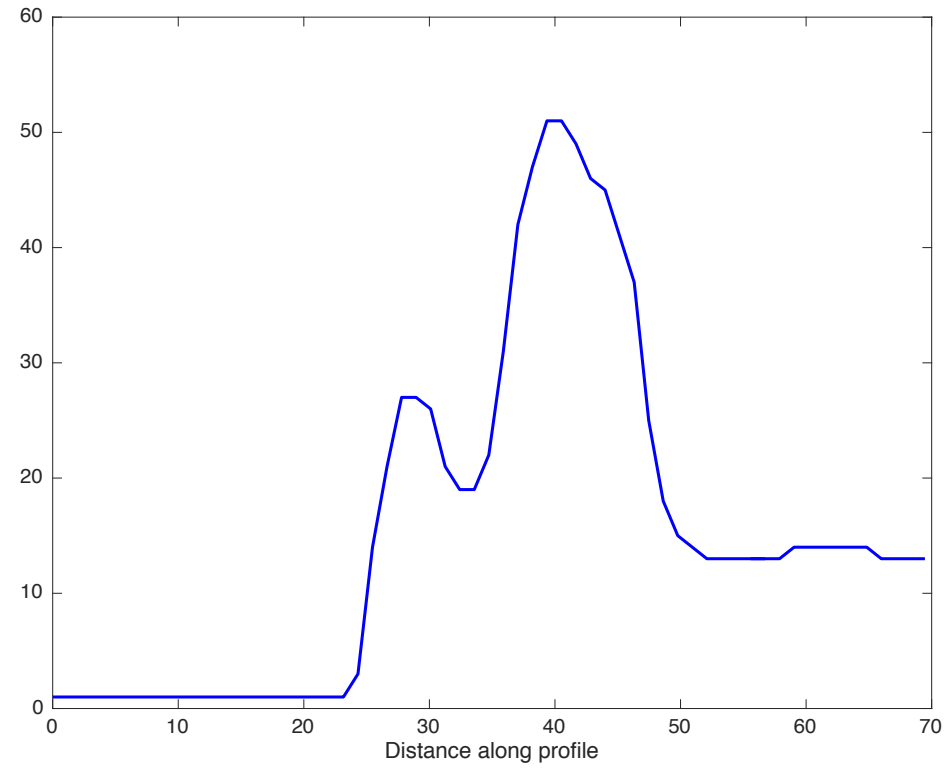
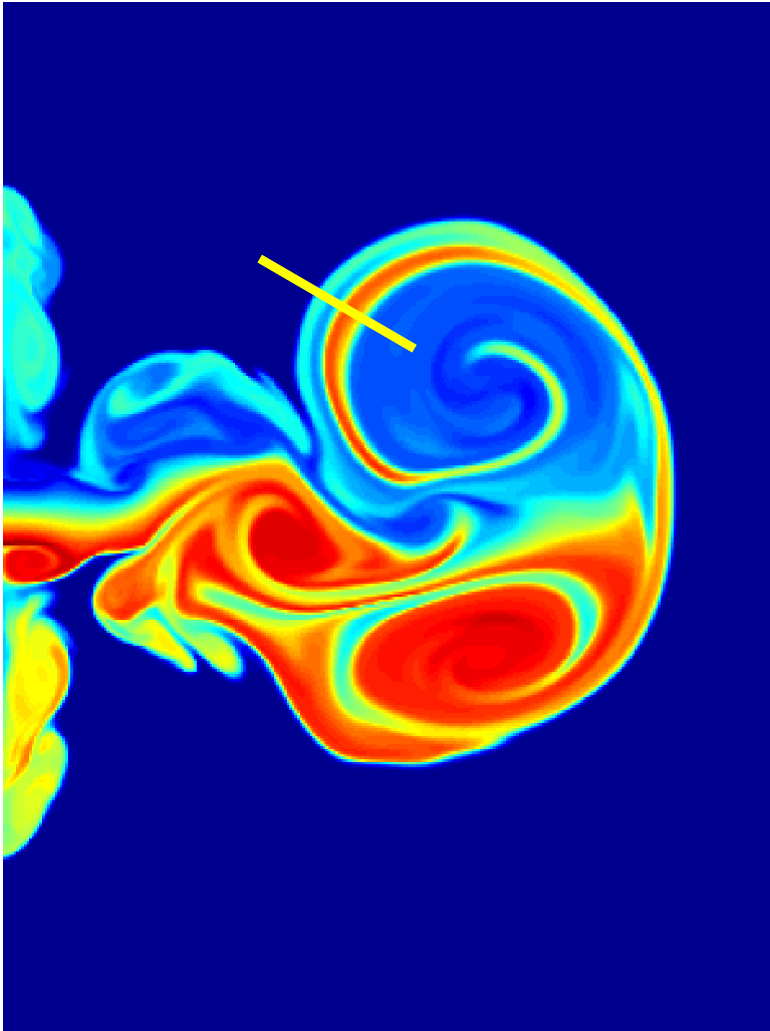


*EOS, Transactions of
American
Geophysical
Union, 2004
Light & Bartlein*

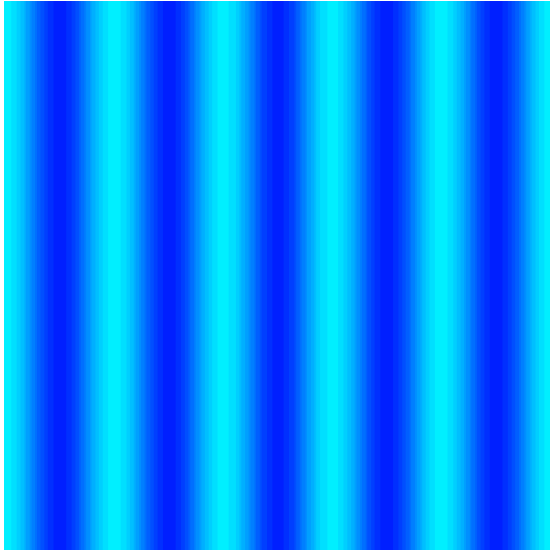
Rainbow criticisms

- Confuses viewers because lack of perceptual ordering of spectral colors
- Obscures data detail in some parts of colormap
- Conveys false data detail in other parts of colormap
- Causes difficulty for some color-impaired viewers
- Prints poorly to gray-scale devices

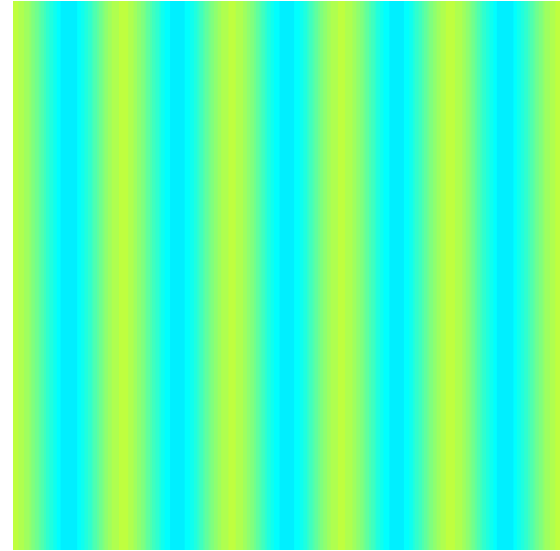




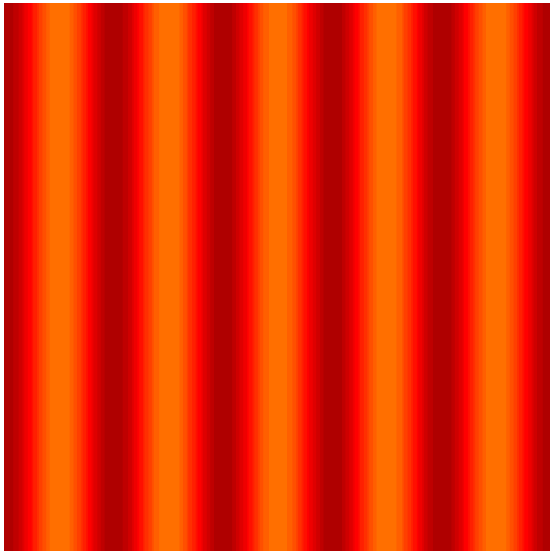
A



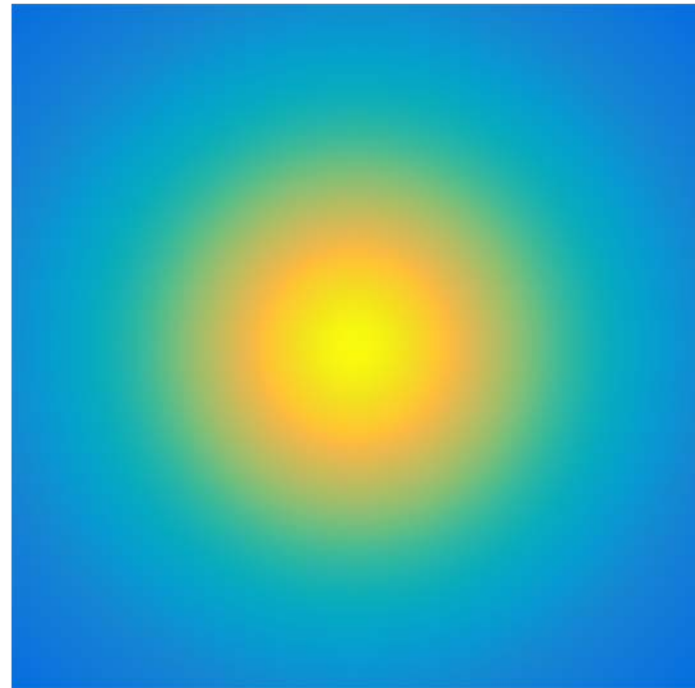
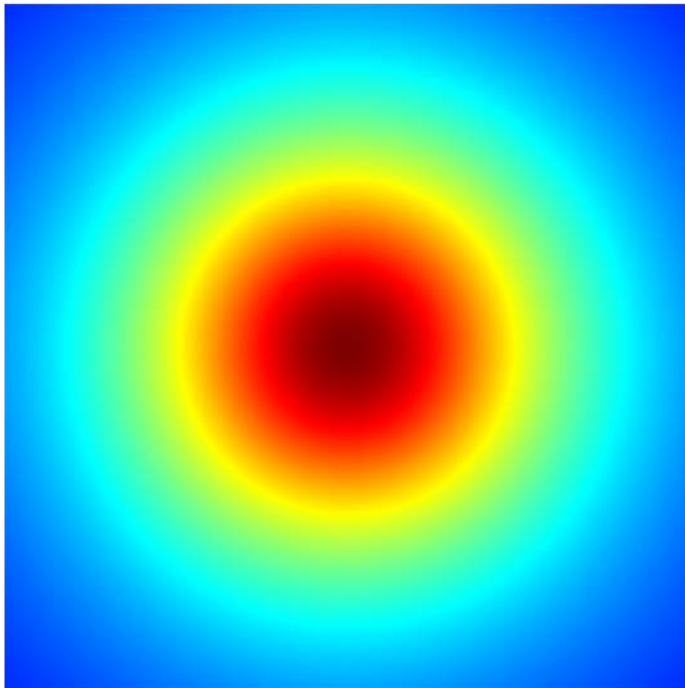
B

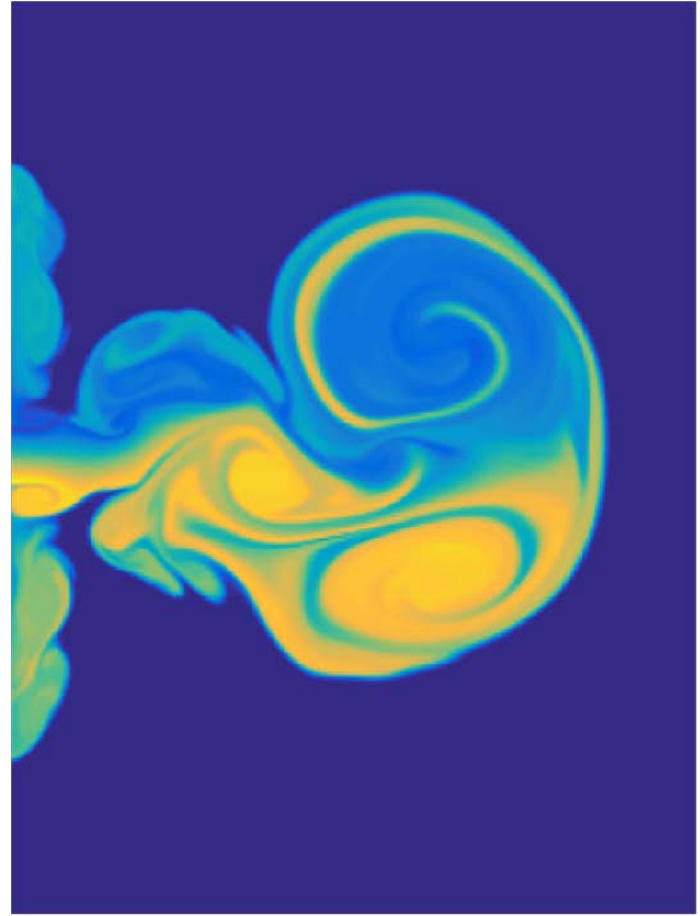
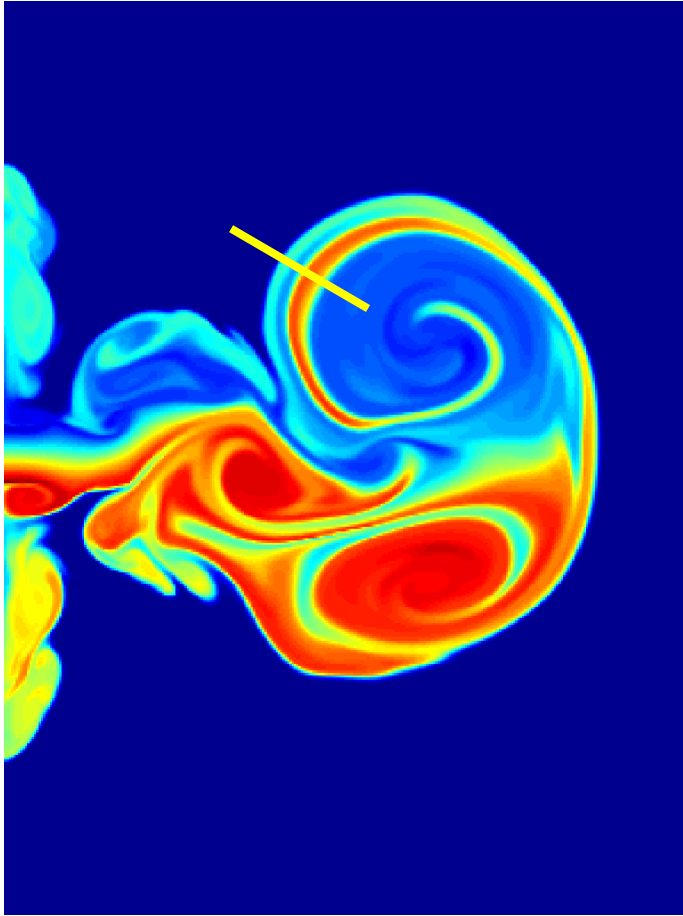


C

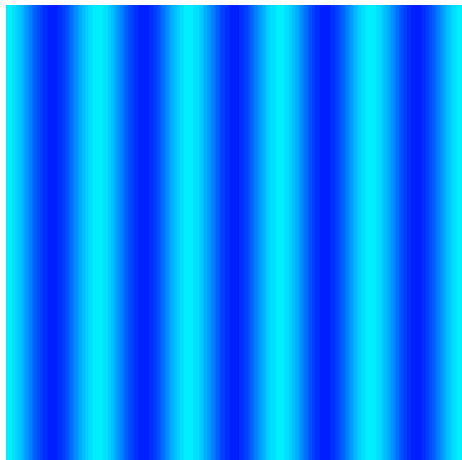




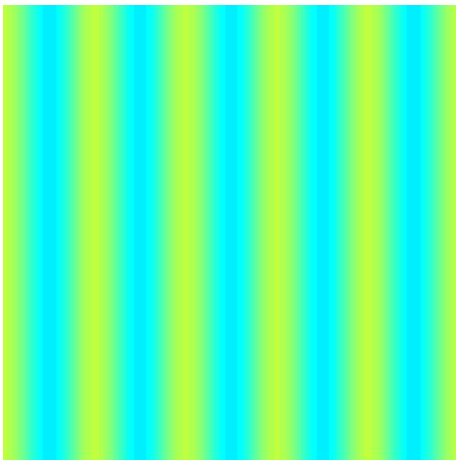




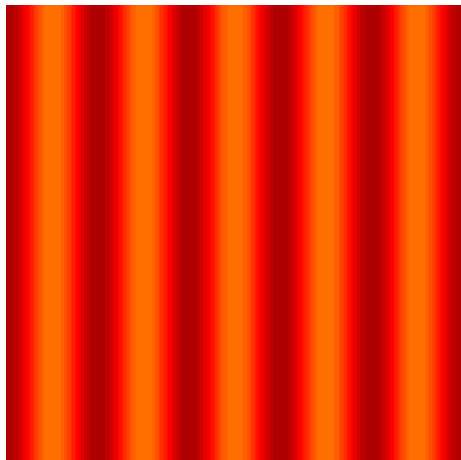
A



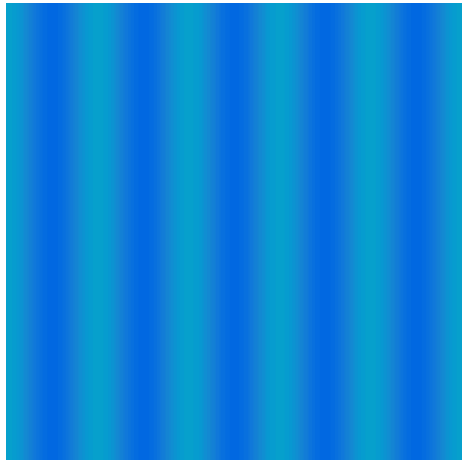
B



C



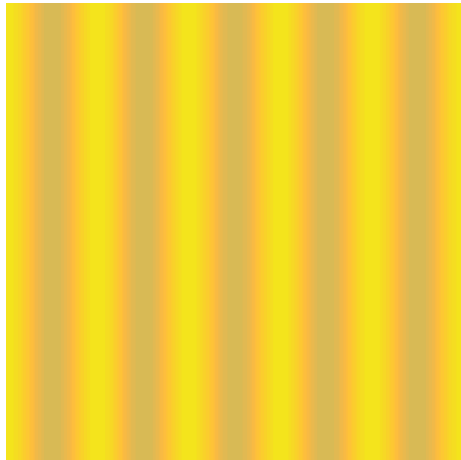
A



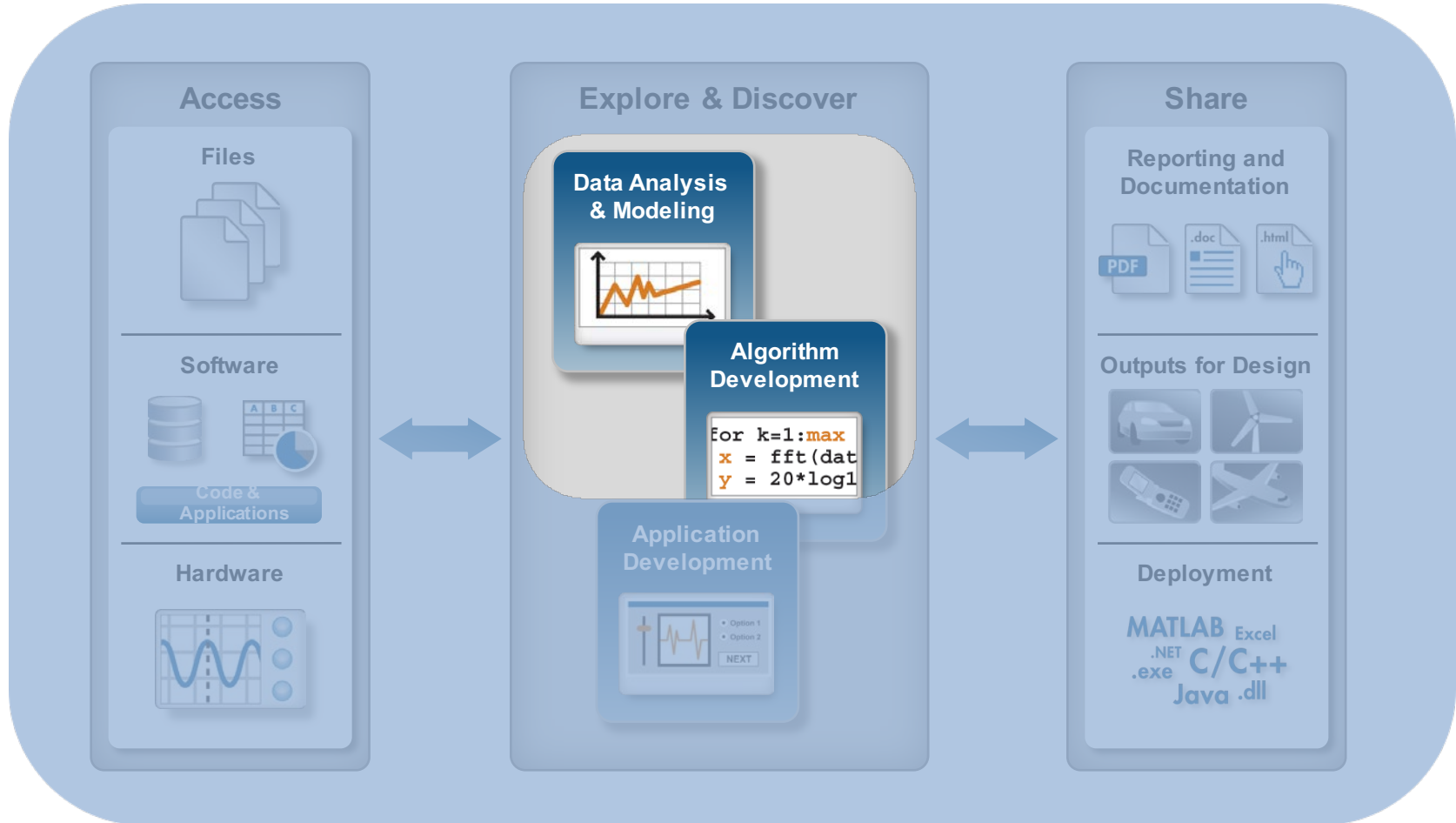
B



C



MATLAB Math



MATLAB Math Topics

- Histograms
- Alpha shapes
- Graphs

Histograms: A New Project Begins

- Peter

"Hey, you know we could really be doing a lot better with histograms in MATLAB."
- The rabble

"What do you mean? `hist` has been in MATLAB since the dawn of time. What's the problem?"
- Peter (later, and at regular intervals)

"Hey, you know we could really be doing a lot better with histograms in MATLAB."
- The rabble (eventually)

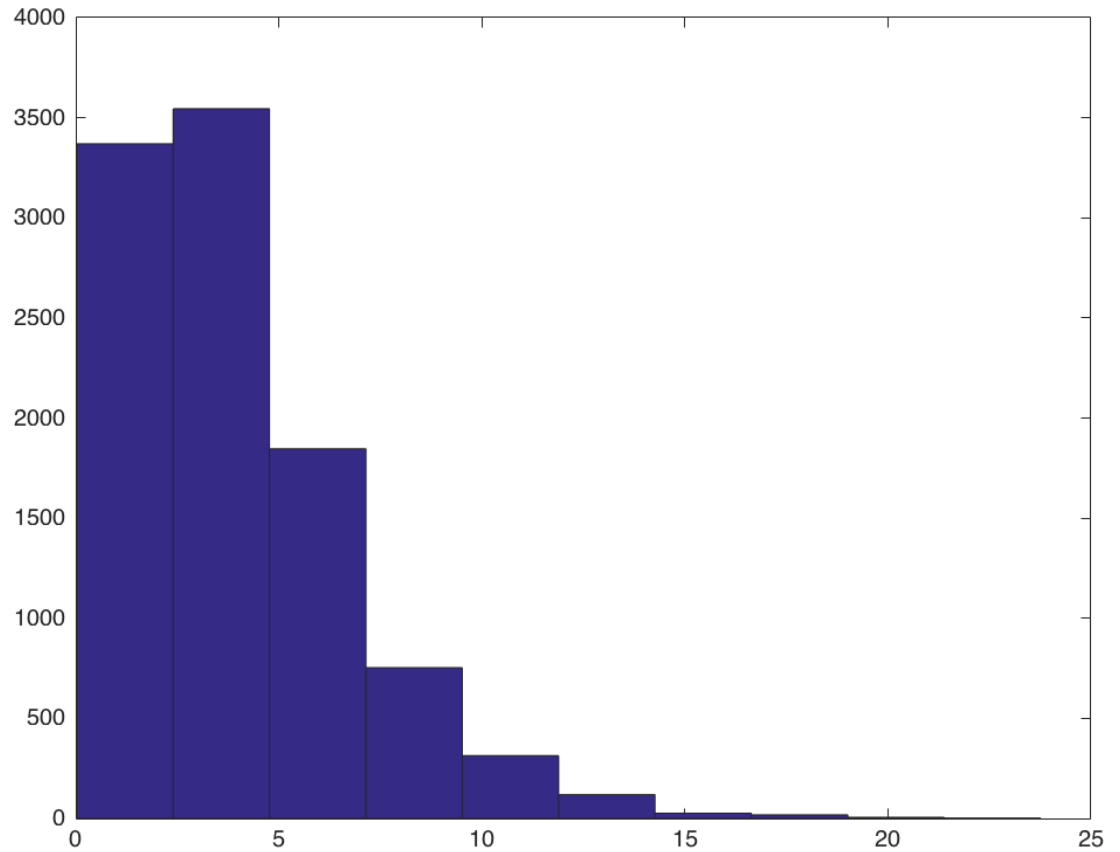
"OK, let's do some research on this."

Issues with hist

- Confusion over hist and histc
- Default selection of 10 bins
- Floating-point input only
- Awkward behavior at left-most and right-most bin edges
- Histogram chart looks bad for multiple histograms
- Modifying histogram chart appearance too difficult
- Normalization computation subtle, mistake-prone

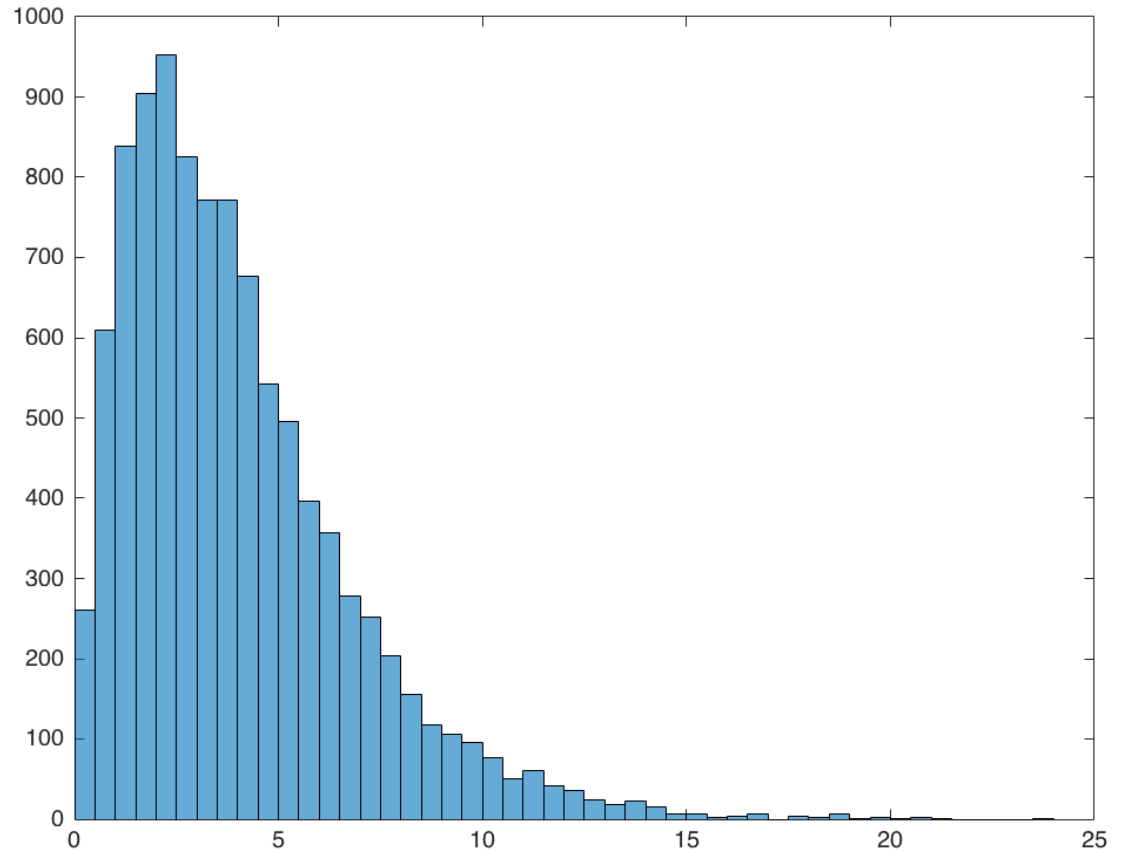
Command Window

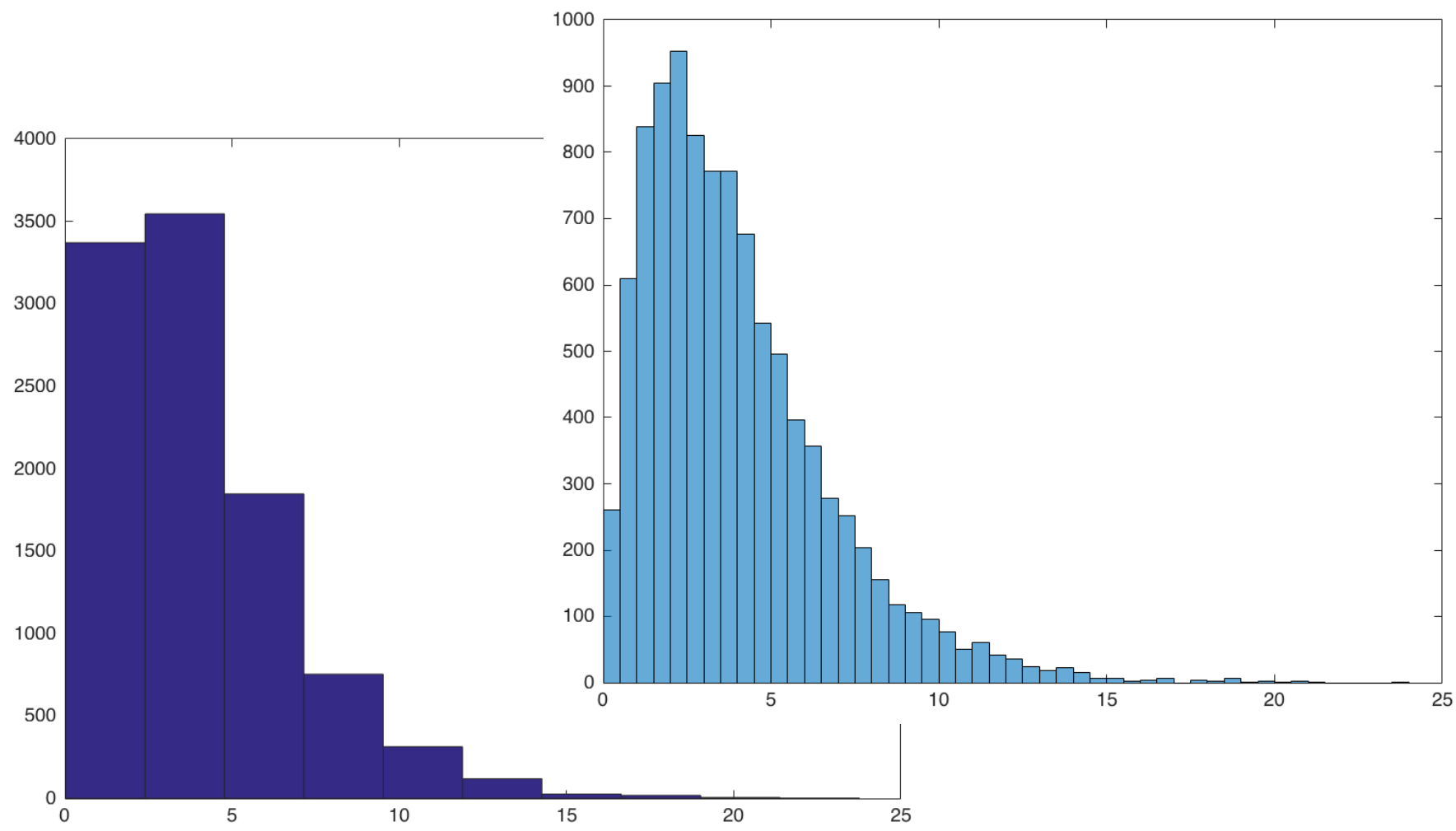
```
>> data = random('chi2',4,10000,1);  
>> hist(data)
```



Command Window

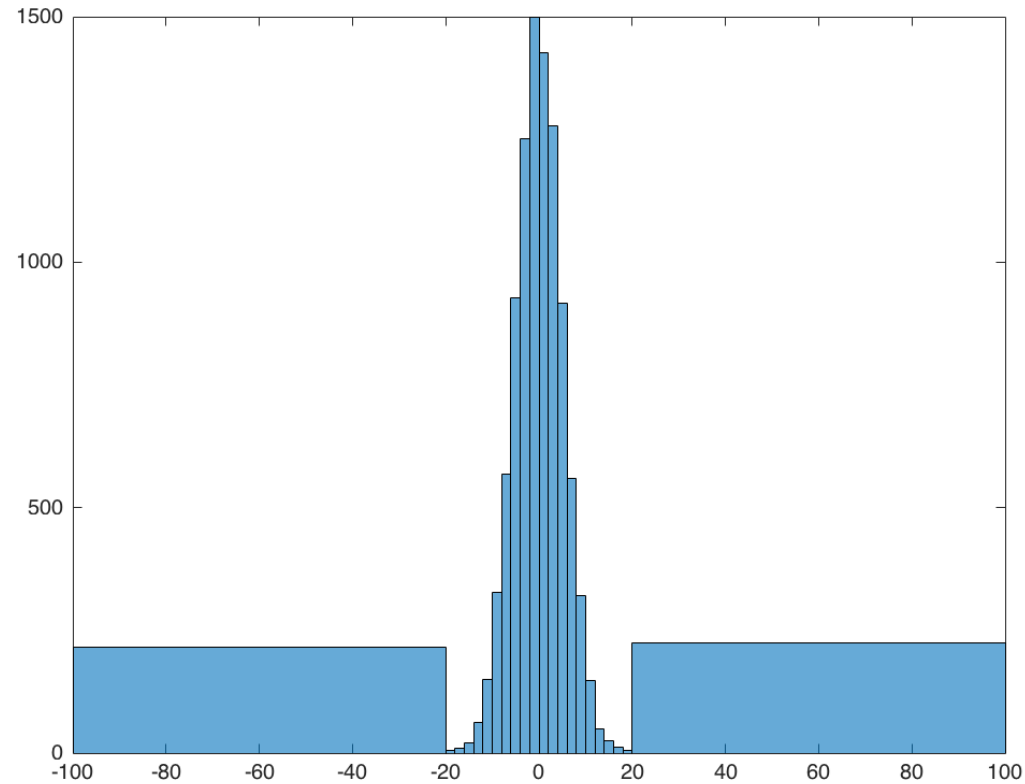
```
>> data = random('chi2',4,10000,1);  
>> histogram(data)
```





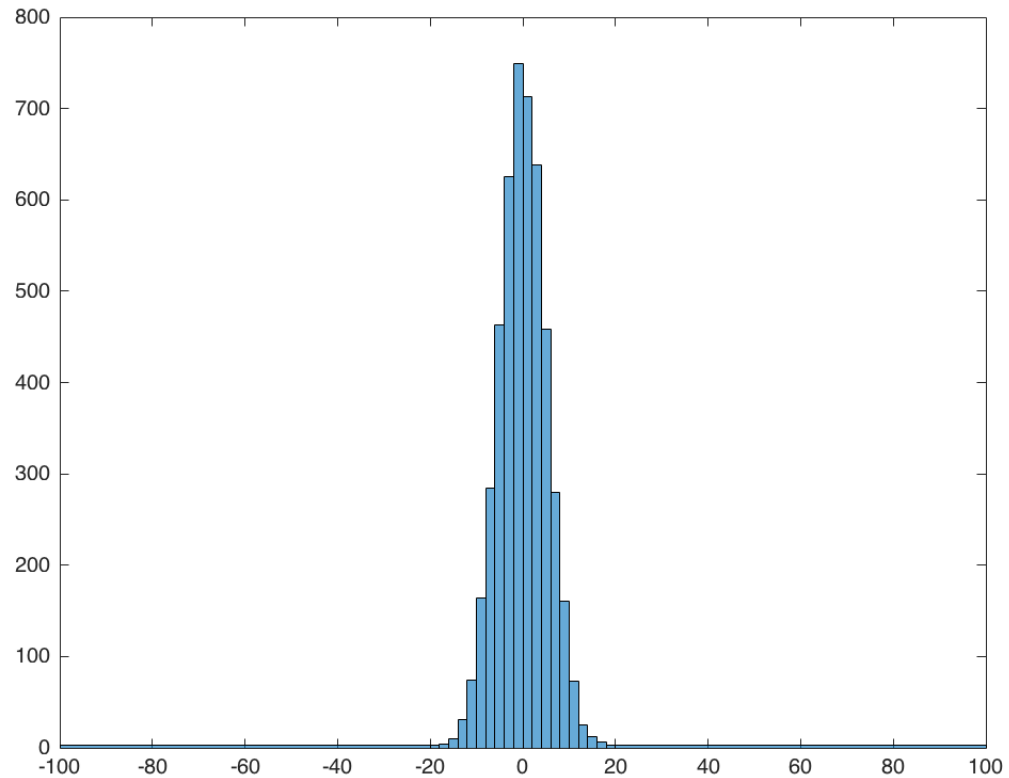
Command Window

```
>> bin_edges = [-100 (-20:2:20) 100];  
>> histogram(data,bin_edges)
```



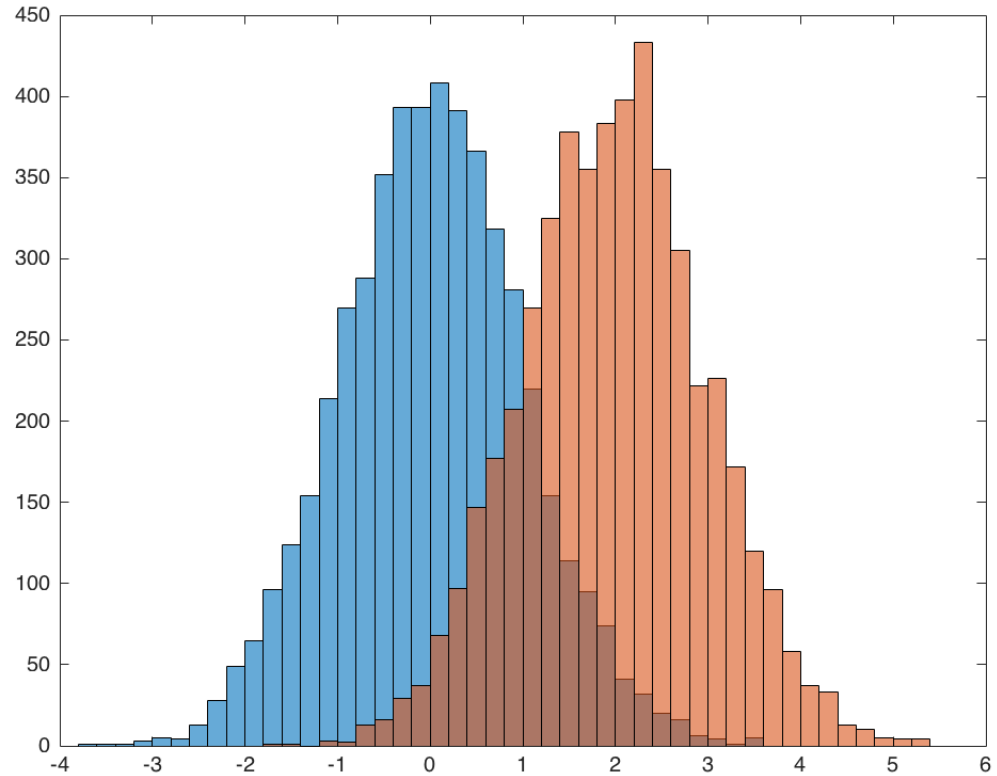
Command Window

```
>> bin_edges = [-100 (-20:2:20) 100];  
>> histogram(data,bin_edges,'Normalization','countdensity')
```



Command Window

```
>> hist([data1 data2])  
>> histogram(data1)  
>> hold on  
>> histogram(data2)  
>> hold off
```



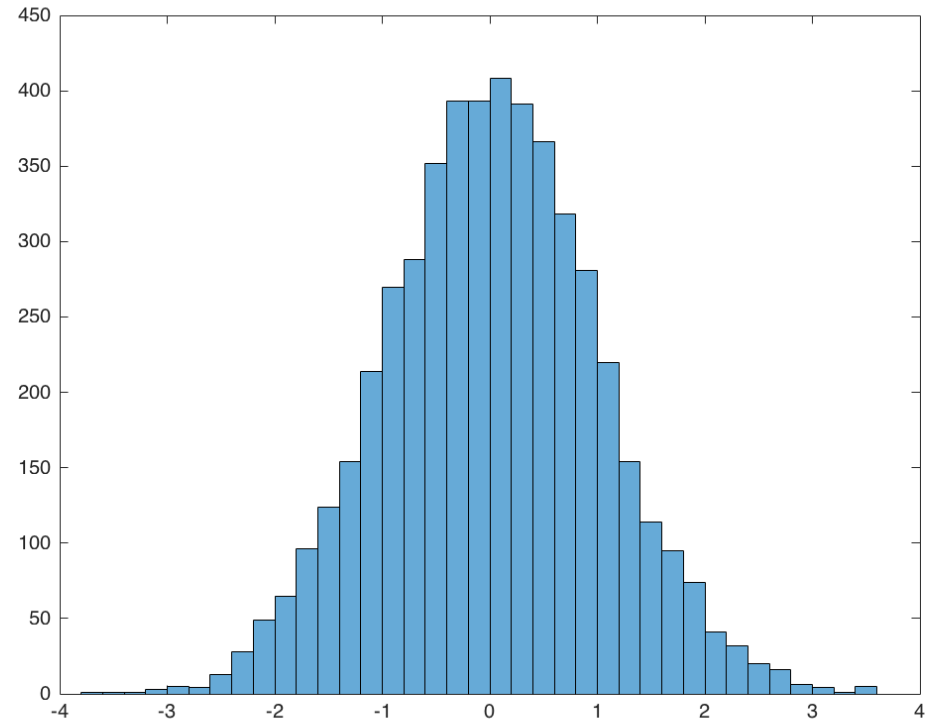
Command Window

```
>> h = histogram(data1)
```

h = [Histogram](#) with properties:

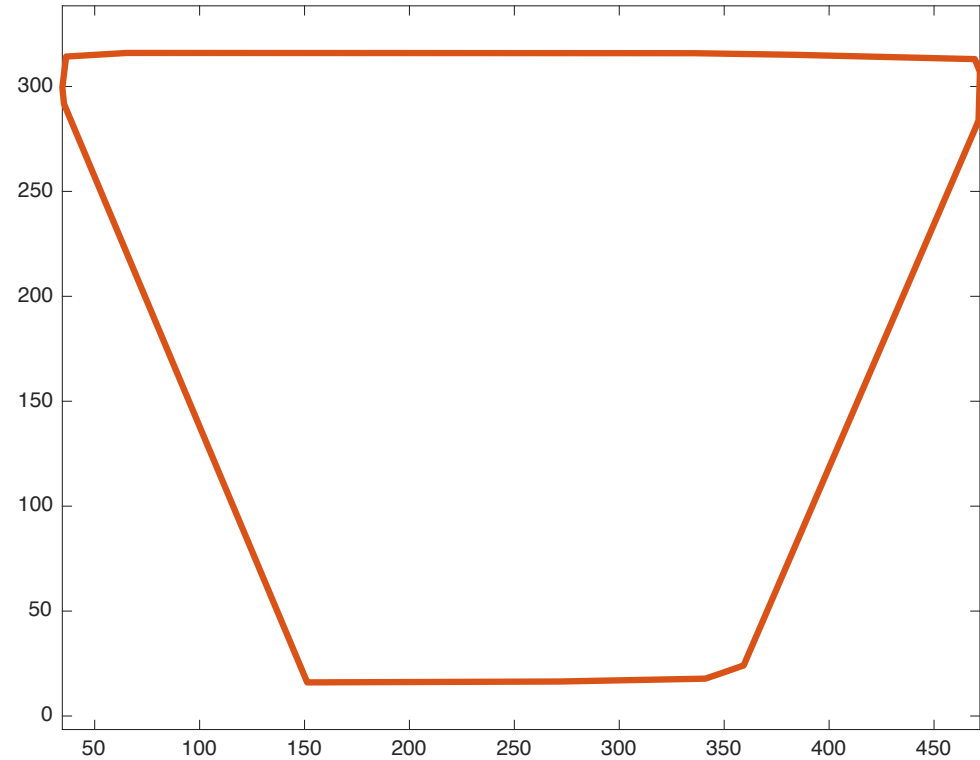
Data: [5000x1 double]
Values: [1x37 double]
NumBins: 37
BinEdges: [1x38 double]
BinWidth: 0.2000
BinLimits: [-3.8000 3.6000]
Normalization: 'count'
FaceColor: 'auto'
EdgeColor: [0 0 0]

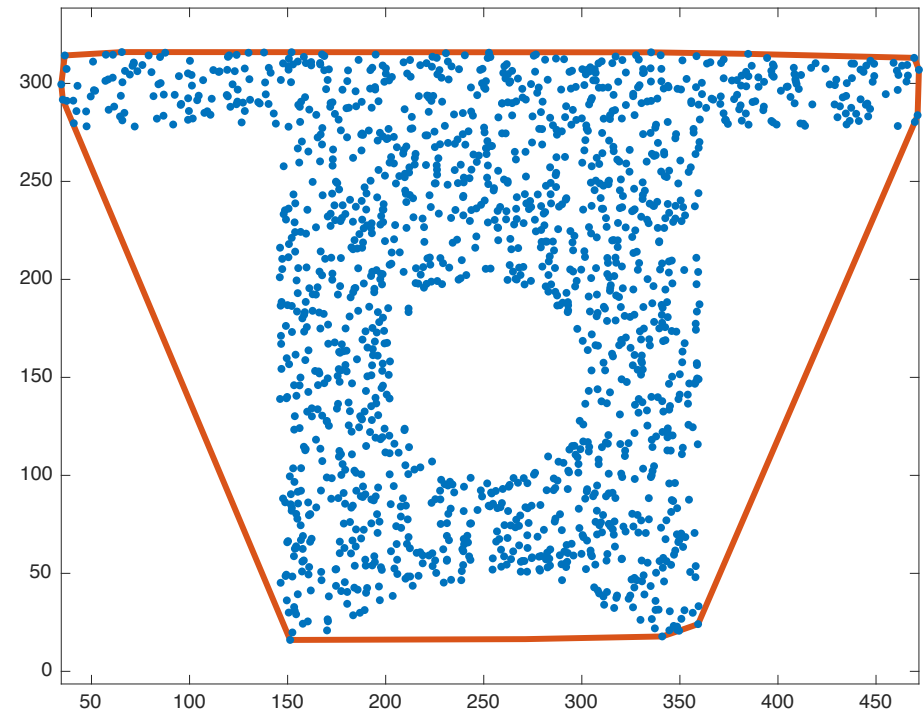
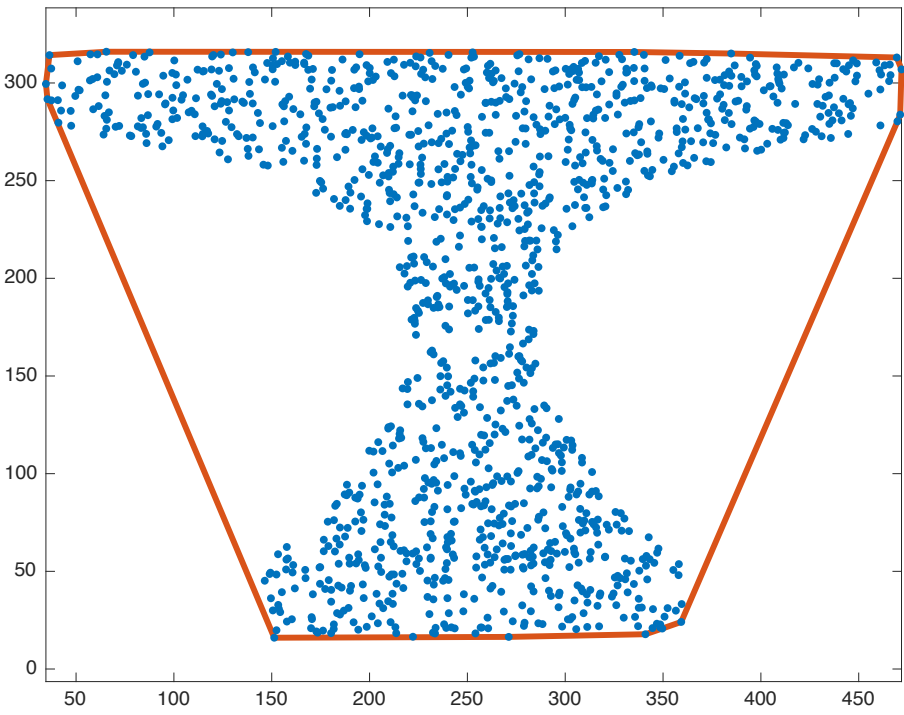
Show [all properties](#)

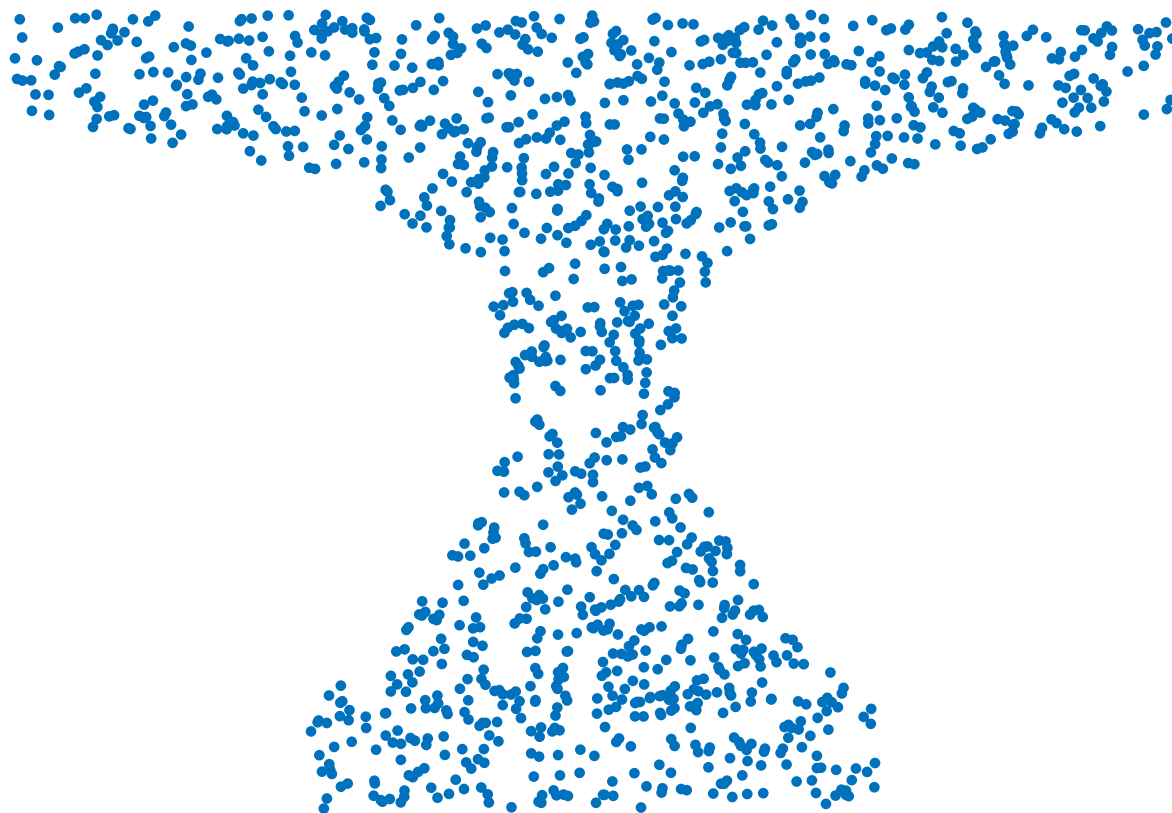


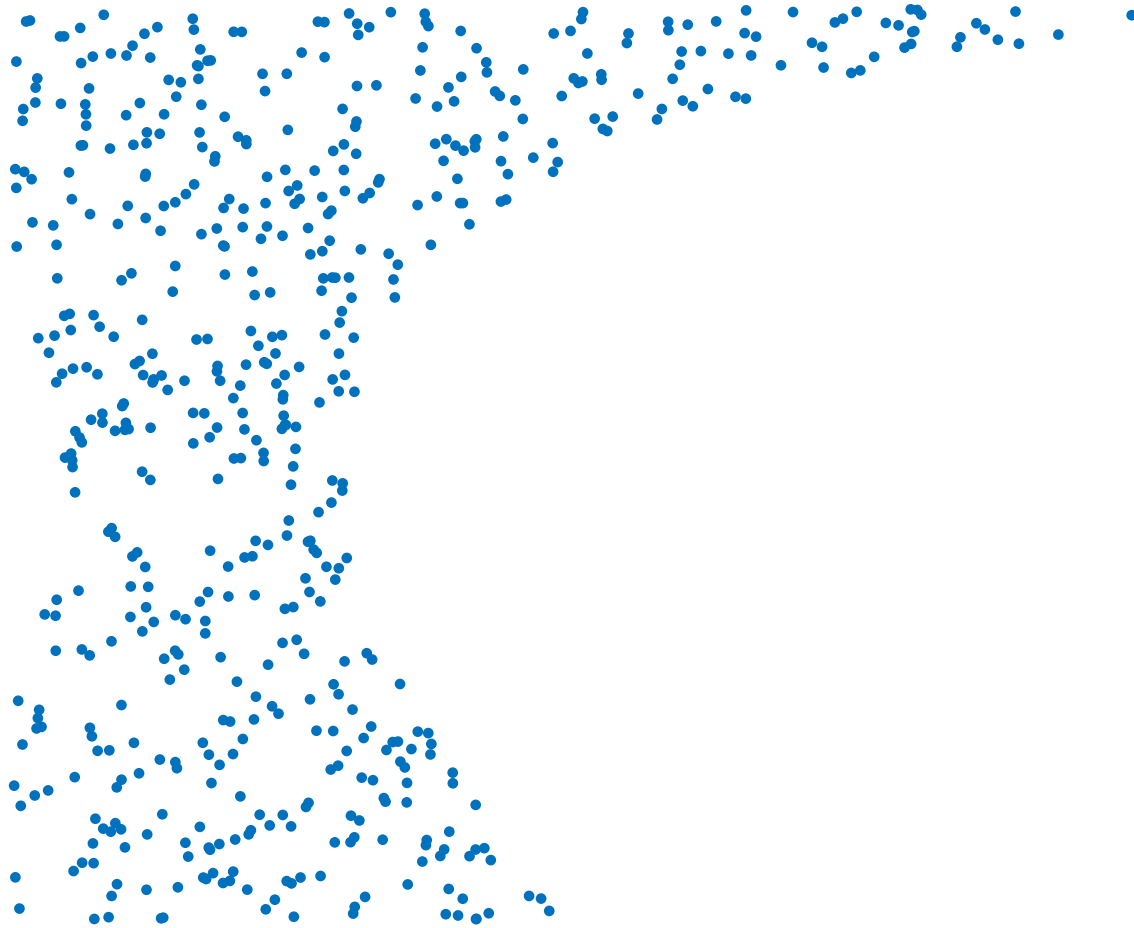
Alpha Shapes

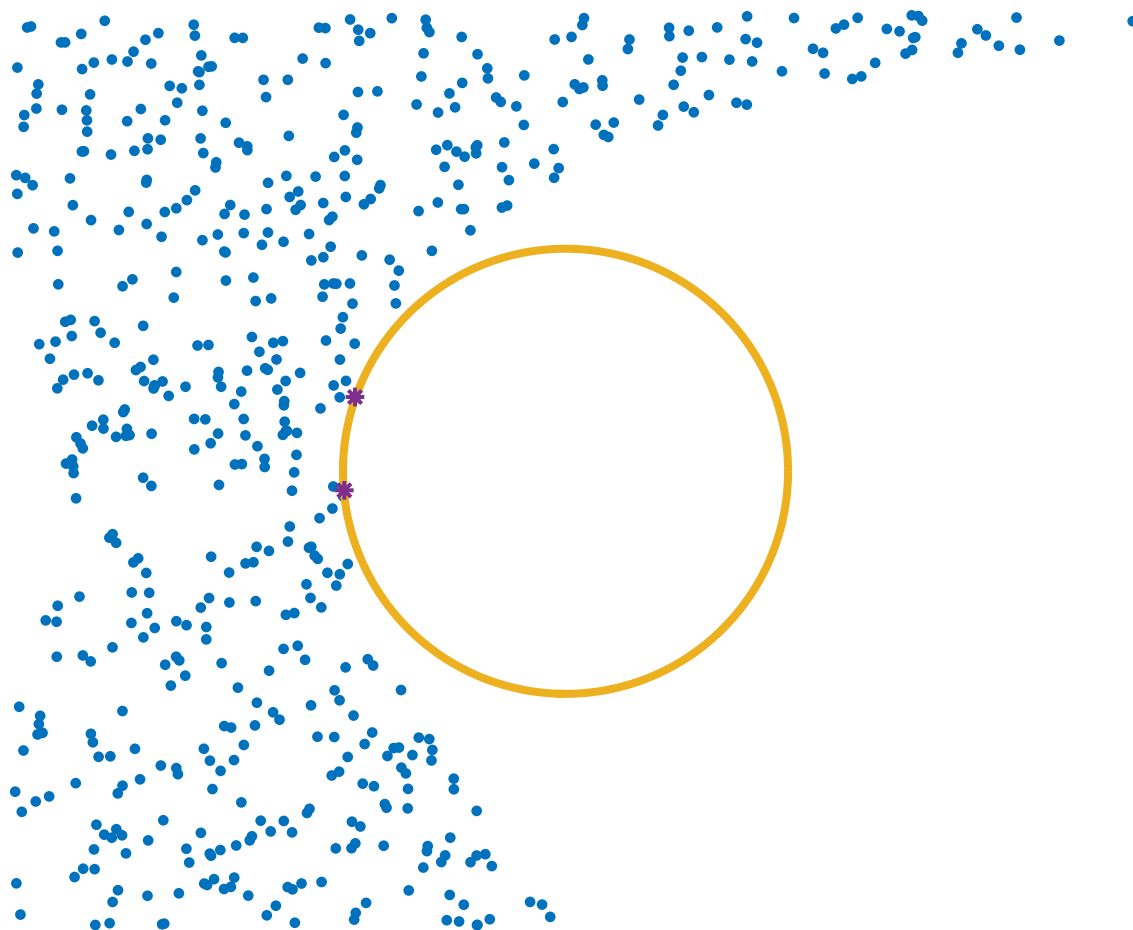
Here's a convex hull:

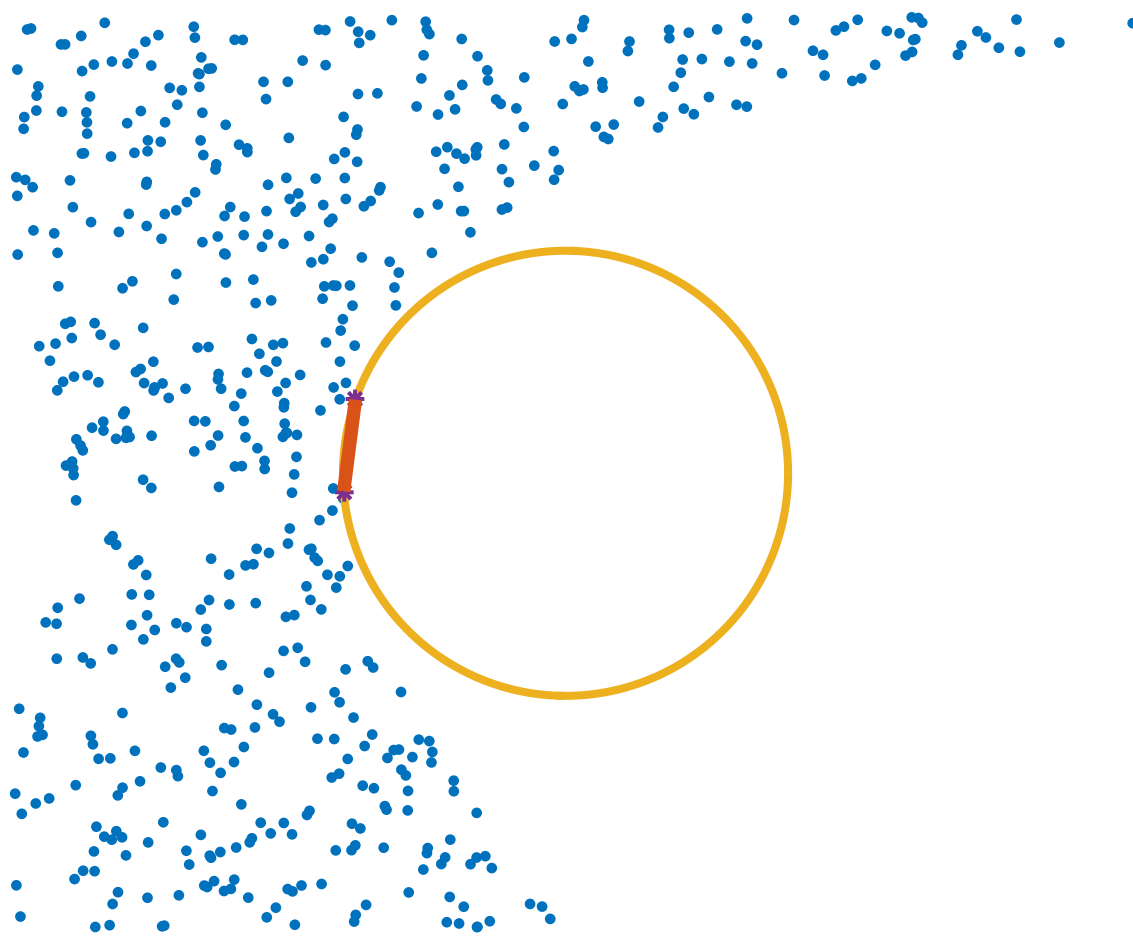


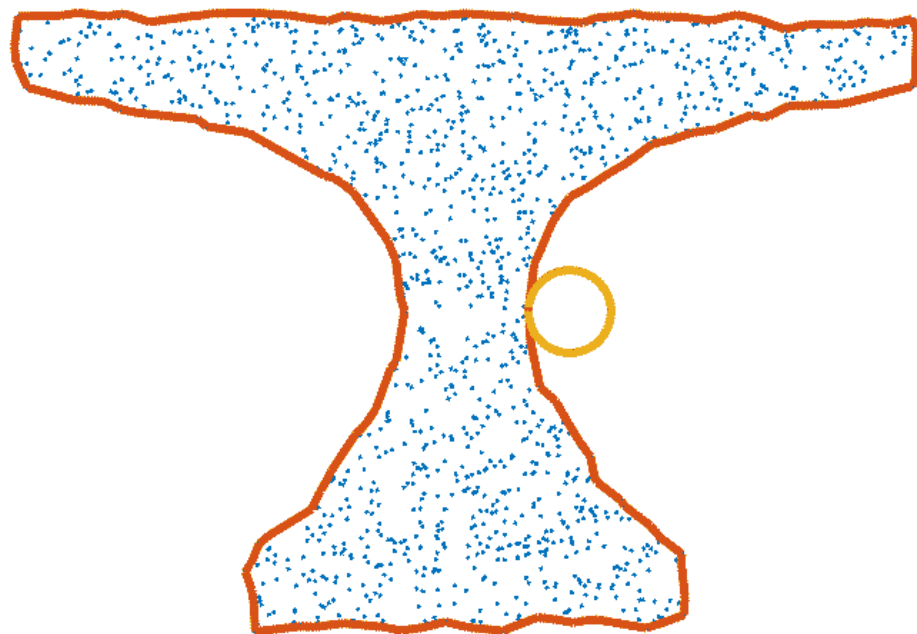


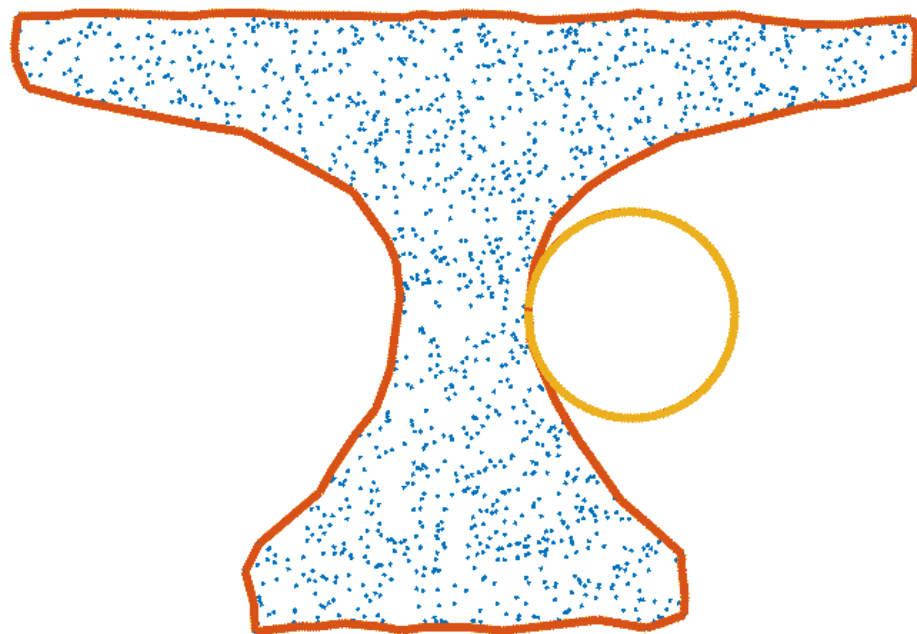


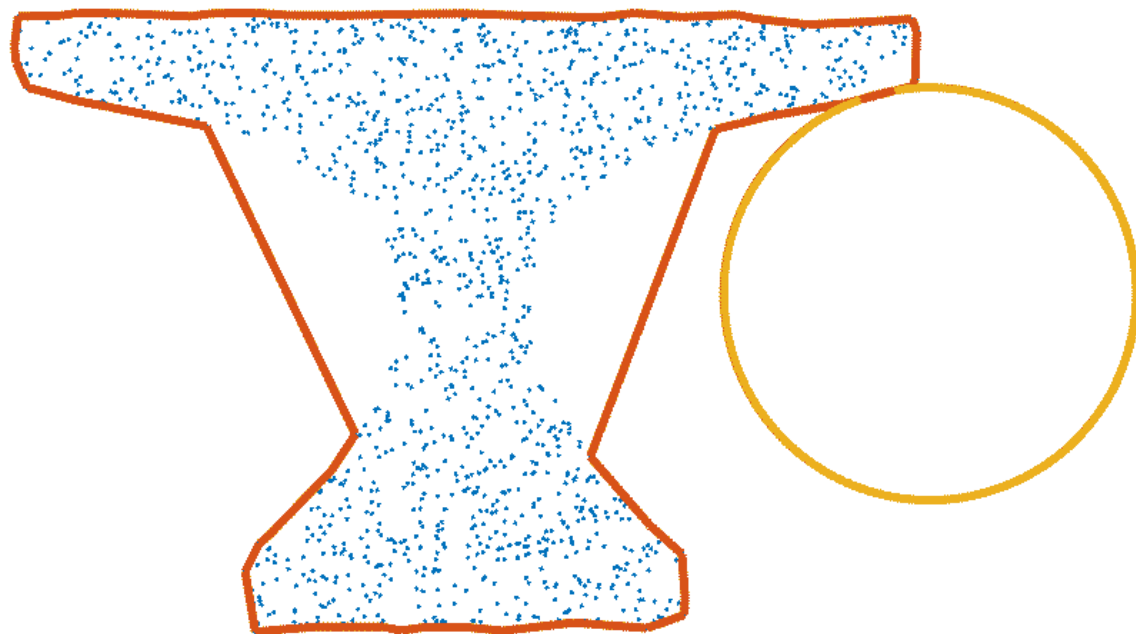


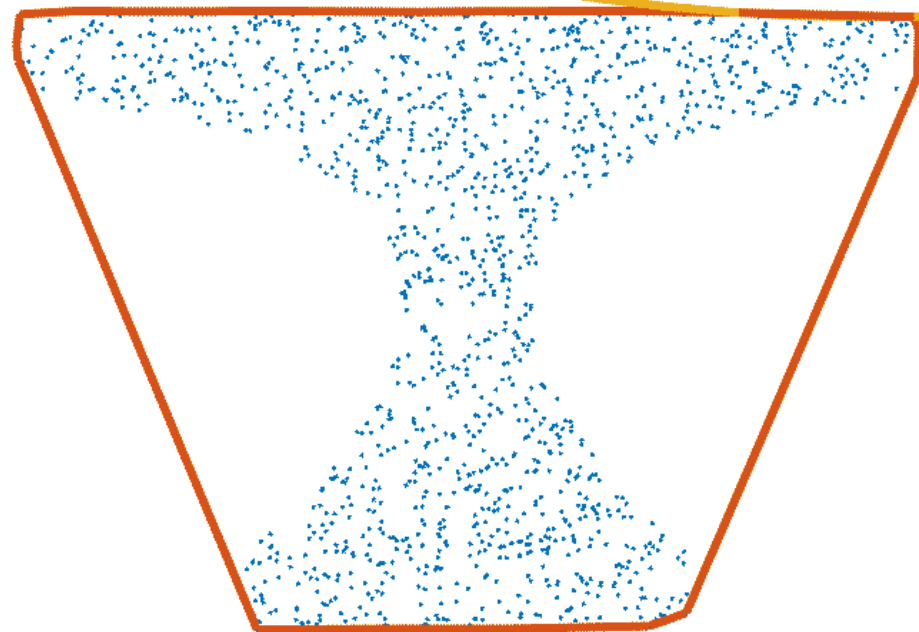












Command Window

```
>> a = alphaShape(x,y,20)
```

```
a =
```

alphaShape with properties:

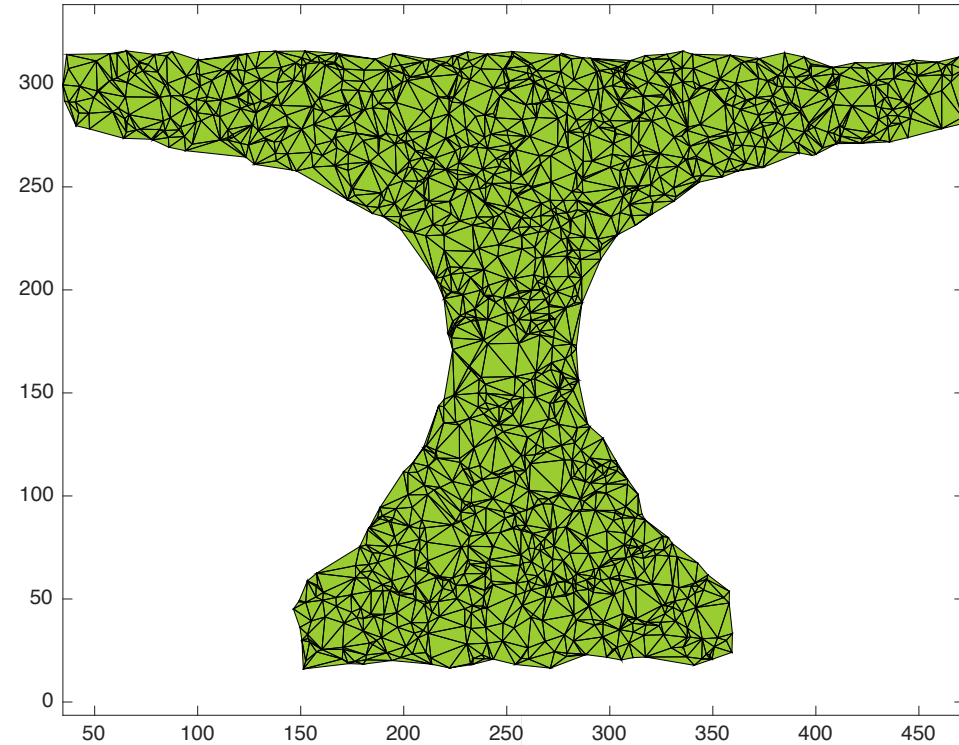
Points: [1411x2 double]

Alpha: 20

HoleThreshold: 0

RegionThreshold: 0

```
>> plot(a)
```



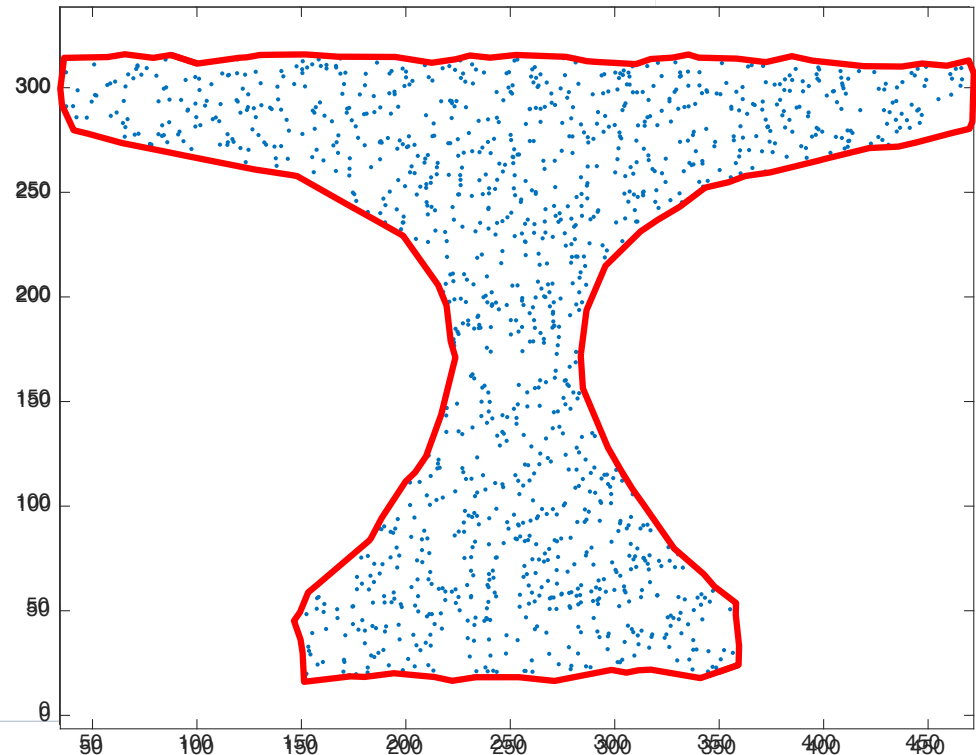
Alpha Shape-Based Geometrical Computations

alphaSpectrum	perimeter
criticalAlpha	area
numRegions	surfaceArea
inShape	volume
alphaTriangulation	nearestNeighbor
boundaryFacets	

Command Window

```
>> plot(x,y,'.')  
>> axis equal  
>> k = boundary(x,y);  
>> hold on  
>> plot(x(k),y(k),'r','LineWidth',3)  
>> hold off
```

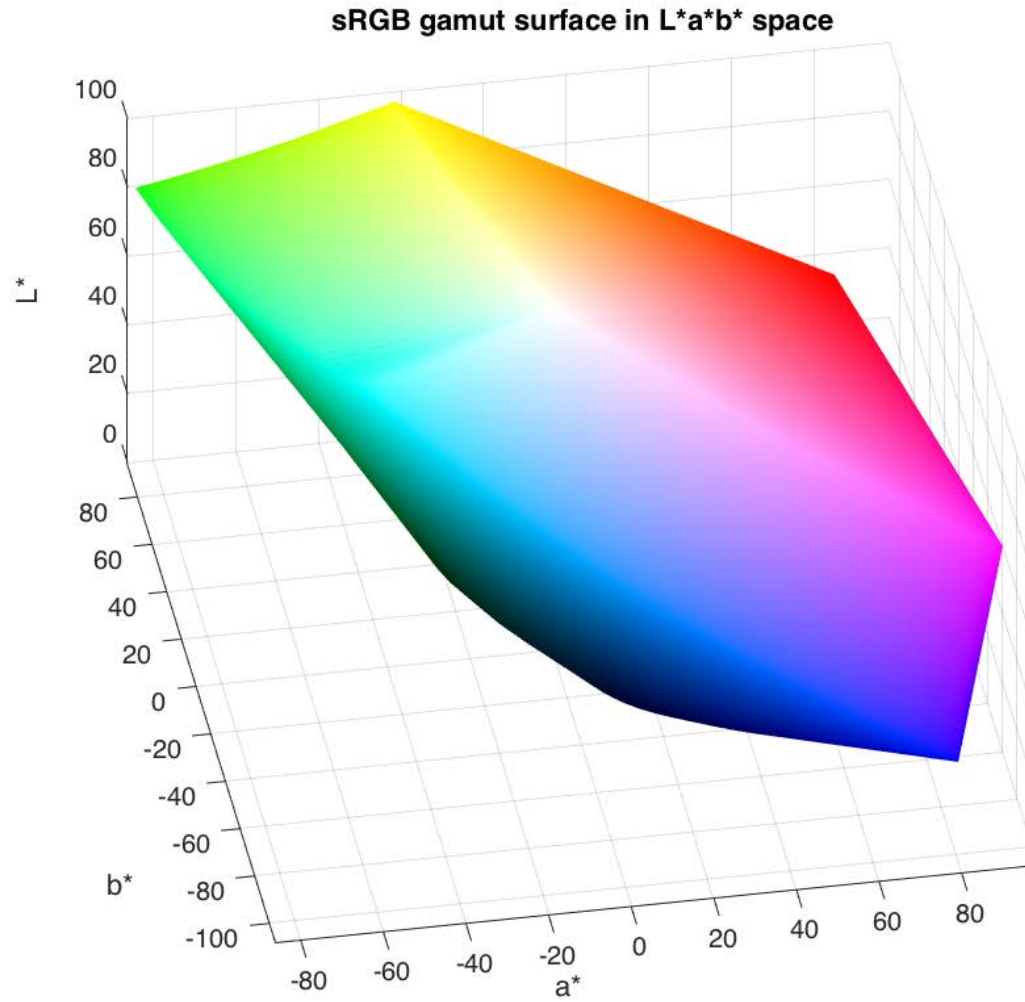
The boundary function is one application of alpha shapes.



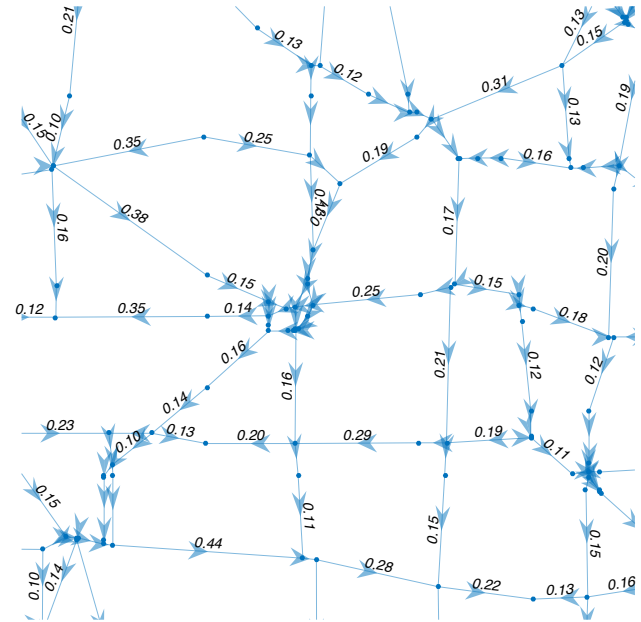
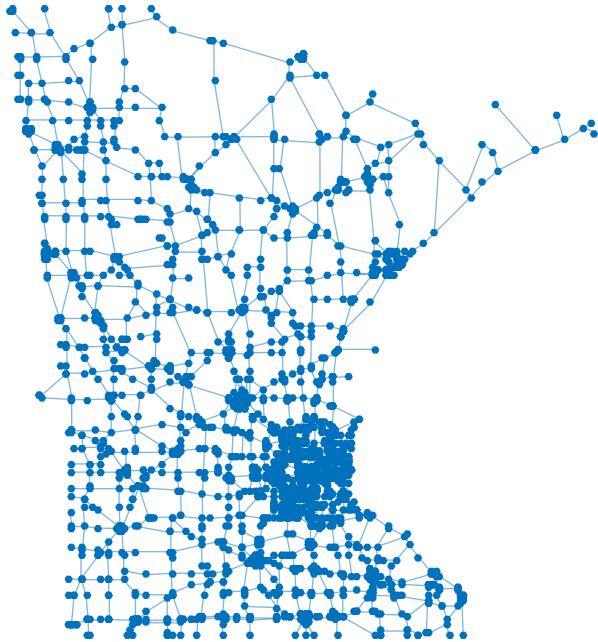
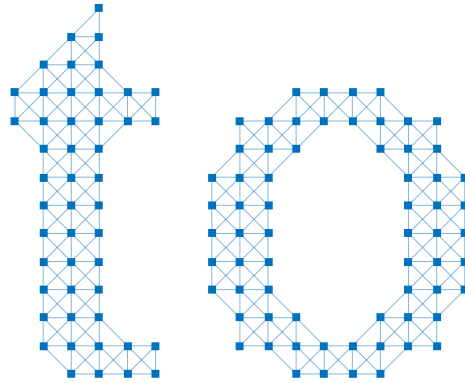
Command Window

```
>> [r,g,b] = meshgrid(linspace(0,1,50));  
>> rgb = [r(:), g(:), b(:)];  
>> lab = rgb2lab(rgb);  
  
>> a = lab(:,2);  
>> b = lab(:,3);  
>> L = lab(:,1);  
>> k = boundary(a,b,L);  
  
>> trisurf(k,a,b,L,'FaceColor','interp',...  
           'FaceVertexCData',rgb,'EdgeColor','none')  
>> xlabel('a*')  
>> ylabel('b*')  
>> zlabel('L*')  
>> axis([-110 110 -110 110 0 100])  
>> view(-10,35)  
>> axis equal
```

The boundary function
works in 3-D, too.



Graphs



Command Window

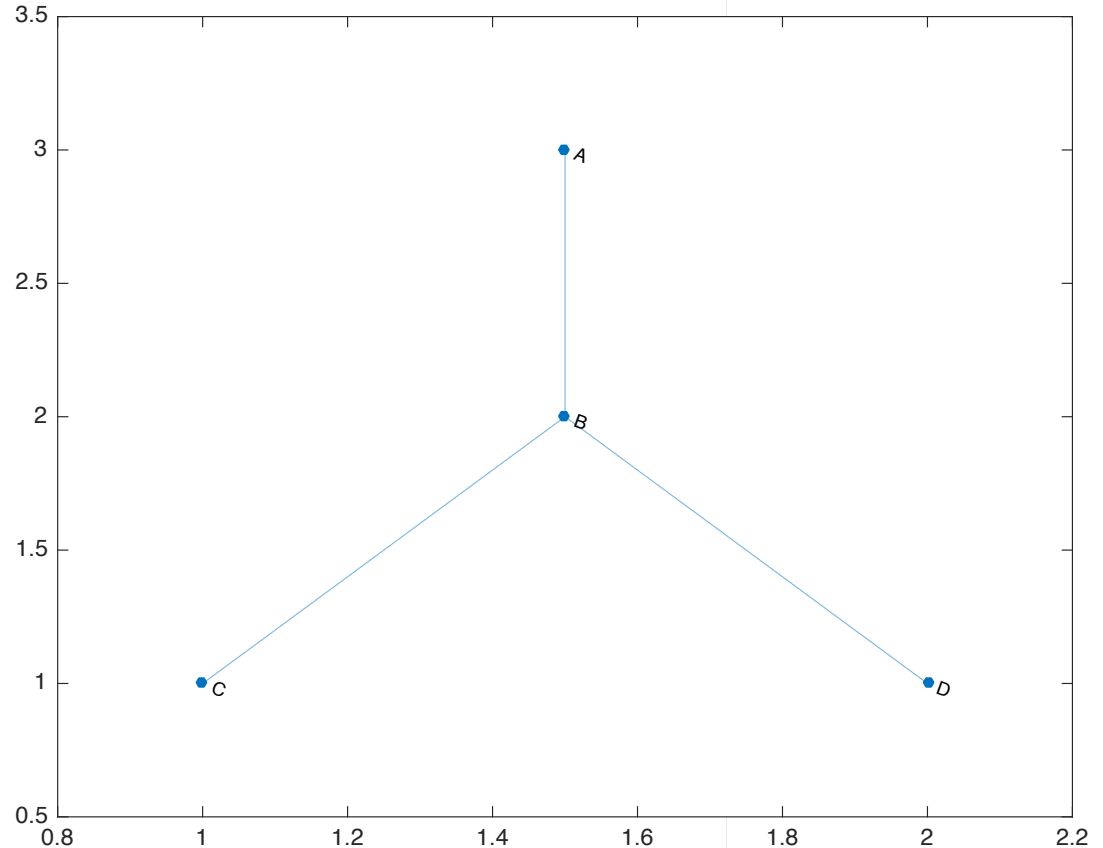
```
>> G = graph({'A', 'B', 'B'}, {'B', 'C', 'D'})
```

G = [graph](#) with properties:

Edges: [3x1 table]

Nodes: [4x1 table]

```
>> plot(G)
```



Command Window

```
>> s = [1 1 2 2 3 3 4 4 5 5];  
>> t = [2 5 3 4 4 5 3 1 1 6];  
>> names = {'alpha', 'beta', 'gamma', ...  
            'delta', 'epsilon', 'zeta'};  
>> weight = randi(100, size(s));  
>> D = digraph(s, t, weight, names)
```

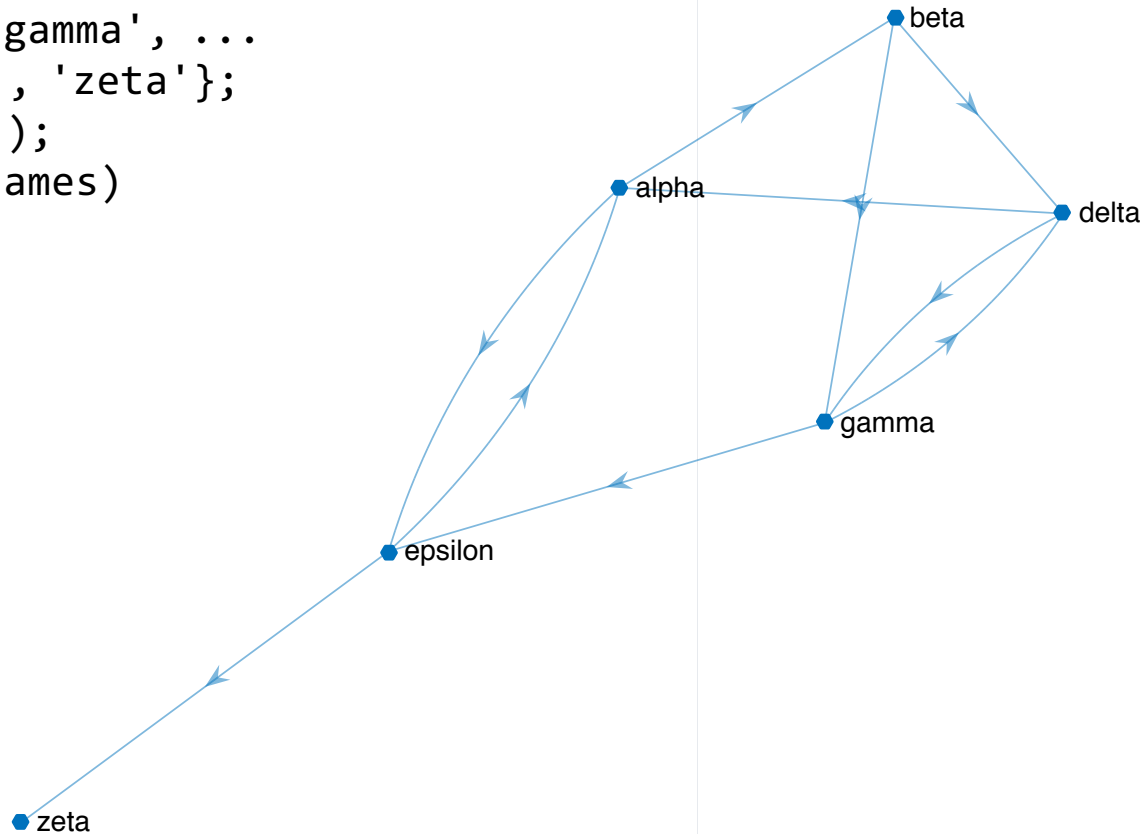
D =

[digraph](#) with properties:

Edges: [10x2 table]

Nodes: [6x1 table]

```
>> plot(D)  
>> axis equal
```



Command Window

```
>> s = [1 1 2 2 3 3 4 4 5 5];  
>> t = [2 5 3 4 4 5 3 1 1 6];  
>> names = {'alpha', 'beta', 'gamma', ...  
            'delta', 'epsilon', 'zeta'};  
>> weight = randi(100, size(s));  
>> D = digraph(s, t, weight, names)
```

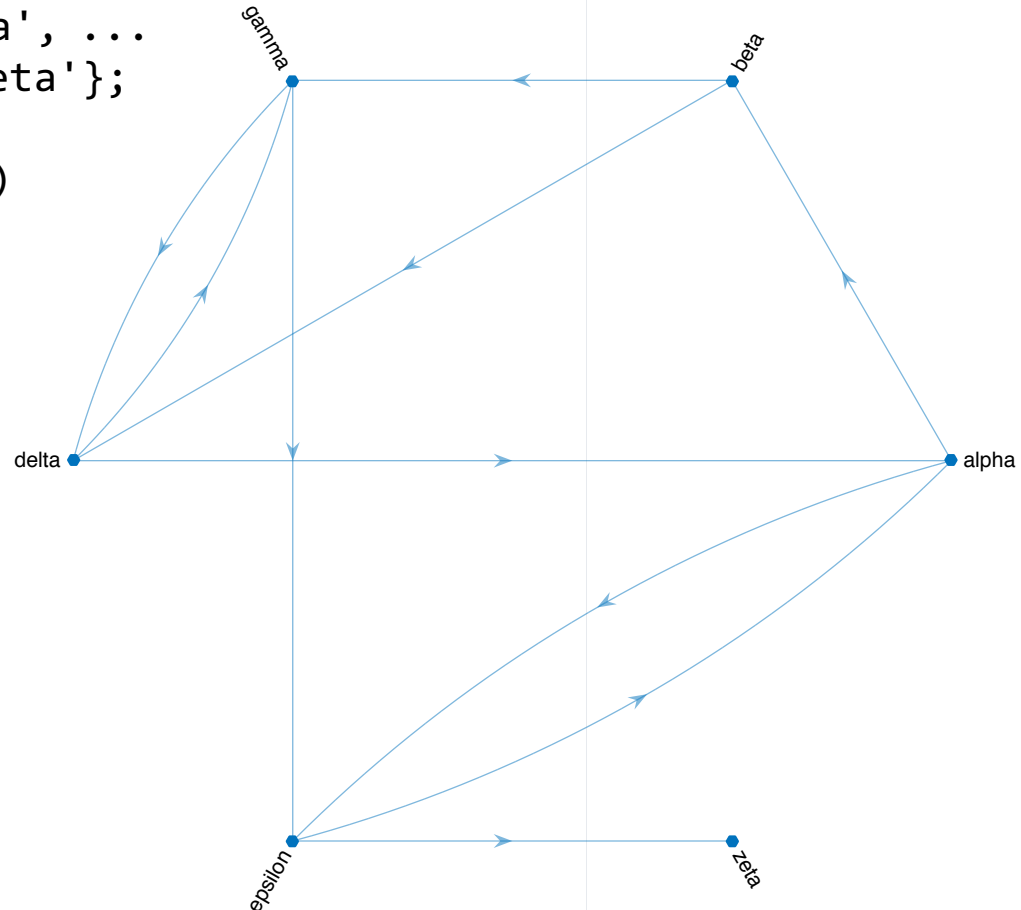
D =

[digraph](#) with properties:

Edges: [10x2 table]

Nodes: [6x1 table]

```
>> plot(D, 'Layout', 'circle')  
>> axis equal
```



Command Window

```
>> p = plot(D)
```

```
p =
```

[GraphPlot](#) with properties:

NodeColor: [0 0.4470 0.7410]

MarkerSize: 4

Marker: 'o'

EdgeColor: [0 0.4470 0.7410]

LineWidth: 0.5000

LineStyle: '-'

NodeLabel: {'alpha' 'beta' 'gamma' 'delta' 'epsilon' 'zeta'}

EdgeLabel: {}

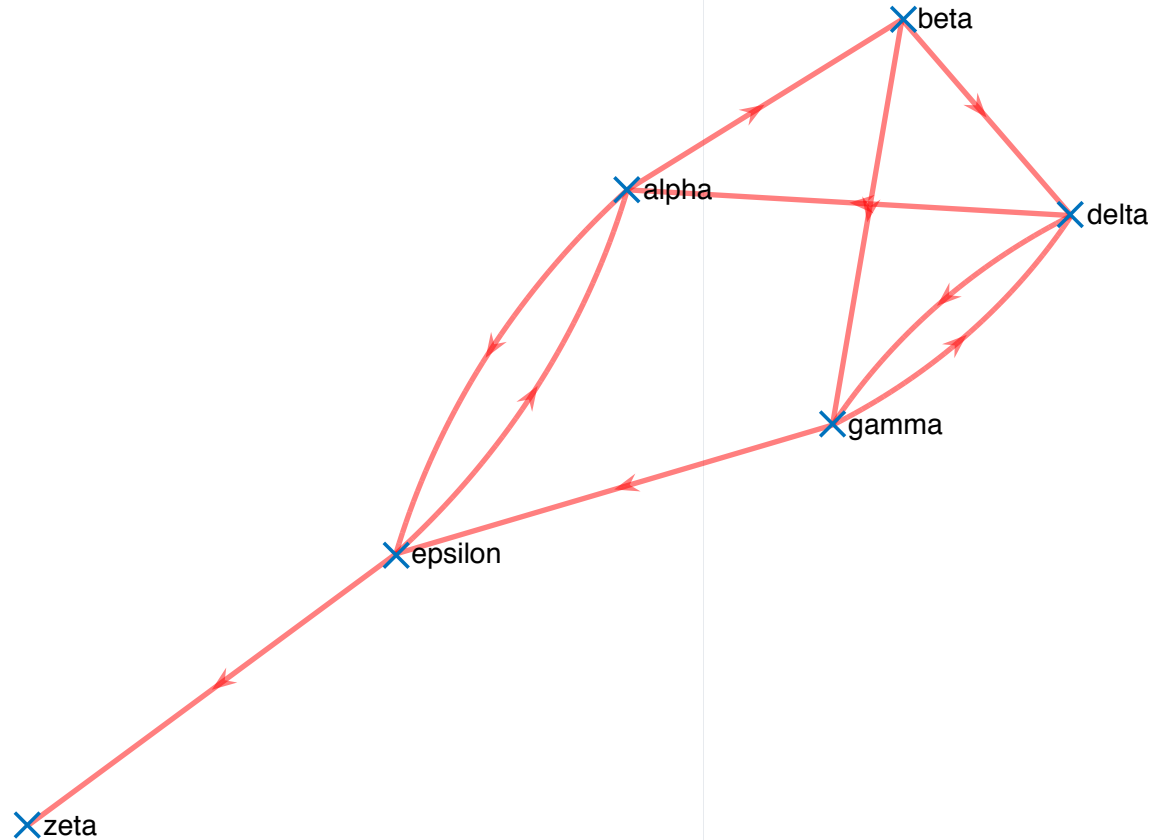
XData: [-0.0350 0.5891 0.4312 0.9742 -0.5613 -1.3981]

YData: [0.4486 0.8689 -0.1321 0.3850 -0.4499 -1.1206]

Show [all properties](#)

Command Window

```
>> p.MarkerSize = 8;  
>> p.Marker = 'x';  
>> p.EdgeColor = 'red';  
>> p.LineWidth = 1.5;
```



Command Window

```
>> path = shortestpath(D, 'alpha', 'zeta')
```

```
shortPath =
```

```
    'alpha'    'epsilon'    'zeta'
```

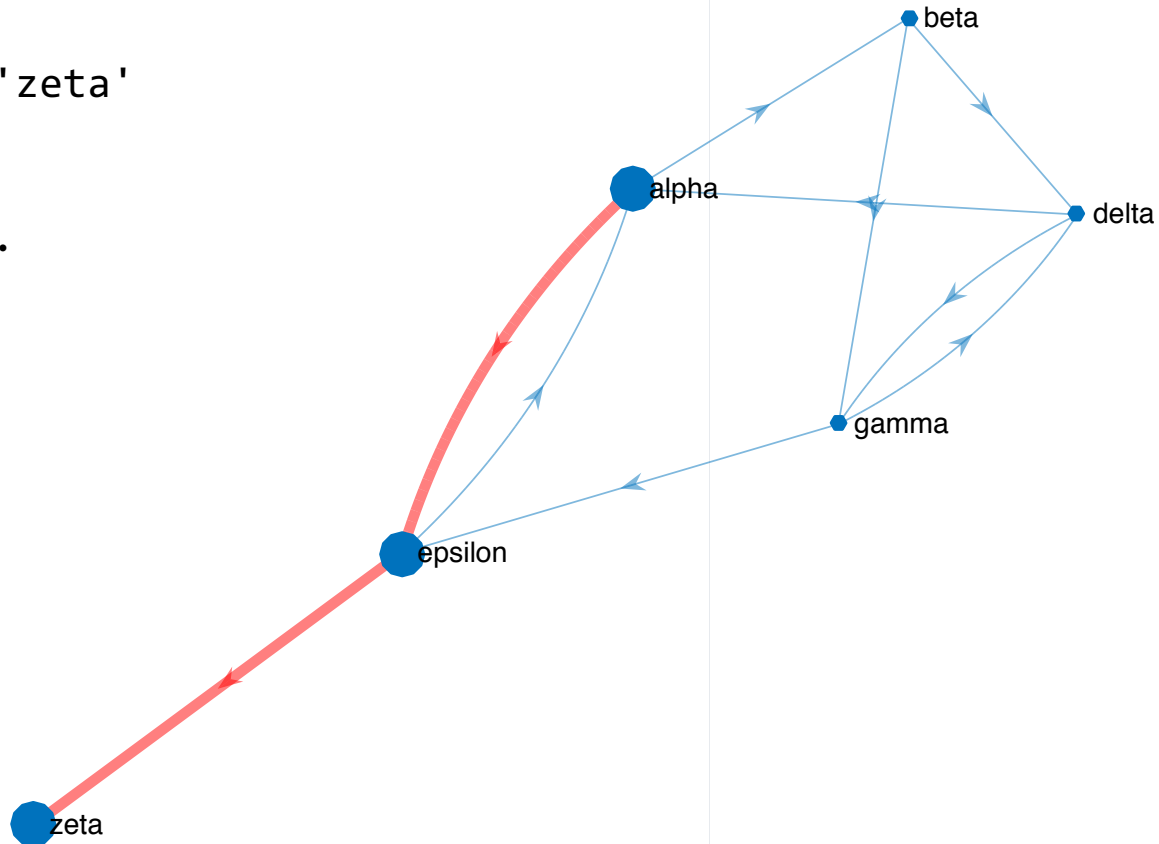
```
>> p = plot(D);
```

```
>> highlight(p, shortPath, ...
```

```
    'MarkerSize',12,...
```

```
    'EdgeColor','r',...
```

```
    'LineWidth',3)
```



Command Window

```
>> distances(D)
```

```
ans =
```

0	9	28	81	42	139
118	0	19	72	108	205
99	108	0	53	89	186
47	56	65	0	89	186
10	19	38	91	0	97
Inf	Inf	Inf	Inf	Inf	0

```
>> outdegree(D)
```

```
ans =
```

```
2  
2  
2  
2  
2  
0
```

Command Window

```
>> g8 = imageGraph([480 640],8)
```

```
g8 =
```

```
graph with properties:
```

```
Edges: [1225442x2 table]
```

```
Nodes: [307200x2 table]
```

```
>> g8.Nodes(1:4,:)
```

```
ans =
```

x	y
1	1
1	2
1	3
1	4

imageGraph and
plotImageGraph are
Steve's prototype functions.
Look for them on the
File Exchange soon.

Command Window

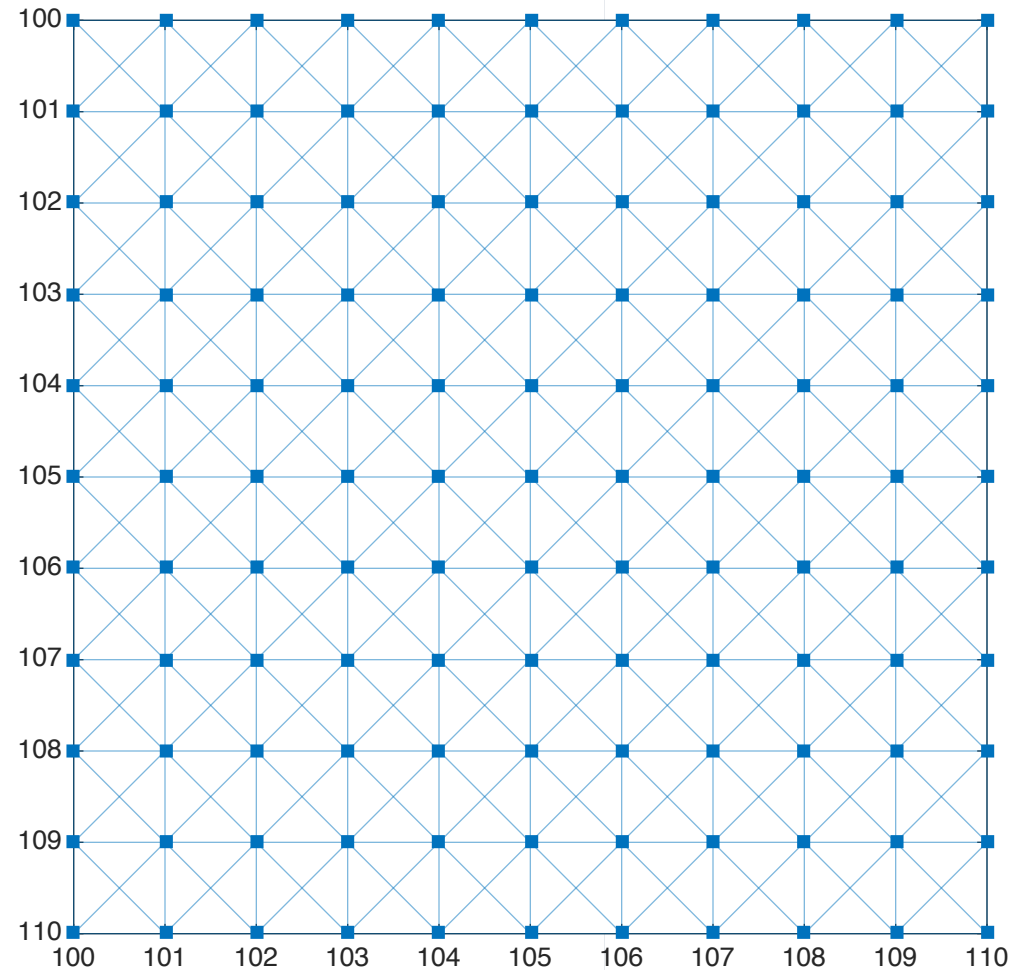
```
>> g8.Edges(1:4, :)
```

```
ans =
```

EndNodes		Weight
1	2	1
1	481	1
1	482	1.4142
2	3	1

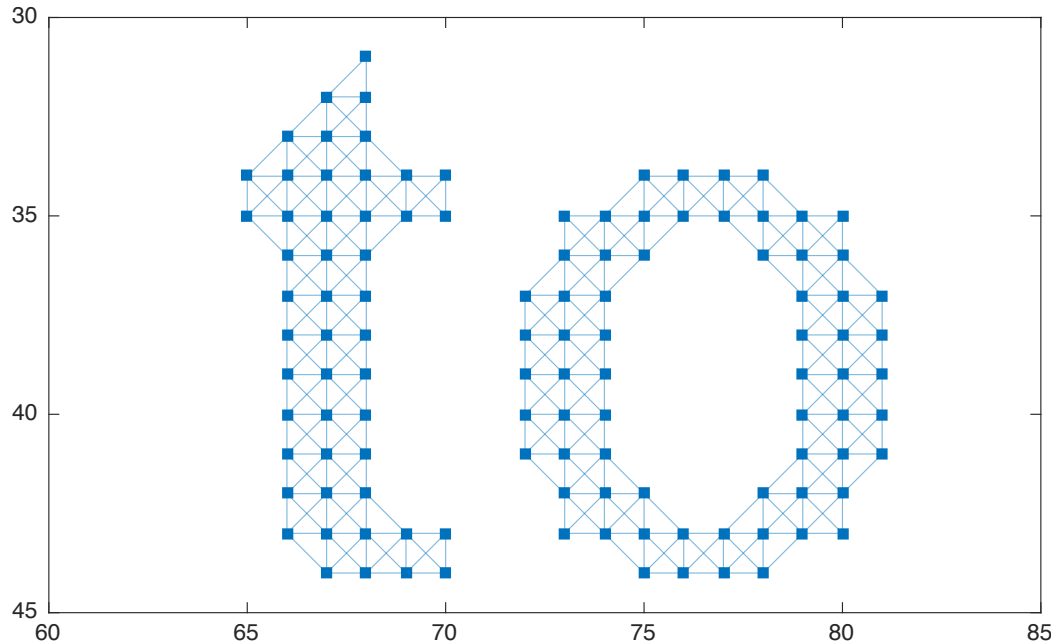
```
>> plotImageGraph(g8)
```

```
>> axis([100 110 100 110])
```



Command Window

```
>> bw = imread('text.png');  
>> g = imageGraph(size(bw),8);  
>> foreground_nodes = find(bw);  
>> g = subgraph(g,foreground_nodes);  
>> plotImageGraph(g)  
>> axis([60 85 30 45])
```

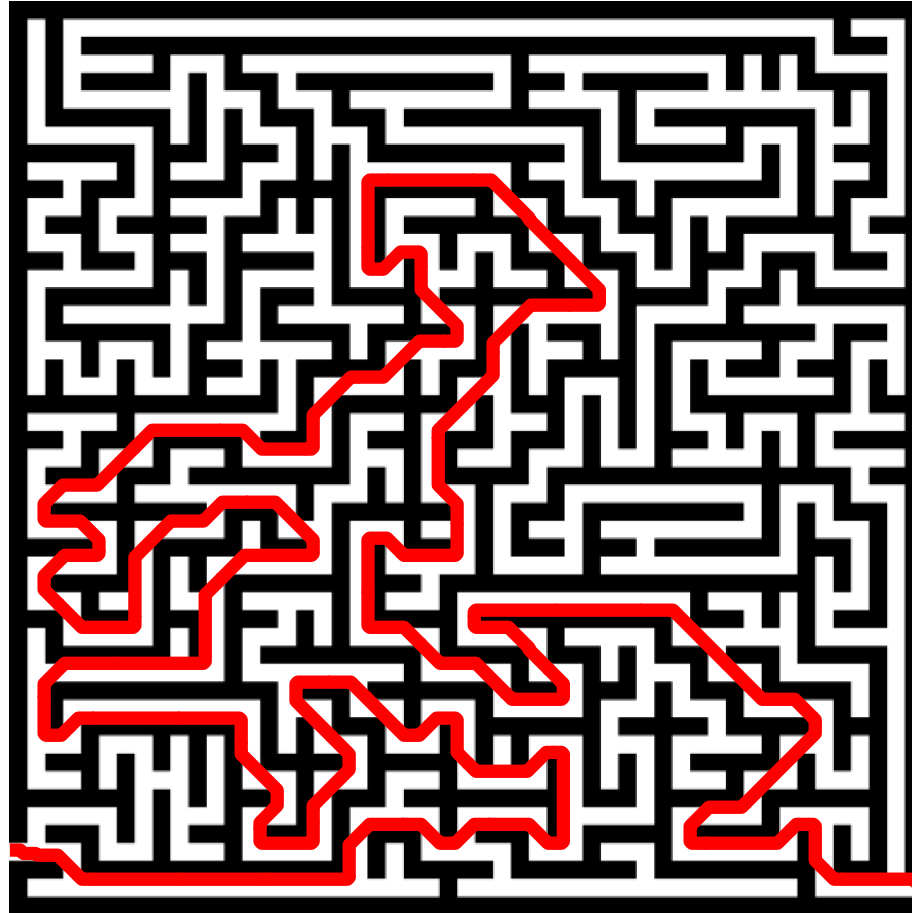


A binary image mask can be used to compute a subgraph.

The term watershed
refers to a ridge that ...

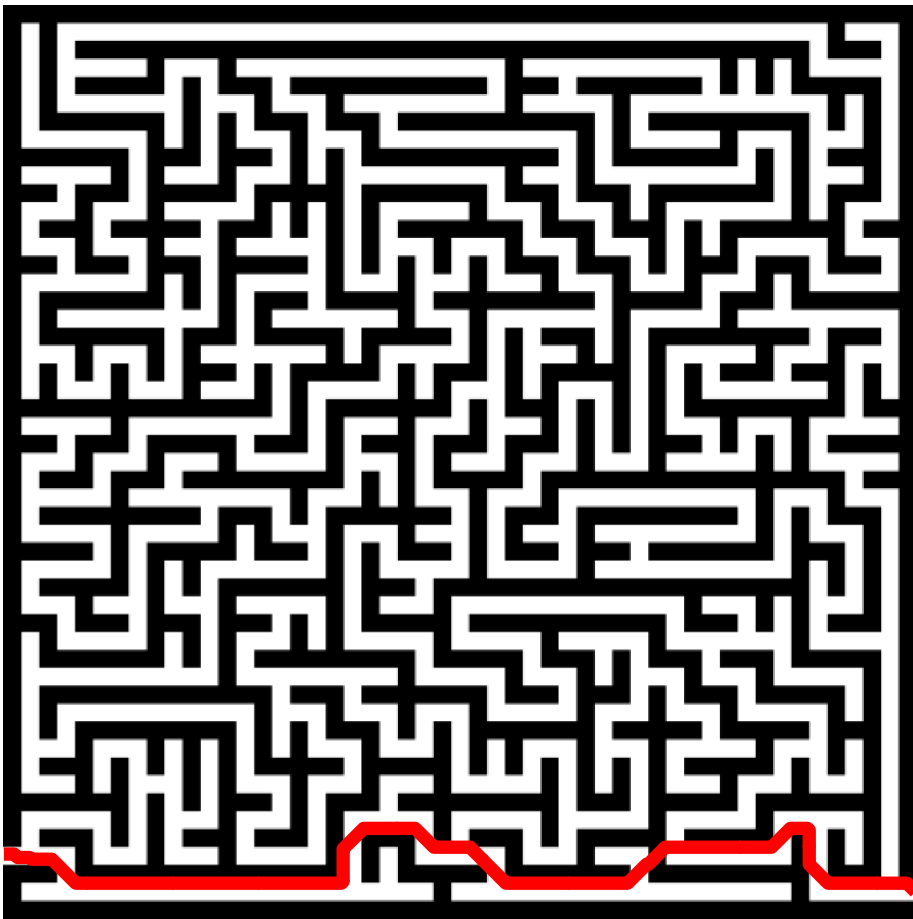
... divides areas
drained by different
river systems.

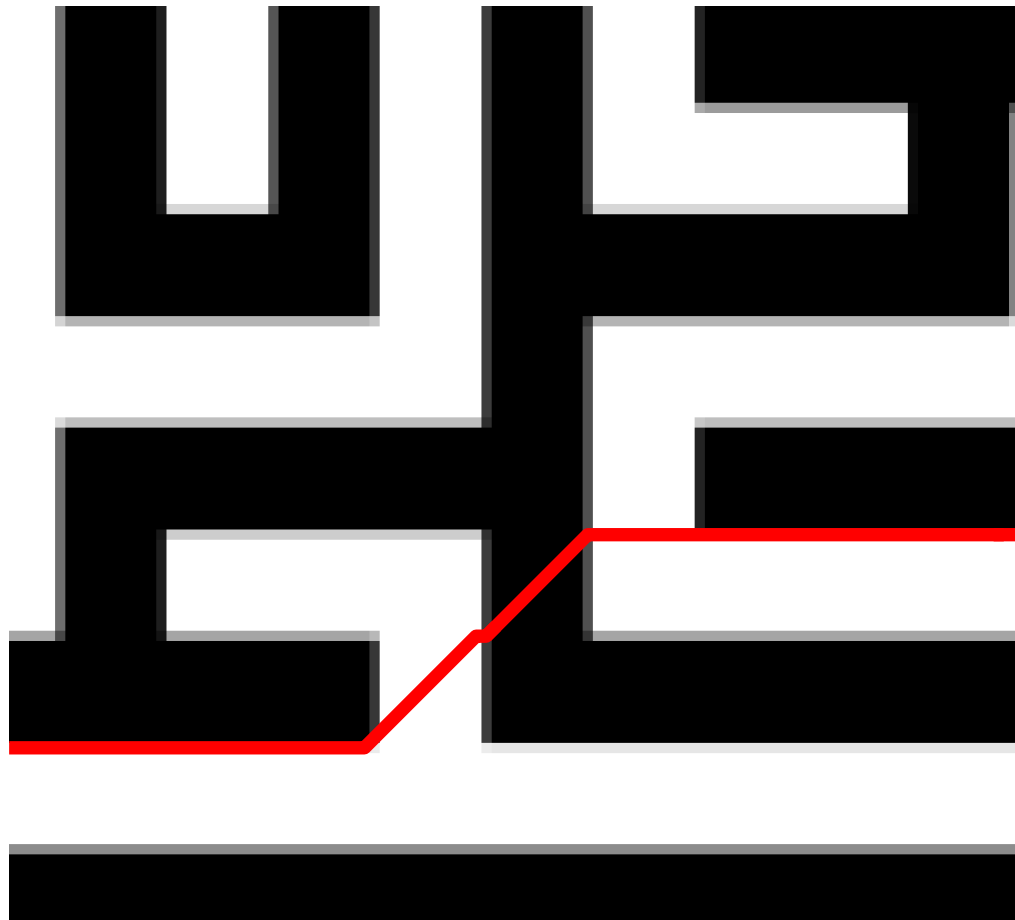
A Cheating Maze Solver



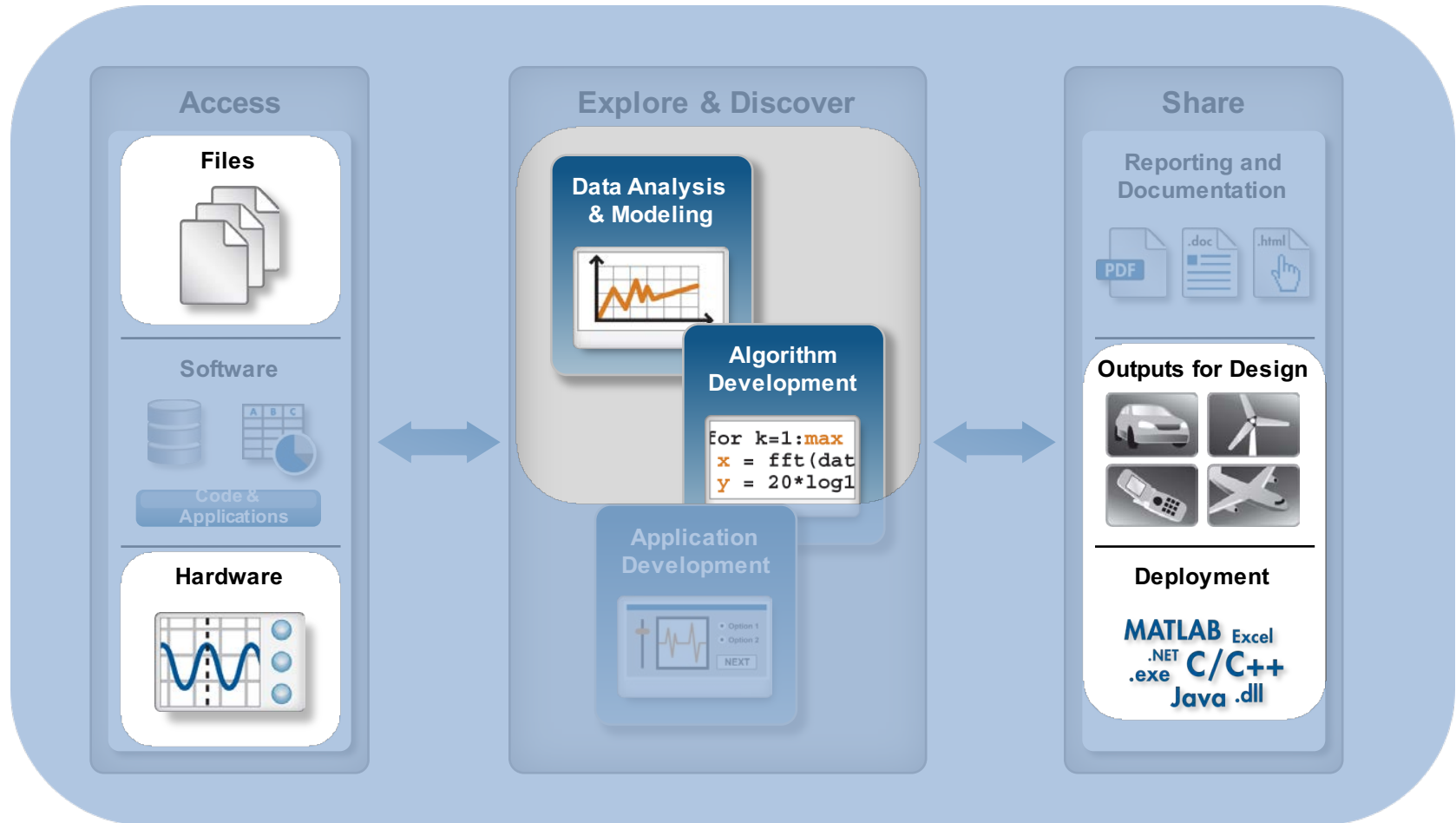
Command Window

```
>> maze = imread('maze-51x51.png');  
>> g = imageGraph(size(maze),8);  
>> tunneling_penalty = 100;  
  
>> touches_wall = any(~maze(g.Edges.EndNodes),2);  
>> g.Edges.Weight(touches_wall) = tunneling_penalty;  
  
>> p = shortestpath(g,start_node,finish_node);  
  
>> imshow(maze)  
>> hold on  
>> plot(g.Nodes.x(p),g.Nodes.y(p),'r','LineWidth',5)  
>> hold off
```





MATLAB Performance

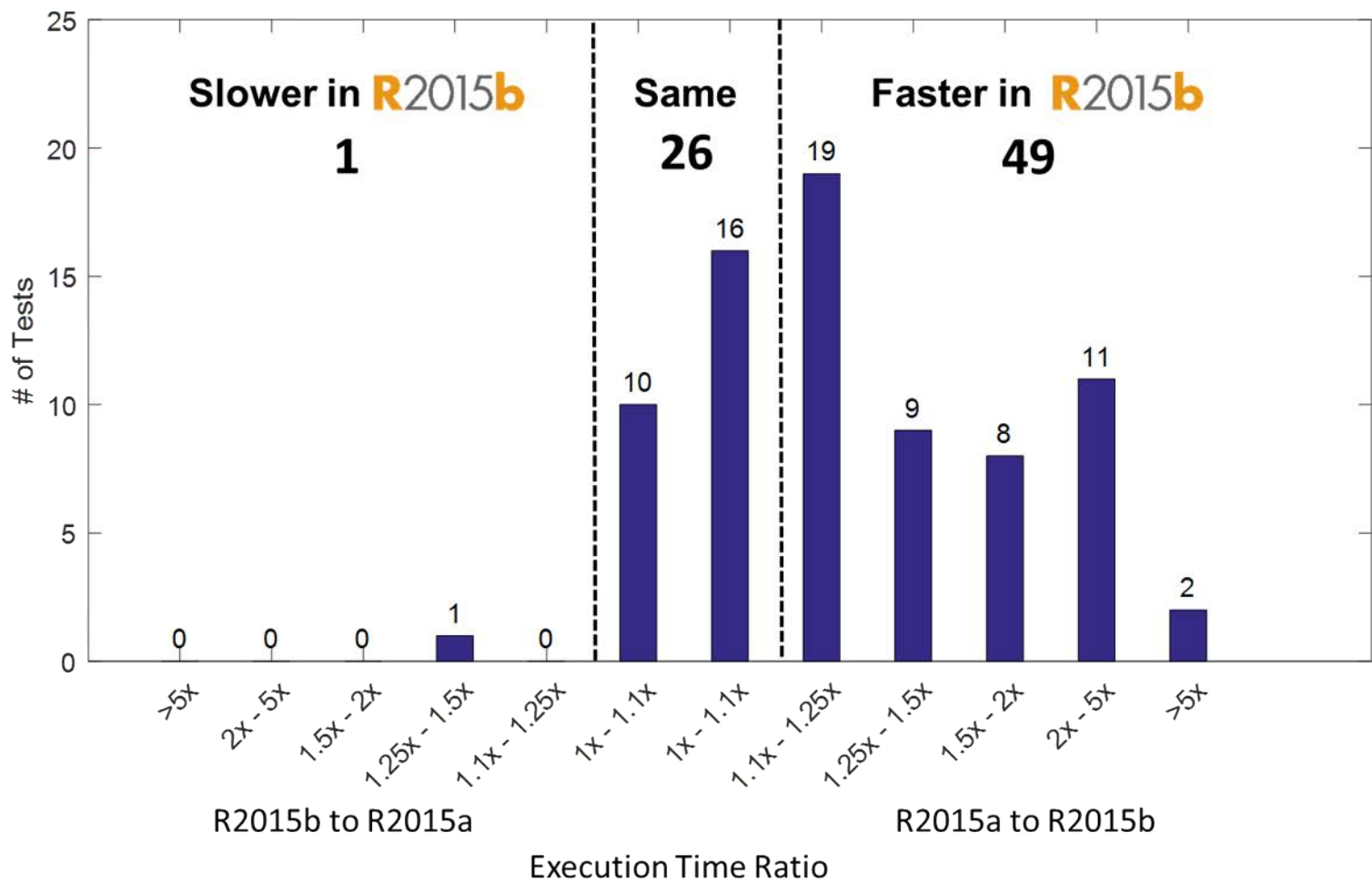


MATLAB Execution Engine

R2015b

- The old MATLAB interpreter is no more.
- All MATLAB code is compiled to machine code just-in-time (JIT)

User Application Benchmarks



Notable Speed-ups

- Function calls
- Some element-wise operations
- Some object-oriented code

Command Window

```
>> f = @() fibonacci(25);  
>> timeit(f)
```

```
ans =
```

```
0.7781
```

R2015a

0.7781

```
function x = fibonacci(n)  
    if n < 2  
        x = n;  
        return  
    else  
        x = fibonacci(n-1) + fibonacci(n-2);  
    end  
end
```


Command Window

```
>> f = @() fibonacci(25);  
>> timeit(f)
```

ans =

0.0113

R2015a 0.7781

R2015b 0.0113

Ratio: 68.9

On Steve's MacBook Pro

```
function x = fibonacci(n)  
    if n < 2  
        x = n;  
        return  
    else  
        x = fibonacci(n-1) + fibonacci(n-2);  
    end  
end
```

Faster Functions

- Dozens of MATLAB functions
- Dozens of Image Processing Toolbox functions
- More are optimized during every six-month release cycle via:
 - Algorithm changes
 - Multithreading
 - Advanced processor instructions
 - Improved memory cache efficiency

Some Faster MATLAB Functions

conv2	integer conversion functions	integer arithmetic functions
fft	sortrows	convn
histc	svd	trig functions
decimal trig functions	chol	textscan
qr	interpolation functions	rand
Bessel functions	airy	psi
permute	flip	circshift
repmat	linear algebra functions (AMD)	filter
readtable	sort	typecast
Excel I/O functions	table I/O functions	VideoReader

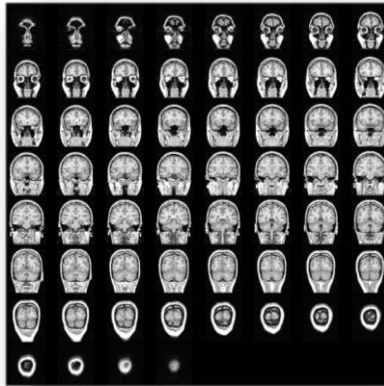
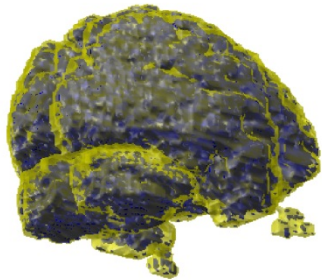
Some Faster Image Processing Toolbox Functions

edge	imdilate	imerode
imfilter	imresize	iradon
medfilt2	bwmorph	imabsdiff
imclose	imopen	dicomread
std2	blockproc (in parallel clusters)	imhist
rgb2gray	imlincomb	adapthisteq
histeq	imrotate	intlut
DICOM functions	Gaussian filtering	

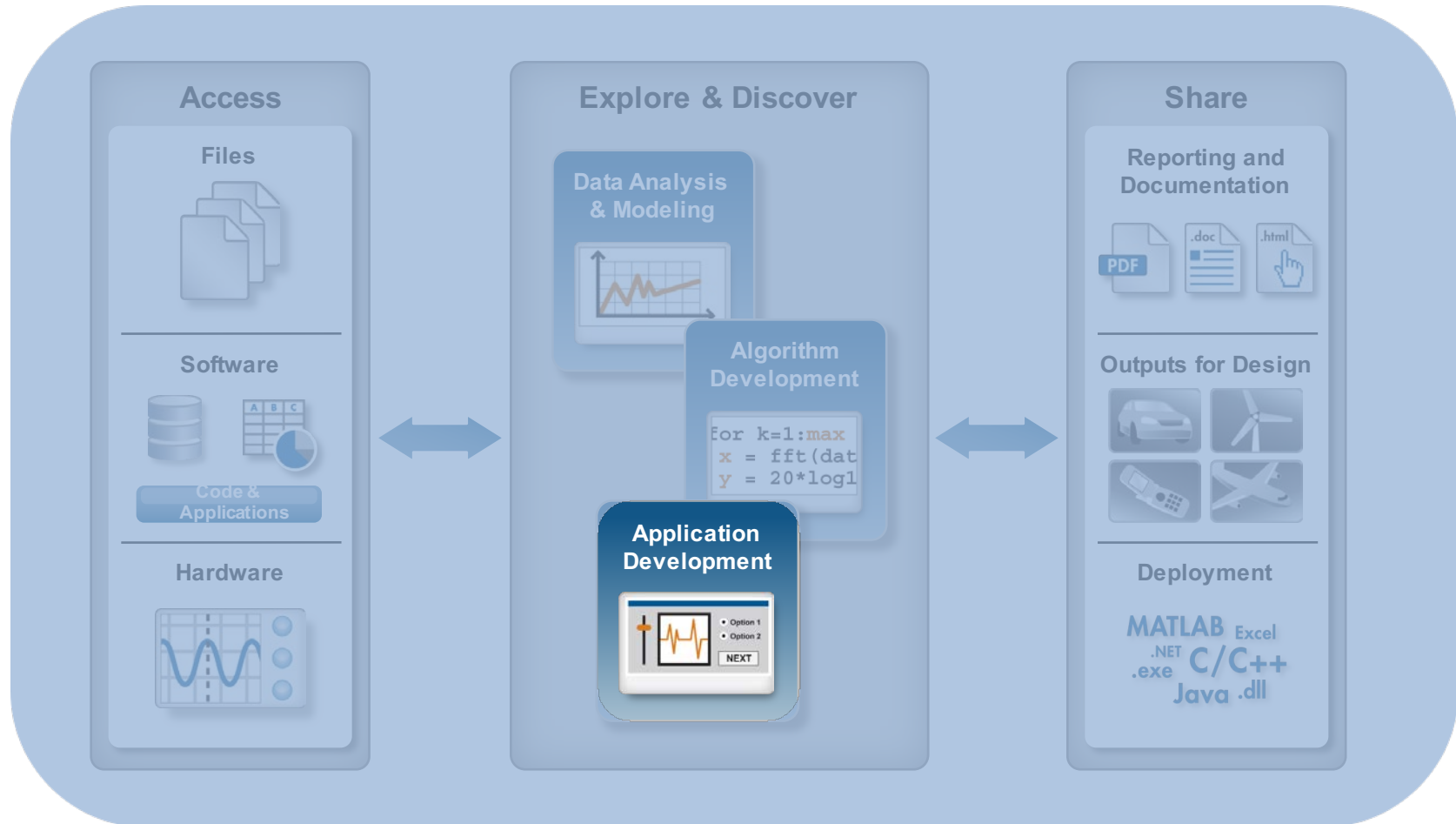
Computing on the GPU



- Requires Parallel Computing Toolbox
- And a supported GPU
 - *CUDA-enabled NVIDIA GPU with compute capability 2.0 or higher*
- 311 MATLAB functions supported
- 48 Image Processing Toolbox functions supported



Software Development



Do You Distribute Code Collections to Others?

Then you have fallen into the world of the software developer.

There are some things you need:

- Version control
- File and folder comparison tools
- Unit testing tools
- Packaging

MATLAB R2015b

HOME PLOTS APPS SHORTCUTS EDITOR PUBLISH VIEW

Save Section Section with Title Bold Italic Monospaced Hyperlink Inline LaTeX Bulleted List Numbered List Image Preformatted Text Code Display LaTeX Publish

FILE INSERT SECTION INSERT INLINE MARKUP INSERT BLOCK MARKUP PUBLISH

Users > steve > Projects > dipum > dipum_toolbox

Current Folder

Name	Git
frdescp.m	
fuzzyedgesys.mat	
fuzzyfilt.m	
fuzzysysfcn.m	
fwcompare.m	
geotrans.m	
gmean.m	
gscale.m	
histroi.m	
hpfilt.m	
hsi2rgb.m	
huff2mat.m	
huffman.m	
i2percentile.m	
ice.fig	
ice.m	
ice.mat	
ice_stand_alone.m	
ifrdescp.m	
ifwcompare.m	
im2jpeg.m	
im2jpeg2k.m	
im2minperpoly.m	
imnoise2.m	
imnoise3.m	
implfcns.m	
imread.m	

geotrans.m (Function)

Editor - /Users/steve/Projects/dipum/dipum_toolbox/geotran...

```

1 function tform = geotrans(varargin)
2 %GEOTRANS Make affine and projective geometric transformations
3 % TFORM = GEOTRANS(TYPE,P1,P2,...) makes a geometric
4 % transformation with the specified type and parameters.
5
6 % Valid values for TYPE and P1, P2, ..., are:
7
8 % 'scale' Scale. If only P1 is provided, it is the scale
9 % factor in both directions. If P1 and P2 are
10 % provided, then P1 is the horizontal scale fact
11 % P2 is the vertical scale factor.
12
13 % 'rotate' Rotation. P1 is the rotation angle, measured i
14 % degrees counterclockwise from the positive
15 % horizontal axis.
16
17 % 'translate' Translation. P1 is the horizontal translation

```

Workspace

Name	Value
a	125000x1 double
A	2642x2642 sparse double
ans	0
b	125000x1 double
bw	256x256 logical
cc	1x4773 double
cheating_path	1x2846 double
conn	[0,0,0;1,1,1;0,0,0]
D	1x1 digraph
f	@()fibonacci(25)
finish_node	284074
finish_x	533
finish_y	518
foreground_nodes	4773x1 double
g	50x50x50 double
G	1x1 graph

Command Window

```

>> |

```

Command History

```

plot(s1.x,s1.y, '.')
axis equal
hold on
plot(s1.x(k),s1.y(k), 'r', 'LineWidth',3)
shg
f = @() fibonacci(25);
timeit(f)
gpuDeviceCount
clc

```


MATLAB R2015b

HOME PLOTS APPS SHORTCUTS EDITOR PUBLISH VIEW

Save Section Section with Title Bold Italic Monospaced Hyperlink Inline LaTeX Bulleted List Numbered List Image Preformatted Text Code Display LaTeX Publish

FILE INSERT SECTION INSERT INLINE MARKUP INSERT BLOCK MARKUP PUBLISH

Users > steve > Projects > dipum > dipum_toolbox

Current Folder

Name	Git
frdescp.m	
fuzzyedgesys.mat	
fuzzyfilt.m	
fuzzysysfcn.m	
fwcompare.m	
geotrans.m	
gmean.m	
gscale.m	
histroi.m	
hpfilter.m	
hsi2rgb.m	
huff2mat.m	
huffman.m	
i2percentile.m	
ice.fig	
ice.m	
ice.mat	
ice_stand_alone.m	
ifrdescp.m	
ifwtcompare.m	
im2jpeg.m	
im2jpeg2k.m	
im2minperpoly.m	
imnoise2.m	
imnoise3.m	
implfcns.m	
imread.m	

geotrans.m (Function)

Editor - /Users/steve/Projects/dipum/dipum_toolbox/geotran...

```

1 function tform = geotrans(varargin)
2 %GEOTRANS Make affine and projective geometric transformations
3 % TFORM = GEOT
4 % transformati
5 %
6 % Valid values

```

Workspace

Name	Value
a	125000x1 double
A	2642x2642 sparse double
ans	0
b	125000x1 double
bw	256x256 logical
cc	1x4773 double
cheating_path	1x2846 double
conn	[0,0,0;1,1,1;0,0,0]
D	1x1 digraph
f	@()fibonacci(25)
finish_node	284074
finish_x	533
finish_y	518
foreground_nodes	4773x1 double
g	50x50x50 double
G	1x1 graph

Command History

```

plot(s1.x,s1.y, '.')
axis equal
hold on
plot(s1.x(k),s1.y(k), 'r', 'LineWidth',3)
shg
f = @() fibonacci(25);
timeit(f)
gpuDeviceCount
clc

```

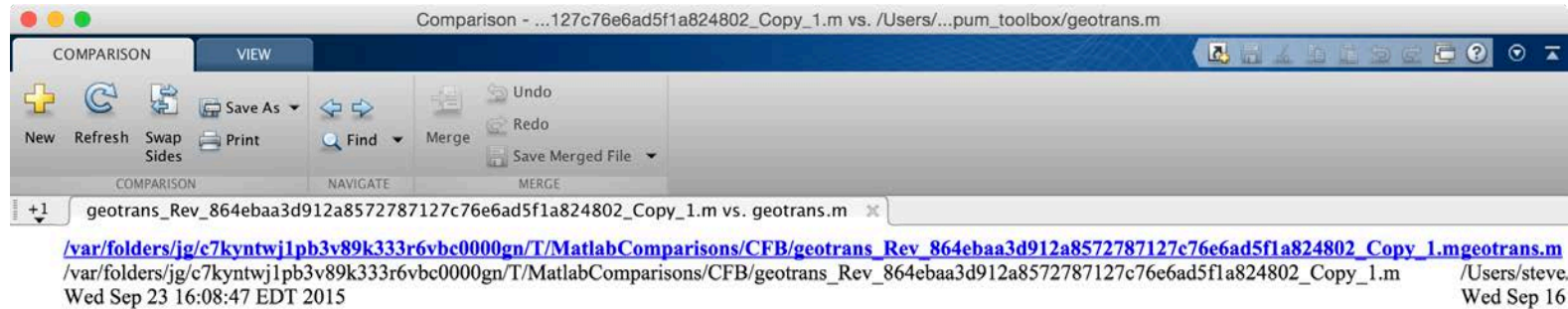
Source Control

- Open
- Show Details
- Run
- Run Script as Batch Job
- View Help
- Show in Finder
- Create Zip File
- Rename
- Delete
- Compare Selected Files/Folders
- Compare Against
- Source Control
- Cut
- Copy
- Paste
- Indicate Files Not on Path
- Check Code Generation Readiness

Manage Files...

- View Details
- Commit All to Git Repository
- Manage Branches
- Push
- Fetch
- Tag
- Refresh Git Status
- Commit Selection to Git Repository
- Revert Local Changes
- Extract Conflict Markers to File
- Show Revisions
- Compare to Ancestor
- Compare to Revision
- Revert using Git

File and Folder Comparison Tool



3 differences found. Use the toolbar buttons to navigate to them.

<pre> 42 case 'v-reflect' 43 tform = reflectVertical; 44 case 'h-shear' 45 tform = shearHorizontal; 46 case 'v-shear' 47 tform = shearVertical; 48 case 'compose' 49 tform = compose(varargin{:}); 50 otherwise 51 error('Unrecognized operation: %s', operation); 52 end </pre>	<pre> [41 unmodified lines hidden] . case 'v-reflect' . tform = reflectVertical; . case 'h-shear' x tform = shearHorizontal(varargin{2}); . case 'v-shear' x tform = shearVertical(varargin{2}); . case 'compose' x tform = compose(varargin{2:end}); . otherwise . error('Unrecognized operation: %s', operation); . end [67 unmodified lines hidden] </pre>
--	---

Number of matching lines: 116

Number of unmatched lines in left file: 3

Number of unmatched lines in right file: 3

File Revision History

File Revisions

Log for /Users/steve/Projects/dipum/dipum_toolbox/geotrans.m

Revision	...	Commit...	▲	Date	Message
864ebaa3d912a857...	...	Steve Eddi...		2015-06-15 14:4...	changes to geotrans; experimental versions of vis funct...
32e7b1c1a7c32895...	...	Steve Eddi...		2015-05-19 16:4...	Add translate option to doc. Change some of the TYPE ...
3f27965138d39713...	...	Steve Eddi...		2015-05-19 16:4...	Add geotrans and visgeotrans functions and data file u...

Author
Steve Eddins (steve@eddins.net)

Committer
Steve Eddins (steve@eddins.net)

Date
2015-05-19 16:47:41

Message
Add translate option to doc. Change some of the TYPE strings to match new doc.

Close

Toolbox Packager (produces self-installing file)

Package a Toolbox - Untitled1.prj

PACKAGER

New Project Open Project Save Project

FILE TOOLBOX FOLDER PACKAGE

Add toolbox folder + Package

Toolbox Information

Select toolbox image

Toolbox Name 1.0

Steve Eddins

Email

MathWorks

Set as default contact

Summary

Description

Unit Testing

- Verify the expected behavior of the smallest components of your code
- Automate the verification process that it can be easily (and frequently!) repeated
- Demo: writing test cases by writing functions

MATLAB Unit Testing Framework

- Supports a variety of test writing styles:
 - Scripts
 - Functions
 - Custom TestCase objects
- Large collection of validation checks
- Extensively customizable
 - test fixtures
 - parameterized tests
 - diagnostics
 - plugins

Image Processing Algorithms and Apps

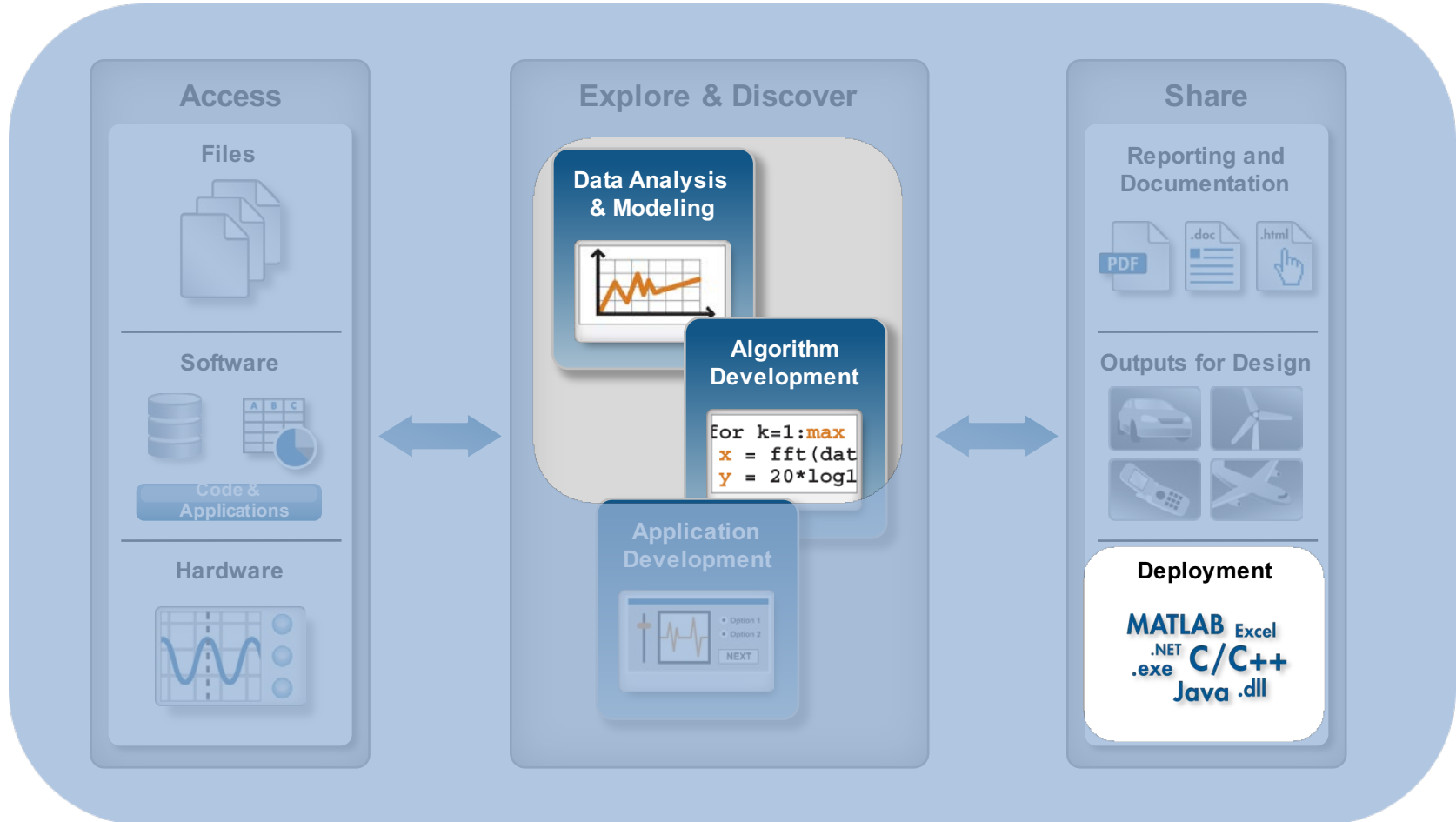


Image Registration

- Intensity-based
 - Unimodal
 - Multimodal
- Phase correlation
- Translation-only
- Nonrigid
- Visualization
 - `imshowpair`
 - `imfuse`

Image Analysis and Segmentation

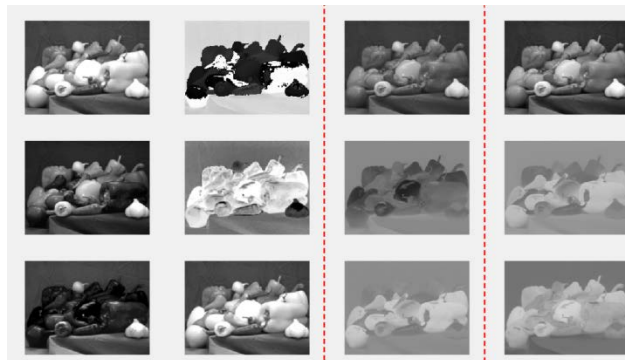
- Circle finding
- Active contours
- Fast marching segmentation
- Fast geodesic interactive segmentation

General Image Processing Operators

- Binary image convex hulls
- Geodesic distance transform
- Gradient magnitude, phase, x- and y-components
- Multilevel thresholding
- Quality metrics
- Gabor filtering
- Box filtering
- Gray-level connected components

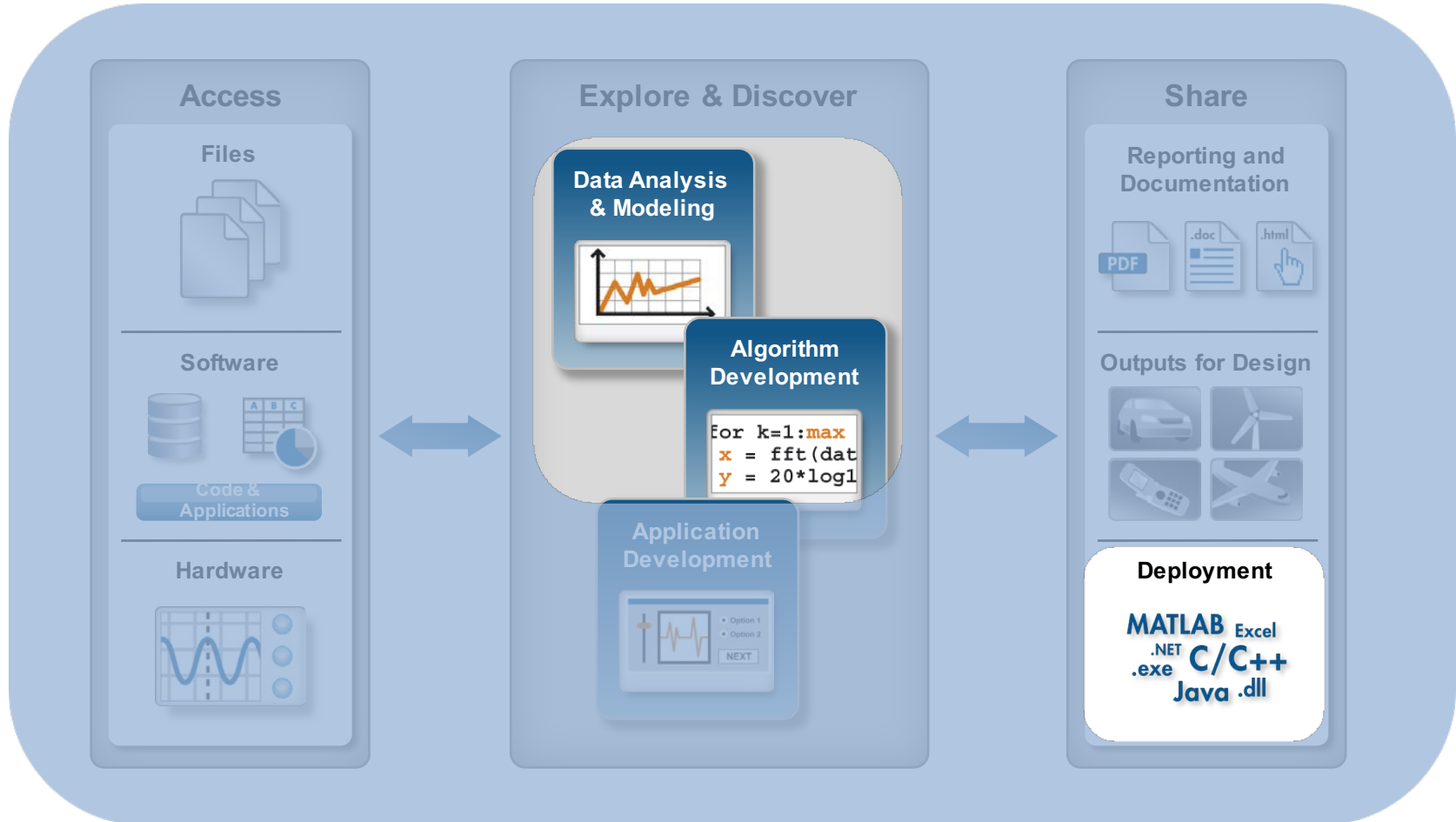
Image Processing Apps

- Color Image Thresholder
- Image Segmentation
- Image Region Analyzer
- Batch Image Processor



Color Thresholder Demo

Computer Vision Algorithms and Apps

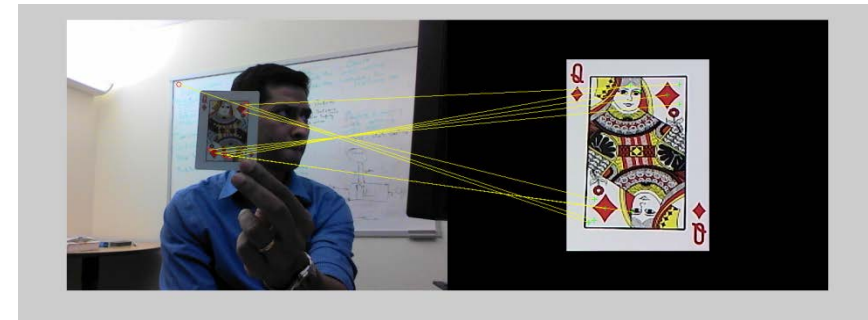
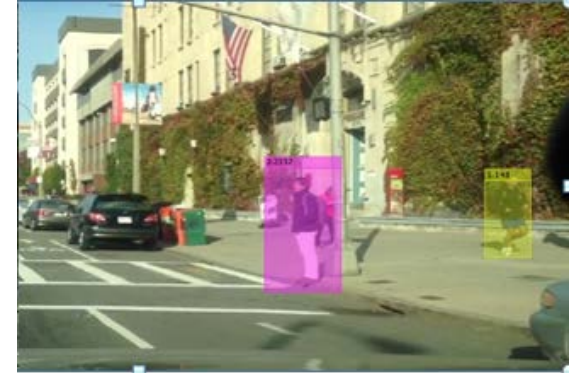


Feature Detection and Extraction

- SURF
- MSER
- BRISK
- Harris Corner
- FREAK
- HOG
- LBP
- Feature matching
- Visualizations for features, feature matching

Object Detection and Recognition

- Cascade detector (Viola-Jones)
 - Face detector
 - Upper body detector
- Cascade detector training
- HOG-based pedestrian detector
- Bag-of-features (BoF)
- Image category classification
- Image search and retrieval
- Training image labeler app
- Nonmaximal bounding box suppression

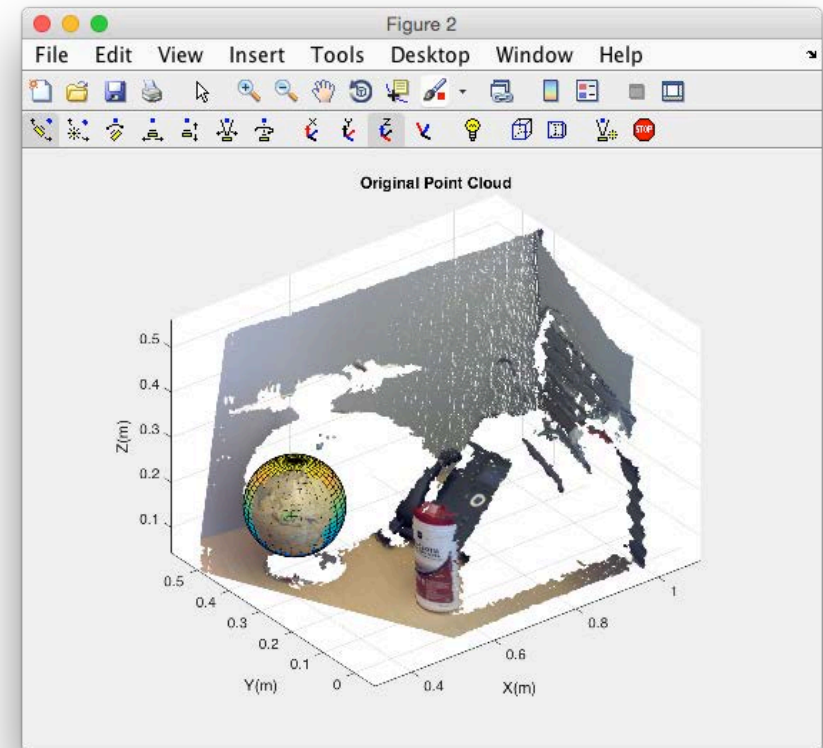


Object Tracking

- Multiobject tracking framework
 - Kalman filter
 - Hungarian algorithm for detection with tracks
- CAMShift tracker
- KLT-based point tracker
- Tracked object annotation

3-D Point Cloud Processing

- K-D tree-based neighborhood search
- Point cloud file I/O
- Registration
- Rigid transformation
- Point cloud stitching
- Downsampling
- Import point clouds from Microsoft Kinect
- Geometric shape fitting
- Streaming point cloud viewer

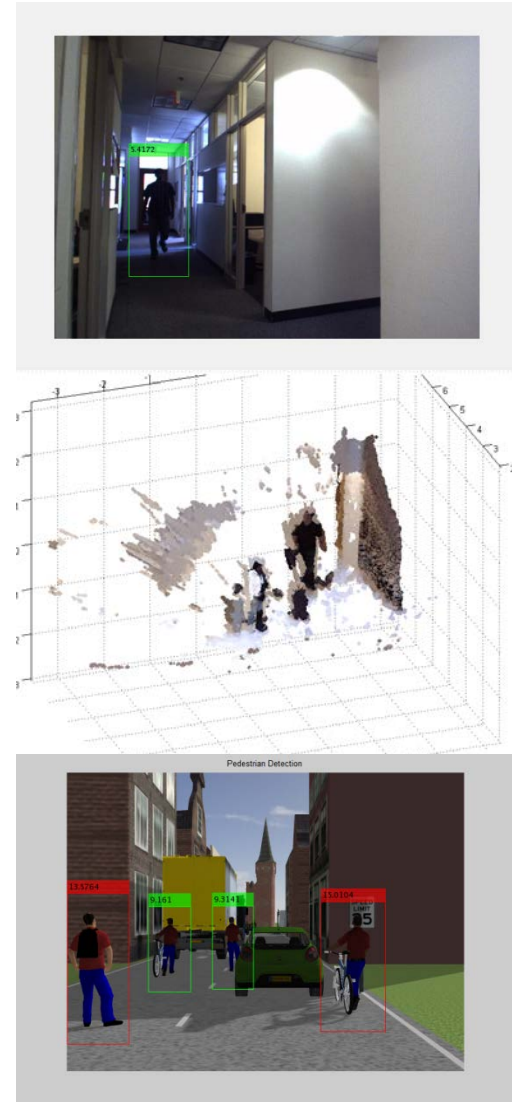


Camera Calibration

- Single-camera calibration functions and interactive app
- Stereo-camera calibration functions and interactive app
- Estimation of camera calibration errors

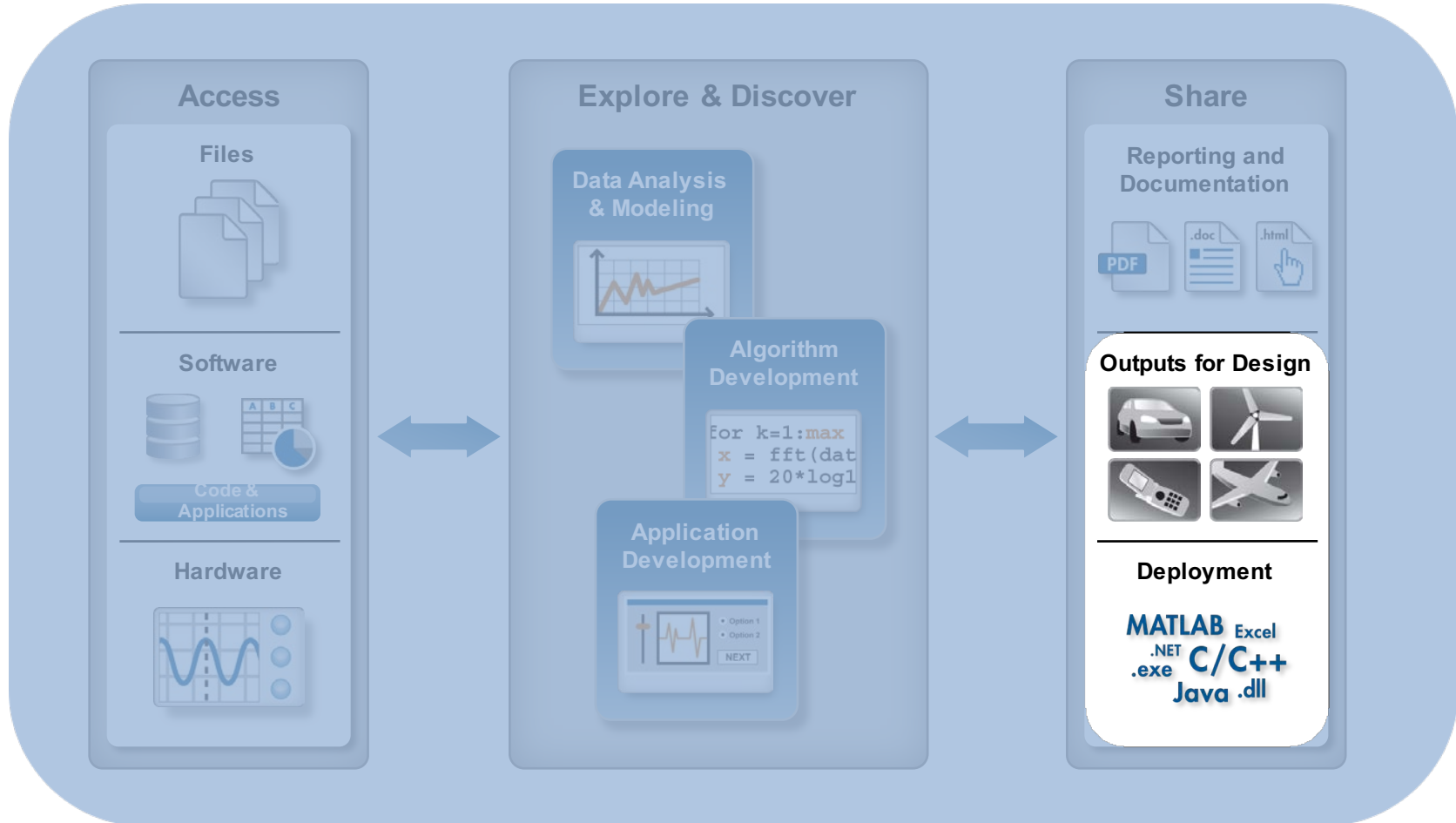
Multiple View Geometry

- Stereo vision
 - Stereo rectification
 - Disparity calculation
 - 3-D scene reconstruction
- Fundamental matrix estimation
- Camera pose estimation
- Camera location visualization
- Triangulation



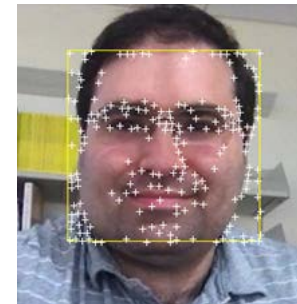
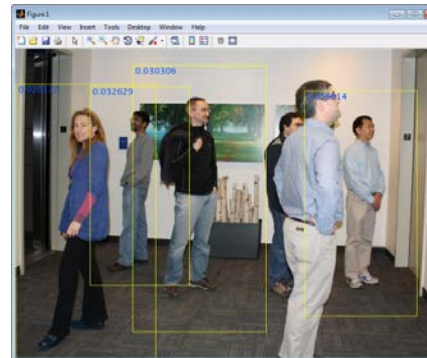
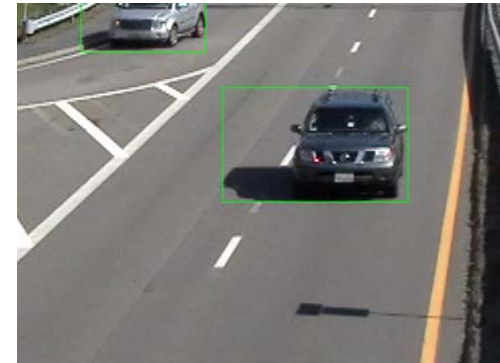
Camera Calibrator Demo

Code Generation



Generate C Code from your Algorithms

- Requires MATLAB Coder
- 80 Image Processing Toolbox functions
- Most Computer Vision System Toolbox functions



A Lot Has Happened in Five Years!

- Access
 - Files
 - Software
 - Hardware
- Graphics
- Math
- Software Development
- Image Processing
- Computer Vision

A Lot Has Happened in Five Years!

